



# Simple Serial Interface

## Developer's Guide





***Simple Serial Interface (SSI)  
Developer's Guide***

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## Revision History

Changes to the original manual are listed below:

Change	Date	Description
-01 Rev. A	1/2001	Initial Release.
-01 Rev. B	4/2001	Engineering updates.
-01 Rev. C	6/2008	Motorola re-branding.



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## Index





# About This Guide

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## Introduction

The *Simple Serial Interface (SSI) Developer's Guide* provides system requirements and programming information about Symbol Technologies' Simple Serial Interface, which enables Symbol's decoders (e.g., SE 2223 scan engine, hand-held scanners, 2D scanners, etc.) to communicate with a serial host. It provides examples of how to implement the host side of the SSI protocol.

---

## Chapter Descriptions

Topics covered in this guide are as follows:

- [Chapter 1, Using the SSI SDK](#) describes how to build the SDK for both DOS and Windows, and how to use the demo application to set SSI commands.
- [Chapter 2, Introduction to SSI](#) provides an overview of SSI, including signal lines, protocol, and packeting information. Protocol layers are described in a "bottom-up" manner, from the hardware layer up through software handshaking.
- [Chapter 3, Decoder API](#) describes the Decoder API commands which enable communication between the host and the decoder.
- [Chapter 4, Communications API](#) detail the Communications API commands, which enable communication between the serial port and the SSI Kernel code.
- [Chapter 5, Kernel API](#) describes the Kernel API commands, which maintain the SSI between the host and SSI-compliant decoder.
- [Chapter 6, OS API](#) describes the Operating System functions, used for the target operating system and the platform-independent SSI Kernel code.
- [Chapter 7, Port API](#) describes the Port API functions, the hardware-specific software implemented for the target operating system and the platform-independent SSI Kernel code.
- [Appendix A, SSI Commands](#) describes each command supported by SSI.

---

## Notational Conventions

The following conventions are used in this document:

- “User” refers to anyone using an SSI product.
- “You” refers to the End User, System Administrator or Programmer using this manual as a reference for SSI.
- *Italics* are used to highlight the following:
  - Chapters and sections in this and related documents
  - Dialog box, window and screen names
  - Drop-down list and list box names
  - Check box and radio button names
  - Icons on a screen.
- **Bold** text is used to highlight the following:
  - Key names on a keypad
  - Button names on a screen or window.
- bullets (•) indicate:
  - Action items
  - Lists of alternatives
  - Lists of required steps that are not necessarily sequential
- Sequential lists (e.g., those that describe step-by-step procedures) appear as numbered lists.



**NOTE** This symbol indicates something of special interest or importance to the reader. Failure to read the note will not result in physical harm to the reader, equipment or data.



**CAUTION** This symbol indicates that if this information is ignored, the possibility of data or material damage may occur.



**WARNING!** This symbol indicates that if this information is ignored the possibility that serious personal injury may occur.

---

## Related Documents

Refer to the *Product Reference Guide* for your product for product-specific information on SSI.

For the latest version of this guide and all guides, go to: [www.motorola.com/enterprise/manuals](http://www.motorola.com/enterprise/manuals).

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## Service Information

If you have a problem with your equipment, contact Motorola Enterprise Mobility support for your region. Contact information is available at: <http://www.motorola.com/enterprise/contactsupport>. When contacting Enterprise Mobility support, please have the following information available:

- Serial number of the unit
- Model number or product name
- Software type and version number

Motorola responds to calls by e-mail, telephone or fax within the time limits set forth in service agreements. If your problem cannot be solved by Motorola Enterprise Mobility Support, you may need to return your equipment for servicing and will be given specific directions. Motorola is not responsible for any damages incurred during shipment if the approved shipping container is not used. Shipping the units improperly can possibly void the warranty.

If you purchased your Enterprise Mobility business product from a Motorola business partner, please contact that business partner for support.



# Chapter 1 Using the SSI SDK

## Introduction

This chapter describes how to build and use Symbol's SSI SDK DOS Demo Application and the SSI SDK 32-bit Windows version.

## Building the SSI SDK DOS Demo Application (MSDOS 6.22 version)

1. Using the build tool MSVC++ version 1.52, open the project `ssidos16.mak` from the `lib` directory on your SSI SDK CD.

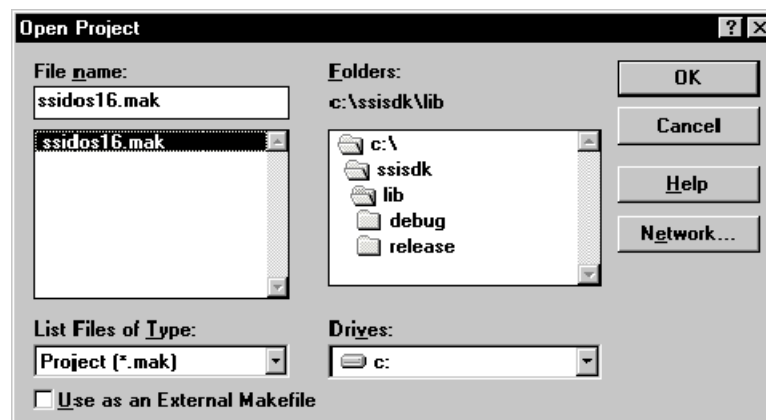


Figure 1-1 Opening `ssidos16.mak` Project

2. Select Project -> Rebuild All SSIDOS16.LIB to create the **ssidos16.lib** file. The following screen displays.

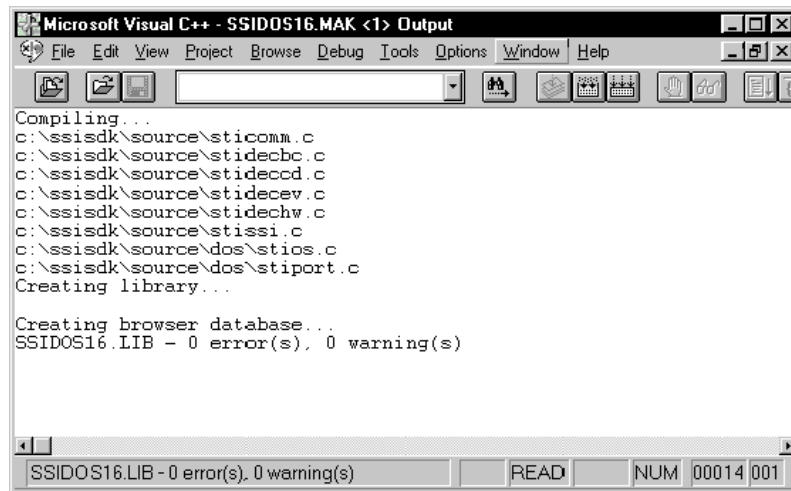


Figure 1-2 Building *ssidos16.lib* Project

3. Open the project **Dosdemo.mak** from the **\dos16test** directory.

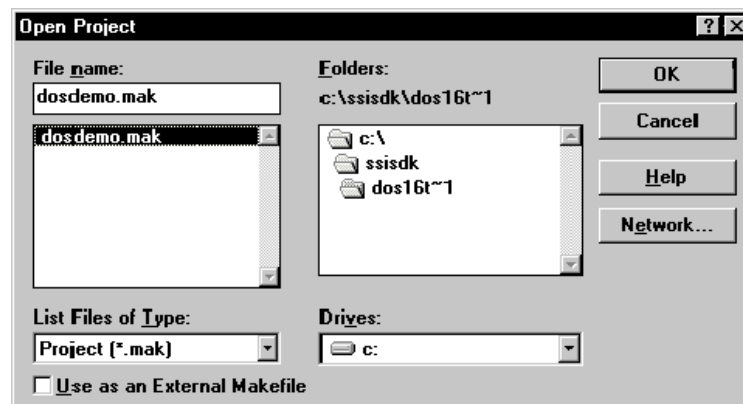
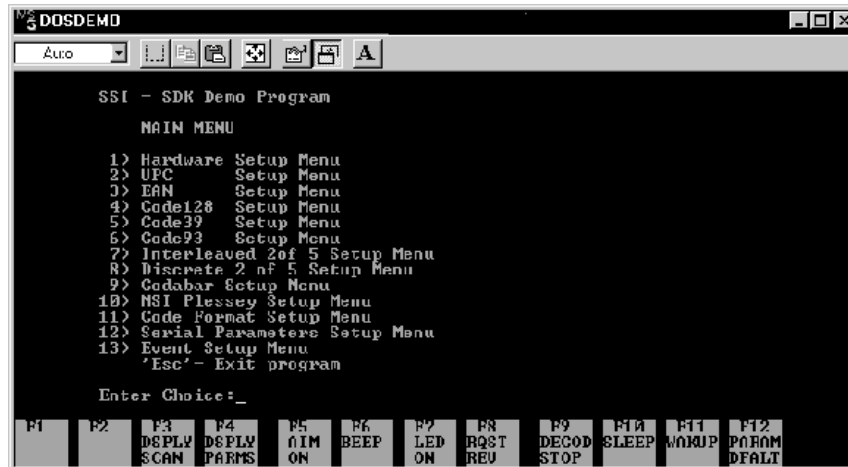


Figure 1-3 Opening *Dosdemo.mak*

4. Selecting Project -> Rebuild All to create **DOSDEMO.EXE**.
5. Connect your device to COM1.
6. Execute DOSDEMO.EXE.

## Using the SSI SDK DOS Demo Application

Executing DOSDEMO.EXE opens the SSI SDK DOS Demo application window:



**Figure 1-4** SSI SDI DOS Demo Application

The Function keys in the DOS Demo Program activate the following functions:

- F3 DSPLY SCAN: Displays scanned data.
- F4 DSPLY PARMS: Displays parameter data.
- F5 AIM ON: Activates the aim pattern.
- F6 BEEP: Sounds the beeper.
- F7 LED ON: Activates the Decode LED output.
- F8 RQST REV: Replies with the decoder's software configuration revision.
- F9 DECOD STOP: Tells decoder to abort a decode event.
- F10 SLEEP: Requests to place the decoder into low power.
- F11 WAKUP: Wakes the decoder after it's been powered down.
- F12 PARAM DFALT: Sets parameter default values.

The DOS Demo Program main menu displays the following Setup Menus: Hardware, UPC, EAN, Code128, Code39, Code93, Interleaved 2 of 5, Discrete 2 of 5, Codabar, MSI Plessey, Code Format, Serial Parameters, and Event Setup.

Select the number preceding each option to set up that option. Following are the screens that display. On each setup screen, enter the number preceding the option you'd like to change, then select the desired value.

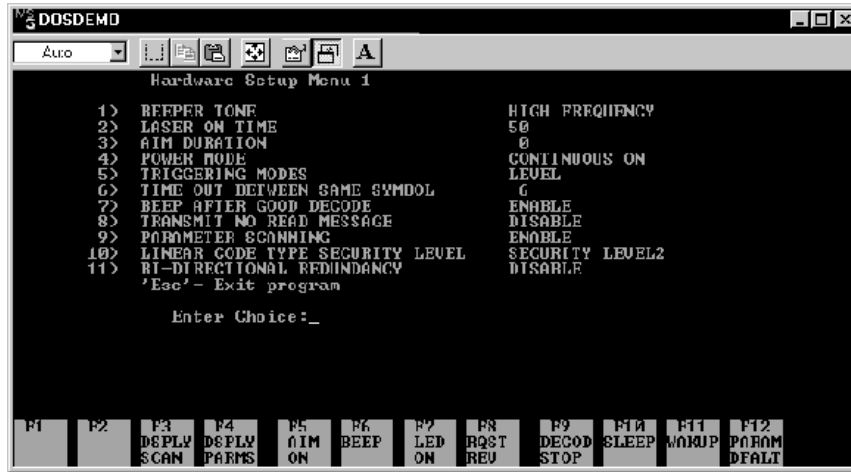


Figure 1-5 Hardware Setup Menu



Figure 1-6 UPC Setup Menu





Figure 1-7 EAN Setup Menu

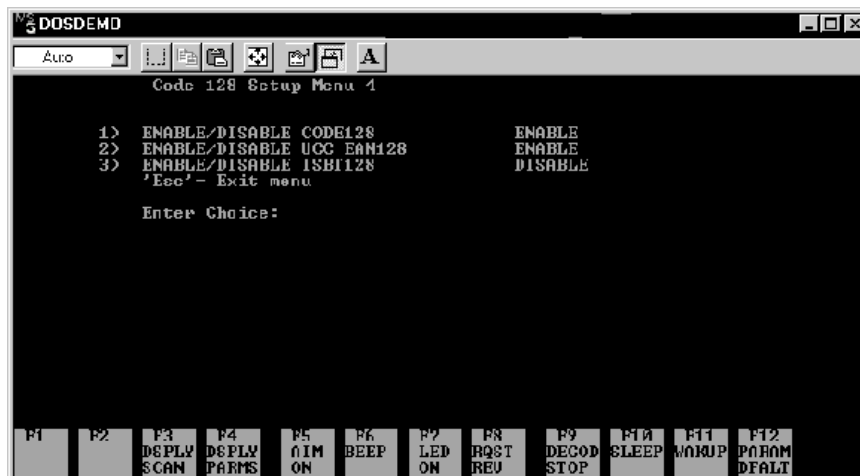


Figure 1-8 Code 128 Setup Menu

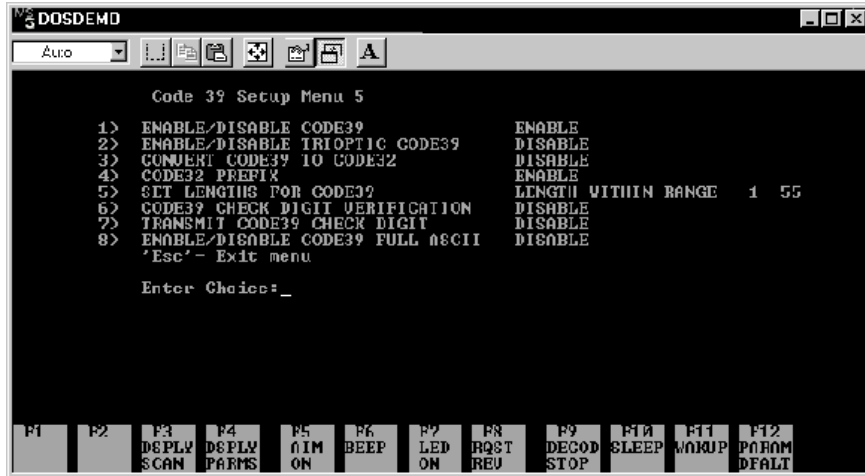


Figure 1-9 Code 39 Setup Menu

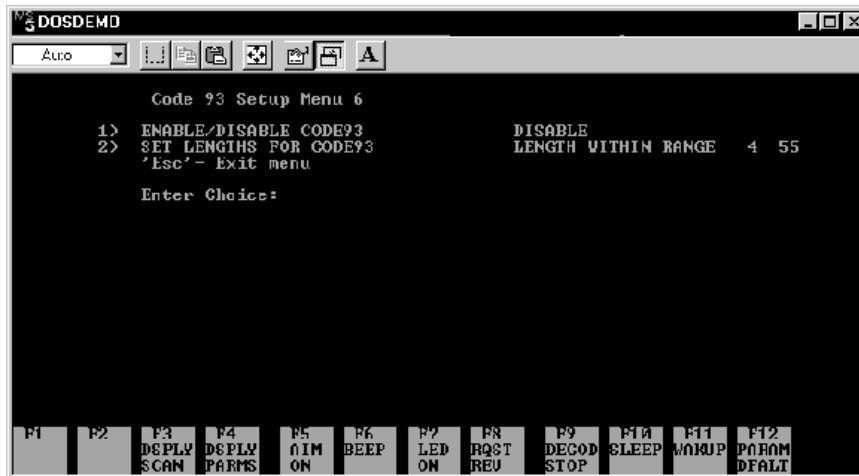


Figure 1-10 Code 93 Setup Menu



Figure 1-11 Interleaved 2 of 5 Setup Menu



Figure 1-12 Discrete 2 of 5 Setup Menu

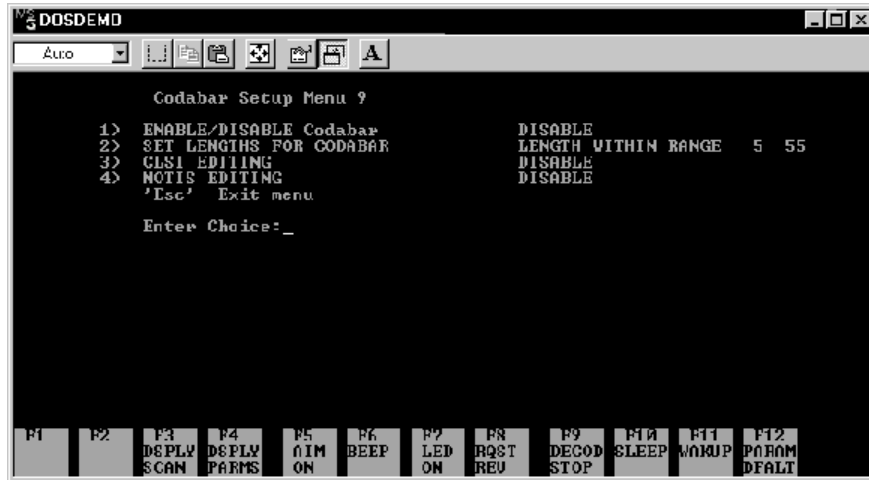


Figure 1-13 Codabar Setup Menu



Figure 1-14 MSI Plessey Setup Menu



Figure 1-15 Code Format Setup Menu



Figure 1-16 Serial Parameter Setup Menu

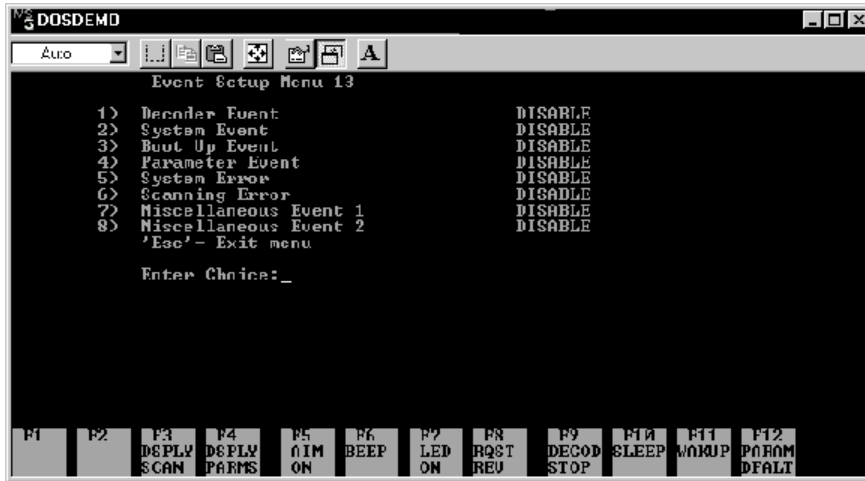
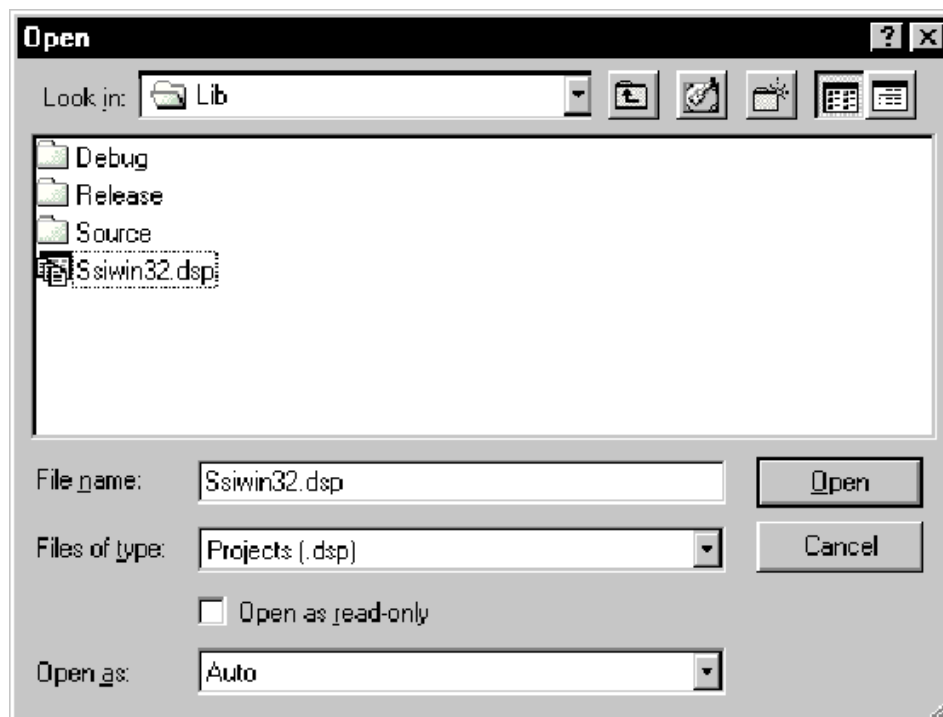


Figure 1-17 Event Setup Menu

## Building the SSI SDK (32-bit Windows Version)

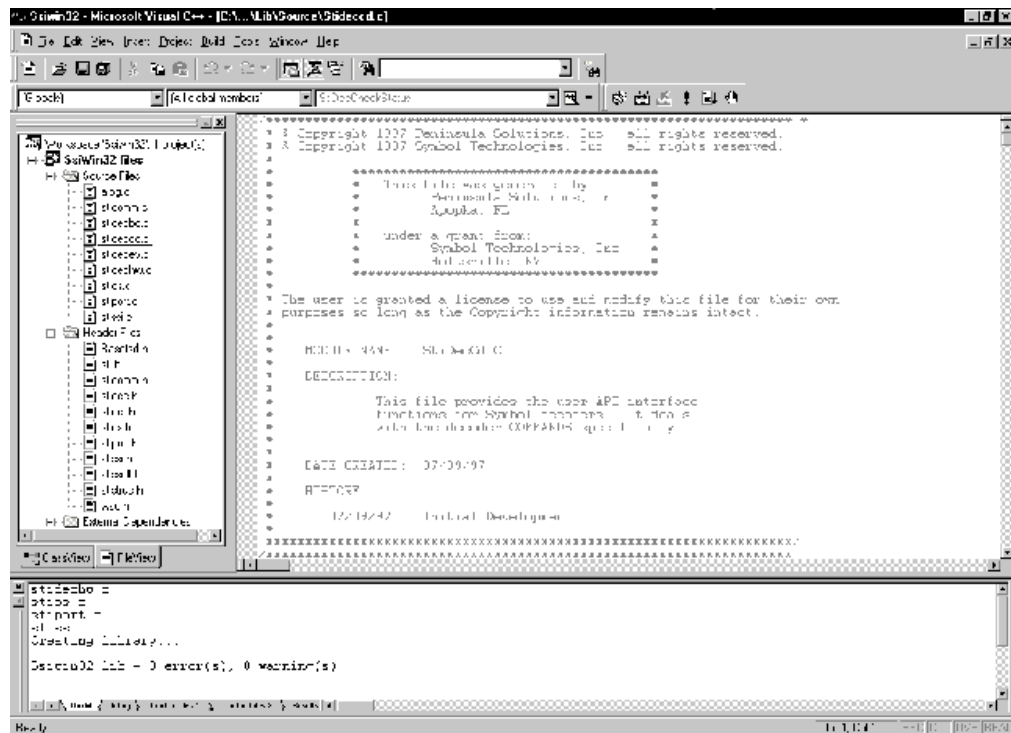
Using the build tool Microsoft Visual Studio 6.0, open the project **ssiwin32.dsp** from the **lib** directory on your SSI SDK CD.

1. In the **File** menu, select **Open**.
2. Navigate to your CD drive.
3. Select the **lib** directory.
4. In Files of type, select **Projects(.dsp)** from the pull down menu.



**Figure 1-18** Opening Ssiwin32 Project

- To build the project, select **Build**, then **Rebuild All**. This creates the **Ssiwin32.lib**. After building the project, the Build tab of the output window displays:



**Figure 1-19** Ssiwin32.lib Build Tab

The **win32test** project can now be built.

## Building the Win32test Project

Open the project **Win32Test.dsp** from the **\ssiwin32** directory on your SDK CD.

- In the **File** menu, select **Open**.
- Navigate to your CD drive.
- Select the **Win32Test** directory.
- In Files of type, select **Projects(.dsp)** from the pull down menu.



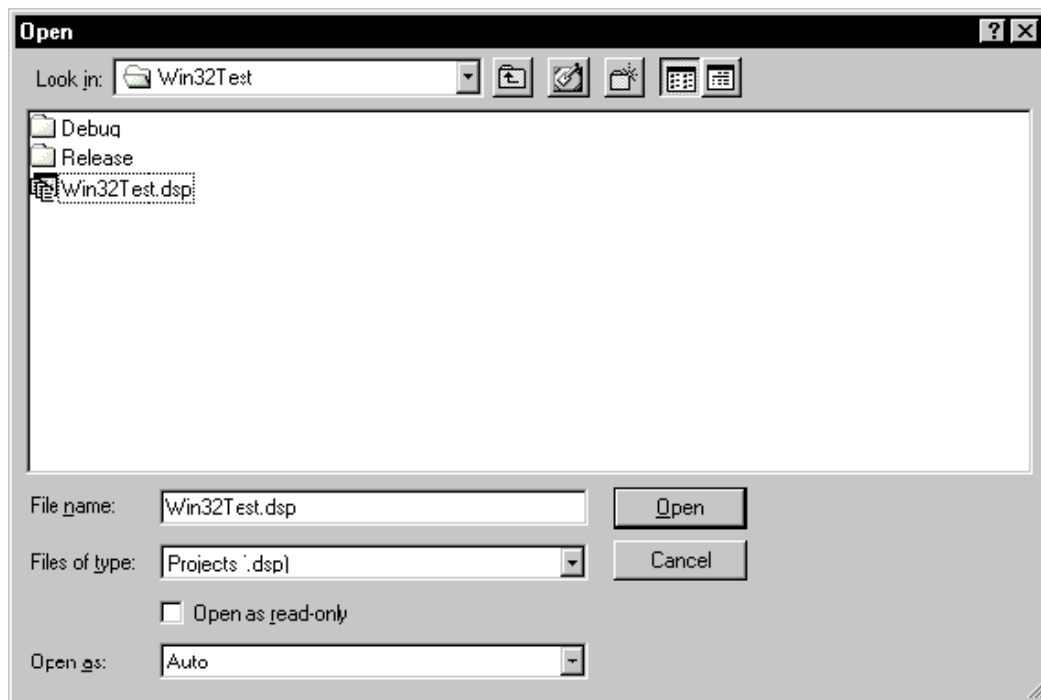
5. Select **Open**.

Figure 1-20 Opening Win32Test Project

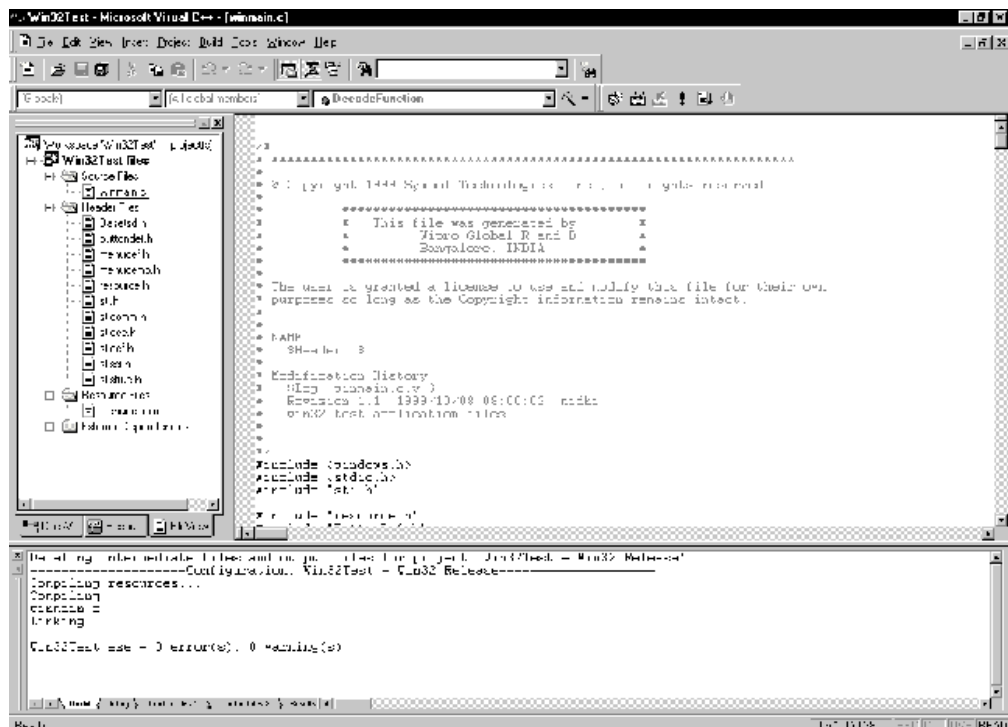
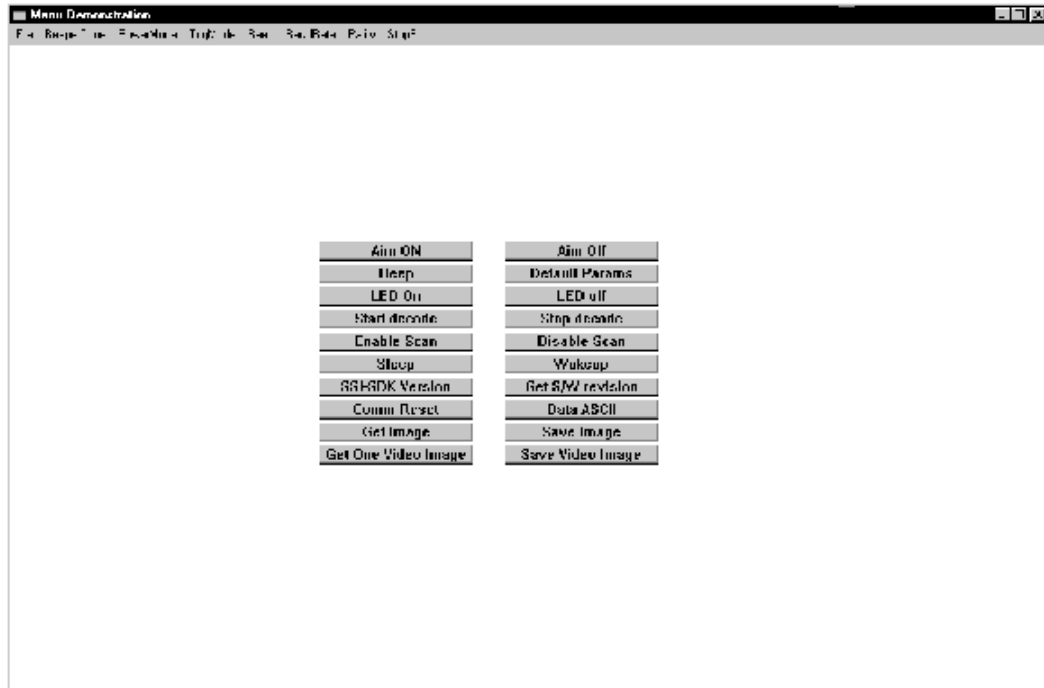
6. To build the project, select **Build**, then **Rebuild All**. This creates the **Win32Test.exe**. After building the project, the output window displays:

Figure 1-21 Win32Test.exe Build Tab

## Using the SSI SDK Demo Application (32-bit Windows Version)

Connect the device to Com2. From the **Win32Test** directory, select **Win32Test.exe**.



**Figure 1-22** Demo Application Window

The demo application supports the following SSI Commands:

- Aim On: Activates the aim pattern.
- Beep: Sounds the beeper.
- LED On: Activates the Decode LED output.
- Start decode: Tells the decoder to attempt to decode a bar code.
- Enable scan: Permits barcode scanning.
- Sleep: Requests to place the decoder into low power.
- SSI-SDK Version: Replies with the SDK version.
- Comm Reset: Resets communication settings.
- Get Image: Captures an image.
- Get one Video Image: Captures one video image.
- Aim Off: Deactivates aim pattern.
- Default Params: Sets parameter default values.
- LED Off: Turns off the Decode LED.
- Stop Decode: Tells decoder to abort a decode event.
- Disable Scan: Prevents the user from scanning bar codes.

- Wakeup: Wakes the decoder after it's been powered down.
- Get S/W revision: Replies with the decoder's software configuration.
- Data ASCII: Displays ASCII bar code value.
- Save Image: Saves a captured image.
- Save Video Image: Saves a video image.

The demo application also provides the following menu options:

- Beeper Tone: Sets beeper tone.
- Power Mode: Sets the power mode to low power or continuous on.
- Trig Mode: Sets the trigger mode to host, level, continuous, blink, or pulse.
- Beep: Enable/Disables the beeper.
- Baudrate: Sets the baud rate.
- Parity: Sets the parity.
- StopBit: Sets the number of stop bits.



# Chapter 2 Introduction to SSI

---

## Introduction

This chapter describes the system requirements of the Simple Serial Interface (SSI), which provides a communications link between Symbol Technologies decoders and a serial host. Information is provided from the perspective of both the host and the decoder.

The following must be understood before using SSI:

- The SSI interface provides a means for the host to control the decoder.
- SSI is a half-duplex communication protocol.
- SSI is transaction-based, that is, the host commands and the decoder responds. For example, the host commands “beep the beeper” and the decoder both beeps and “ACKs” as a response. Acknowledgements are vital for maintaining synchronization.

The following sections describe the basic hardware layer (signals and handshaking) first, followed by software protocol, and finishing with a description of message packets.

---

## Serial Parameter Settings

For communication to occur serial parameters must match between the host and the decoder. These parameters can be set using information in the Product Reference Guide supplied with your decoder.

The default parameters are:

- Baud Rate:9600 Baud
- Data Bits:8 bits
- Number of parity bits:1 bit
- Parity: None
- Stop Bits:1
- Hardware Handshaking:Always
- Software Handshaking:On
- Inter-Packet Delay:0 milliseconds
- Multi-Packet Option:Option 1

Settings for other parameters related to image capture, video capture and other decoder performances should also be reviewed before using SSI.

---

## Hardware Signals

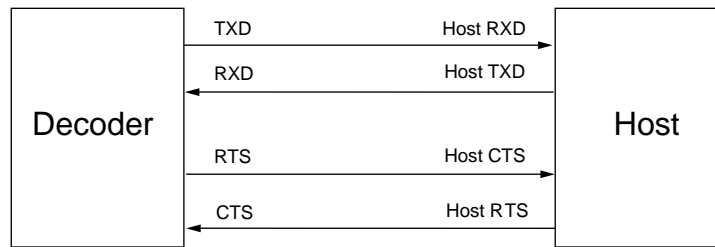
The hardware layer of SSI consists of four signals: Transmit Data (TXD), Receive Data (RXD), Request to Send (RTS) and Clear to Send (CTS).

From the decoder's perspective:

- TXD:Serial data transmit output. Drives the serial data receive input of the host.
- RXD:Serial data receive input. Driven by the serial data transmit output of the host.
- RTS:Drives host CTS, Decoder Output. Acknowledges host demand to transmit.
- CTS:Driven by HOST RTS. Decoder Input. Host Demand / Interrupt to receive.

From the host's perspective:

- HOST RXD:Serial data receive input. Driven by the serial data transmit output of the decoder.
- HOST TXD:Serial data transmit output. Drives the serial data receive input of the decoder.
- HOST CTS:Driven by decoder RTS. Host Input. Decoder ACK of host demand to transmit.
- HOST RTS:Host demand / interrupt to transmit. Must be honored by decoder.



**Figure 2-1** *Host/Decoder Interconnection*

## Hardware Handshaking

The four hardware signals are used to perform host transmission to decoder, and decoder transmission to host. The host is the Bus Master and controls the actions of SSI. In cases of collision or arbitration, the decoder always defers to the actions of the host. The host programmer should adhere to these specifications closely.

### Host Transmission to Decoder

When the host wants to transmit data to the decoder:

1. The host changes the state of the HOST RTS line from inactive to active.
2. The decoder replies by changing the state of the HOST CTS line from inactive to active, within the time frame set by the response timeout parameter.
3. Upon detecting the active HOST CTS, the host transmits the message on the HOST TXD line, verifying that HOST CTS remains active on a character-by-character basis.
4. After sending all characters in the message, the host must change the state of the HOST RTS line from active to inactive.
5. The decoder responds by changing the state of the HOST CTS line from active to inactive.

If the decoder does not respond with HOST CTS when it detects HOST RTS within the programmable (via parameters) response timeout, the host may retry the message. Only after multiple failure attempts spread over some period of time should the host declare the interface 'non-viable'. The decoder may be performing a time-intensive function which precludes talking to the host, resulting in the failure of the HOST CTS to go active.

Only one message per HOST RTS/CTS handshake is recognized, so if the host sends two (or more) messages without changing the state of the HOST RTS line, the decoder ignores the second (and subsequent) messages. Once the number of characters indicated by the host is received (plus the two bytes required for a checksum), further characters are ignored. The host may briefly toggle the state of the RTS line during this transaction, as long as the inter-character timeout is not exceeded.

While the host is not required to continuously stream characters, the maximum character-to-character delay cannot exceed the host Intercharacter Timeout parameter. If this timeout is exceeded, the decoder waits for the host to de-assert HOST RTS. Once the HOST RTS is in-active, the decoder issues a NAK message, which causes the host to re-try the entire message.

### Host Transmission Sample Code

```

boolean host_transmit()
  request permission to send [HOST RTS active]
  WHILE (the last character has not been sent) DO
    set up serial response time out
    WHILE (permission has not been granted [HOST CTS is inactive]) DO
      IF (serial response time out expired) THEN
        remove request to send /* transmit failed */
        /* calling function may retry transmit */
        RETURN (FALSE)
      END
    END
    transmit a character
  END
  remove request to send [HOST RTS inactive]
  RETURN (TRUE) /* transmit successful */

```

### Decoder Reception of Host Transmission

The decoder constantly monitors the CTS line for activity:

1. When CTS is made active by the host, the decoder responds by making the RTS line active, even if the decoder was attempting to transmit, deferring to host action.
2. The decoder monitors the RXD line and receives the characters comprising the message.
3. When all characters are received (length of message plus the two byte checksum) the decoder acts upon the message/command and ignores further characters.
4. When the decoder detects that CTS is inactive, it makes RTS inactive and transmits the response.

If the host exceeds the inter-character timeout delay, the decoder waits for de-assertion of the CTS line to send a NAK message to the host.

There are two cases where the host may make the CTS line inactive before the message is complete. If the host did not send any characters, there is no message, so the decoder does not reply. If, however, the first character is sent, an incomplete message results in a NAK.



## Decoder Reception Sample Code

This pseudo code assumes that the receiving is enabled.

```

void decoder_receive()
  IF (host is requesting to send [CTS active]) THEN
    give host permission to send [RTS active]
    WHILE (no characters received) DO
      IF (host not requesting to send [CTS Inactive]) THEN
        remove host's permission to send
        RETURN /* NULL xmit - do not NAK */
      END
    END
    set up host character time out
    WHILE (not timed out AND not the last character) DO
      IF (a character was received) THEN
        reset host character time out
      END
    END
    WHILE (host is requesting to send [CTS active]) DO
      wait /* for host to end handshake */
    END
    remove host's permission to send [RTS inactive]
    process received message and prepare response
  END
RETURN

```

## Decoder Transmission to Host

The decoder is sometimes required to send data to the host. This transaction is more complicated than the host transmission.

The decoder first ensures that the host is not attempting to send by examining the state of CTS. If the host is attempting to send, the decoder defers transmission and permits the host to send as described previously. The response to the host transmission is given by the decoder before the transmission pending. For example, if the decoder is sending decode data (as a result of scanning a bar code) and the host interrupts with a beep the beeper message, the beeper message is acted upon and acknowledged prior to transmitting the decode data message.

The host may temporarily hold off the decoder transmission by making the HOST RTS line active until it is ready to receive. If the host does not send any characters, the decoder resumes transmission when the HOST RTS line becomes inactive. If, however, the host sends one or more characters, the decoder resends the entire packet from the start when the HOST RTS line becomes inactive.

If the host is not trying to send, the decoder sends one character of the transmission on the TXD line. The decoder again checks the state of the CTS line, so the host may interrupt on a character-by-character basis. While the host should try to avoid interrupting the decoder transmission, bus collisions are possible and must defer to the host.

## Decoder Transmission Sample Code

```

boolean decoder_xmit()
/* insure that the host is not trying to send something */
IF (host is requesting to send [CTS active]) THEN
  /* host attempt to send..grant permission */
  enable receiving
  give host permission to send [RTS active]
  set up serial response time out
  WHILE (host is still requesting to send [CTS active]) DO
    IF (character was received OR timed out) THEN
      /* abort transmission..try again later */
      RETURN (FALSE)
    END
  END
  disable receiving
  remove host's permission to send [RTS inactive]
END
WHILE (there are characters to send) DO
  IF (host is not requesting to send [CTS inactive]) THEN
    send next character
  ELSE
    /* the host is either holding us off or beginning */
    /* a transmission to the decoder */
    enable receiving
    give host permission to send [RTS active]
    WHILE (host is still requesting to send [CTS active]) DO
      IF (character was received) THEN
        /* beginning of a host transmission */
        /* abort transmission..try again later */
        RETURN (FALSE)
      END
    END
    /* by virtue of code flow to here the host */
    /* was merely holding off the decoder */
    disable receiving
    remove host's permission to send [RTS inactive]
  END /* resume transmit */
END
RETURN (TRUE)

```

## Host Reception of Decoder Transmission

The host must be ready to receive data from the decoder anytime the host is not transmitting. The host can temporarily hold off the decoder transmission by keeping the HOST RTS line asserted. The host can also interrupt an incoming message by asserting HOST RTS.

Since the decoder does not change the state of the HOST CTS line when transmitting, the host is aware of a decoder transmission only when it receives the first character. For each subsequent character, the host sets up an intercharacter timeout. If this timeout has not expired and the host has not received the last character of the transmission, the host receives the next character.

## Host Reception Sample Code

```

void host_receive()
  IF (a character has been received) THEN
    set up intercharacter time out
    WHILE (not timed out AND not the last character) DO
      IF (host can receive right now) THEN
        deassert HOST RTS /* in case host was holding off decoder */
        IF (a character was received) THEN
          reset intercharacter time out
        END
      ELSE
        IF (host wants to send to decoder) THEN
          RETURN /* so host can transmit */
        ELSE
          /* host does not want to send but needs some time */
          assert request to send [HOST RTS active] /*hold off
          decoder */
          set up new intercharacter time-out
        END
      END
    END
    process received message and prepare response
  RETURN
END
RETURN

```

---

## Software Handshaking

Software handshaking provides an ACK/NAK response for commands that do not have a natural response. For example, the command “tell me your parameters” is followed by the response “my parameters are X”. A “start a decode session” command, however, has no natural response, so software handshaking provides an ACK/NAK response.

ACK/NAK handshaking may be enabled (default) or disabled. If enabled, all packeted messages must have a response in the form of an ACK, or a NAK of various types. We recommend this handshaking remain enabled to provide feedback to the host.

Raw decode data and the WAKEUP command do not use ACK/NAK handshaking since they are not packeted data.

## Transfer of Decode Data

The Decode Data Packet Format parameter controls how decode data is sent to the host. When this parameter is enabled, the data is sent in a DECODE\_DATA packet. When disabled, data is transmitted as raw ASCII data.



**NOTE** When decode data is transmitted as raw ASCII data, ACK/NAK handshaking does not apply even if it is enabled.

## ACK/NAK Enabled and Packeted Data

The decoder sends a DECODE\_DATA message after a successful decode. The decoder waits for a programmable time-out for a CMD\_ACK response. If it does not receive the response, the decoder tries to send two more times before issuing a host transmission error. If the decoder receives a CMD\_NAK from the host, it may attempt a retry depending on the cause field of the CMD\_NAK message.

## ACK/NAK Enabled and Unpacketed ASCII Data

The decoder sends a RAW DATA message after a successful decode. No ACK/NAK handshaking occurs even though it is enabled because data is unpacketed.

## ACK/NAK Disabled and Decode Data of Any Type

The decoder sends the decode data. No response is expected from the host since ACK/NAK handshaking is disabled. The security of this transaction is not guaranteed.

## Unsolicited ACK/NAK

An unsolicited ACK or NAK is an unexpected message, and is ignored since the decoder can not interpret the message.

CMD\_NAK Cancel is a special case of transmission by the host, so is considered a solicited message. This message halts (and discards) an unwanted transmission by the decoder. For example, a large image sent by the decoder to the host is typically multi-packeted, and consists of a large transmission. The host may cancel this by transmitting a CMD\_NAK Cancel.

## Expected Responses

The following tables list allowable decoder and host responses.

**Table 2-1. Decoder Responses to Host Transmission**

Host Transmission	Allowable Decoder Responses
AIM_OFF	CMD_ACK / CMD_NAK
AIM_ON	CMD_ACK / CMD_NAK
BATCH_REQUEST	BATCH_DATA / CMD_NAK
BEEP	CMD_ACK / CMD_NAK
CAPABILITIES_REQUEST	CAPABILITIES_REPLY
CMD_ACK	None
CMD_NAK	None
FLUSH_QUEUE	CMD_ACK / CMD_NAK
IMAGER_MODE	CMD_ACK / CMD_NAK
LED_OFF	CMD_ACK / CMD_NAK
LED_ON	CMD_ACK / CMD_NAK
PARAM_DEFAULTS	CMD_ACK / CMD_NAK
PARAM_REQUEST	PARAM_SEND
PARAM_SEND	CMD_ACK / CMD_NAK

**Table 2-1. Decoder Responses to Host Transmission (Continued)**

Host Transmission	Allowable Decoder Responses
REQUEST_REVISION	REPLY_REVISION
SCAN_DISABLE	CMD_ACK / CMD_NAK
SCAN_ENABLE	CMD_ACK / CMD_NAK
SLEEP	CMD_ACK / CMD_NAK
START_SESSION	CMD_ACK / CMD_NAK Note that once the decoder gathers the appropriate data, it sends this data unsolicited.
STOP_SESSION	CMD_ACK / CMD_NAK
WAKEUP	None

**Table 2-2. Host Responses to Decoder Transmission**

Decoder Transmission	Allowable Host Responses
CAPABILITIES_REPLY	None
CMD_ACK	None
CMD_NAK	None
DECODE_DATA	CMD_ACK / CMD_NAK *
EVENT	CMD_ACK / CMD_NAK *
IMAGE_DATA	CMD_ACK / CMD_NAK *
PARAM_SEND	None
REPLY_REVISION	None
VIDEO_DATA	CMD_ACK / CMD_NAK
*Multipacketed data; the host may ACK/NAK only the last packet of a multi-packeted message. Intermediate packets get no response. Intermediate packets always have the continuation bit set (1). The last packet has the continuation bit cleared (0). See <i>Multipacketing</i> on page -10 for multi-packeting options.	

---

### Message Packets

All communications between the host and the decoder are exchanged in the form of packets. A packet is a collection of bytes framed by the proper SSI protocol formatting bytes. The maximum length of a packet is 257 bytes, consisting of a checksum (two bytes), a header (four bytes), and up to 251 characters of data. Note that the length field in the header does NOT include the length of the checksum, but DOES include the length of the header itself.

### Multipacketing

SSI supports multiple packets for one message for cases when size is insufficient to transfer a complete message. Bit1 of the status byte in the message header is set to one for all packets except the last to indicate another packet is to follow. In the last packet, this bit is set to zero. The host must re-assemble these packets into one message. The decoder sends each packet in order.

#### Multipacketing, Option 1

The host ACK/NAKs each packet in a strict transaction-based method. If a CMD\_NAK checksum message occurs, the decoder retransmits the packet that was NAK'd.

#### Multipacketing, Option 2

The decoder sends data packets continuously, with no ACK/NAK handshaking to pace the transmission. If the host is overrun, it can use hardware handshaking to temporarily hold off the decoder.

At the end of transmission, the decoder waits for a CMD\_ACK or CMD\_NAK. The host acknowledges the transmission, or requests the entire multi-packet message be resent from the first packet.

The host may stop the transmission from the decoder at any time by asserting hardware handshaking. The host then transmits either CMD\_NAK, resend to instruct the decoder to resend the entire message, or CMD\_NAK, cancel to cancel the transmission completely. Note that because these NAKs are unexpected, interruption of transmission must occur first.

#### Multipacketing, Option 3

Option 3 is similar to Option 2, except there is a programmable inter-packet delay. The decoder waits a programmed period after sending each packet. This may be faster than Option 1 because the host receives data on a periodic basis without attempting to send the ACK/NAK, but slower than Option 2 since the inter-packet delay transpires on each packet. However, it helps prevent host receiver overrun.

## Packet Format

The general packet format for SSI messages is as follows:

Length	Opcode	Message Source	Status	Data...	Checksum
--------	--------	----------------	--------	---------	----------

**Table 2-3. Field Descriptions**

Field Name	Format	Sub-Field	Meaning
<b>Length</b>	1 Byte	Length	Length of message not including the check sum bytes. Maximum value is 0xFF.
<b>Opcode</b>	1 Byte	See <Blue><Italic>SSI Command Lists on page A-1.	Identifies the type of packet data sent.
<b>Message Source</b>	1 Byte	0 = Decoder, 04 = Host	Identifies where the message is coming from.
<b>Status</b>	Bit 0	Retransmit	0 = First time packet is sent 1 = Subsequent transmission attempts
	Bit 1	Continuation Bit	0 = Last frame of a multipacket message 1 =Intermediate packet of a multipacket message
	Bit 2	Reserved	Always set to zero
	Bit 3	Change Type (applies to parameters)	0 = Temporary change 1 = Permanent change
	Bits 4 - 7		Unused bits must be set to 0.
<b>Data...</b>	Variable number of bytes	See individual sections for details.	
<b>Checksum</b>	2 Bytes	2's complement sum of message contents excluding checksum.	Checksum of message formatted as HIGH BYTE LOW BYTE

Note: The checksum is a 2 byte checksum and must be sent as HIGH BYTE followed by LOW BYTE.





# Chapter 3 Decoder API

---

## Introduction

The host application uses the Host API Function Set to direct the decoder's operation and receive information from the decoder. All SSI interface functions are available to the host via the functions in the Decoder API.

To promote an event-driven architecture for the SDK, use callback function registration, even in the single-threaded DOS implementation, to enable interrupt-driven background processing of the communication tasks and to return control to the host application between interface events.

The following decoder capabilities, as a minimum, are defined in terms of callback registration:

- Decode Event
- System Event
- Boot Up Event
- Parameter Event
- System Error
- Scanning Error
- Miscellaneous Event 1
- Miscellaneous Event 2

---

## Return Value Definitions

The functions in this chapter may return the following standard status codes:

- Any non-negative value (0 to 32767): parameter value.
- STATUS\_OK: the function parameters were verified. If a function must wait for an ACK from the decoder, STATUS\_OK indicates the ACK was received.
- MSG\_PENDING: a message is pending in the transmit buffer. No further messages can be placed in the buffer in this condition; the program must wait until there is room for a new message in the transmit buffer.
- NOT\_SUPPORTED: the last packet received from the decoder was either a NAK\_DENIED or NAK\_BAD\_CONTEXT. When retrieving parameters from the decoder, this indicates that the specified parameter is not supported by this decoder, or that it was unable to comply with the request.
- COMMUNICATIONS\_ERROR: either a timeout condition or the maximum number of retries (or both) occurred. The previous transmit message was not acknowledged, and therefore is questionable.
- BAD\_PARAM: the user-supplied parameter(s) in the function call was not in the expected range.
- BATCH\_ERROR: the limits of a batch function have been exceeded. Unless otherwise indicated, functions that start with **StiDecSet\_** are responsible for generating a batch command to establish decoder parameters. The parameters are not sent to the decoder until the **StiDecSendParams()** function is called, when a new batch is started.
- ERROR\_UNDEFINED: an error condition not specifically associated with the decoder or its communications.

## StiDecCheckStatus

### Description

Returns the status of the current message.

### Syntax

*int far* StiDecCheckStatus( *void* )

### Return Values

STATUS\_OK  
MSG\_PENDING  
NAK\_DENIED  
NOT\_SUPPORTED  
COMM\_ERROR

## StiDecCmdAimOff

### Description

Turns off the aiming pattern.

### Syntax

*int far* StiDecCmdAimOff( *int func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdAimOn

### Description

Turns on the aiming pattern.

### Syntax

*int* far StiDecCmdAimOn( *int func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdBeep

### Description

Sounds the beeper.

### Syntax

*int far* StiDecCmdBeep( *int beep*, *int func\_wait* )

where:

*beep* is one of the following values:

ONE\_SHORT\_HIGH  
TWO\_SHORT\_HIGH  
THREE\_SHORT\_HIGH  
FOUR\_SHORT\_HIGH  
FIVE\_SHORT\_HIGH

ONE\_SHORT\_LOW  
TWO\_SHORT\_LOW  
THREE\_SHORT\_LOW  
FOUR\_SHORT\_LOW  
FIVE\_SHORT\_LOW

ONE\_LONG\_HIGH  
TWO\_LONG\_HIGH  
THREE\_LONG\_HIGH  
FOUR\_LONG\_HIGH  
FIVE\_LONG\_HIGH

ONE\_LONG\_LOW  
TWO\_LONG\_LOW  
THREE\_LONG\_LOW  
FOUR\_LONG\_LOW  
FIVE\_LONG\_LOW

FAST\_WARBLE  
SLOW\_WARBLE  
MIX1  
MIX2  
MIX3  
MIX4

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### **Return Values**

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdDecodeData

### Description

Fills in a structure with type, decoded data, length, and checksum information. Decode data in SSI packet format.

### Syntax

```
int far StiDecCmdDecodeData( DECODE_DATA_STRUCT *ptr, int func_wait )
```

where:

*ptr* is a pointer to the user allocated DECODE\_DATA\_STRUCT where the decoded data is to be placed.

*ptr->length* indicates the number of characters in the decoded data string

*ptr->data* contains the decoded data

*ptr->data[ptr->length]* is the start of the packet checksum

*ptr->type* indicates what type of barcode was decoded:

```

DECODE_DATA
BCTYPE_NOT_APPLICABLE
BCTYPE_CODE39
BCTYPE_CODABAR
BCTYPE_CODE128
BCTYPE_D2OF5
BCTYPE_IATA2OF5
BCTYPE_I2OF5
BCTYPE_CODE93
BCTYPE_UPCA
BCTYPE_UPCA_2SUPPLEMENTALS
BCTYPE_UPCA_5SUPPLEMENTALS
BCTYPE_UPCE0
BCTYPE_UPCE0_2SUPPLEMENTALS
BCTYPE_UPCE0_5SUPPLEMENTALS
BCTYPE_EAN8
BCTYPE_EAN8_2SUPPLEMENTALS
BCTYPE_EAN13_5SUPPLEMENTALS
BCTYPE_EAN8_5SUPPLEMENTALS
BCTYPE_EAN13
BCTYPE_EAN13_2SUPPLEMENTALS
BCTYPE_MSI_PLESSEY
BCTYPE_EAN128
BCTYPE_UPCE1
BCTYPE_UPCE1_2SUPPLEMENTALS
BCTYPE_UPCE1_5SUPPLEMENTALS

```



BCTYPE\_CODE39\_FULL\_ASCII  
BCTYPE\_TRIOPTIC\_CODE39  
BCTYPE\_BOOKLAND\_EAN  
BCTYPE\_COUPON\_CODE

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### **Return Values**

if (*func\_wait* == WAIT)

STATUS\_OK  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR  
BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING  
BAD\_PARAM

## StiDecCmdGetImage

### Description

Tells the decoder to enter image capture mode.

### Syntax

```
int CDECL STIFAR StiDecCmdGetImage( int func_wait );
```

where:

*func\_wait* is one of the following values:

    WAIT: waits for the function to complete before returning to the caller.

    NO\_WAIT: does not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

    STATUS\_OK

    NOT\_SUPPORTED

    COMMUNICATIONS\_ERROR

    BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

    MSG\_PENDING

    BAD\_PARAM

## StiDecCmdGetVideo

### Description

Tells the decoder to enter Video capture mode.

### Syntax

```
int CDECL STIFAR StiDecCmdGetVideo( int func_wait );
```

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdLedOff

### Description

De-activates LED output.

### Syntax

*int far* StiDecCmdLedOff( *int func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdLedOn

### Description

Activates LED output.

### Syntax

*int* far StiDecCmdLedOn( *int func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdParamDefaults

### Description

Sets all parameters to the factory defaults.

### Syntax

*int far* StiDecCmdParamDefaults( *void* )

### Return Values

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecCmdRequestRevision

### Description

Requests the software revision string from the decoder.

### Syntax

*int far* StiDecCmdRequestRevision( *void*, *int func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdScanDisable

### Description

Prevents the decoder from scanning bar codes.

### Syntax

*int* StiDecCmdScanDisable( *int func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM



## StiDecCmdScanEnable

### Description

Permits the decoder to scan bar codes.

### Syntax

*int* far StiDecCmdScanEnable( *int func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdSleep

### Description

Request to place the decoder into low power mode.

### Syntax

*int far* StiDecCmdSleep( *int func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdStartDecode

### Description

Tells decoder to attempt to decode a bar code.

### Syntax

*int* far StiDecCmdStartDecode( *int func\_wait* )

where:

*func\_wait* is one of the following values:

    WAIT: Wait for the function to complete before returning to the caller.

    NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

    STATUS\_OK

    NOT\_SUPPORTED

    COMMUNICATIONS\_ERROR

    BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

    MSG\_PENDING

    BAD\_PARAM

## StiDecCmdStopDecode

### Description

Tells decoder to abort a decode attempt.

### Syntax

*int* far StiDecCmdStopDecode( *int* *func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecCmdWakeUp

### Description

Wakes up decoder after it's been put into low power operation. The WAKEUP character has no effect if sent when the decoder is awake. If the host is unsure of the decoder state, it should send the wakeup character anytime it wants to communicate with the decoder.

### Syntax

*int* far StiDecCmdWakeUp( *int func\_wait* )

where:

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiDecEventCount

### Description

Returns the current count for the requested event (listed below) and resets the count for that event.

✓ **NOTE** System event codes from the decoder.

### Syntax

*int far* StiDecEventCount( *int event* )

where:

*event* is one of the following values:

DECODE\_EVENT  
SYSTEM\_EVENT  
BOOT\_UP\_EVENT  
PARAMETER\_EVENT  
SYSTEM\_ERROR  
SCANNING\_ERROR  
MISCELLANEOUS\_EVENT1  
MISCELLANEOUS\_EVENT2

## StiDecGetAimDuration

### Description

Gets the duration the aiming pattern is seen before a scan attempt begins for long-range (LR) or high-visibility (HV) scanners triggered either by a trigger pull or a START\_DECODE command.

### Syntax

*int far* StiDecGetAimDuration( *void* )

### Return Values

Returns an integer value in the range [0..99] , representing a time period from 0.0 to 9.9 seconds in 0.1 second increments. If an error occurs, the function returns one of the following values:

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetBeepAfterGoodDecode

### Description

Returns whether beeping after a good decode is enabled. If disabled, the beeper still operates during parameter menu scanning and indicates error conditions.

### Syntax

*int far* StiDecGetBeepAfterGoodDecode( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR



## StiDecGetBeeperTone

### Description

Gets the decode beep frequency (tone).

### Syntax

*int far* StiDecGetBeeperTone( *void* )

### Return Values

LOW\_FREQUENCY  
MEDIUM\_FREQUENCY  
HIGH\_FREQUENCY  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetBidirectionalRedundancy

### Description

Returns whether a bar code must be successfully scanned in both directions (forward and reverse) before being decoded.

### Syntax

*int far* StiDecGetBidirectionalRedundancy( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetBooklandEan

### Description

Returns whether Bookland EAN is enabled or disabled.

### Syntax

*int far* StiDecGetBooklandEan( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetBootUpEvent

### Description

Returns whether the Boot Up Event option is enabled or disabled.

### Syntax

```
int StiDecGetBootUpEvent( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetClsiEditing

### Description

Returns whether CLSI Editing is enabled or disabled.

### Syntax

*int far* StiDecGetClsiEditing( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetCodabar

### Description

Returns whether Codabar is enabled or disabled.

### Syntax

*int far* StiDecGetCodabar( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetCode128

### Description

Returns whether Code 128 is enabled or disabled.

### Syntax

*int far* StiDecGetCode128( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetCode32Prefix

### Description

Appends the character 'A' to the start of the decode data if enabled.

### Syntax

*int far* StiDecGetCode32Prefix( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR



## StiDecGetCode39

### Description

Returns whether Code 39 is enabled or disabled.

### Syntax

*int far* StiDecGetCode39( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetCode39CheckDigit

### Description

Returns whether Code 39 check digit is enabled or disabled.

### Syntax

*int far* StiDecGetCode39CheckDigit( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetCode39FullAscii

### Description

Returns whether Code 39 Full ASCII is enabled or disabled.

### Syntax

*int far* StiDecGetCode39FullAscii( *void* )

Returns one of the following values:

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetCode93

### Description

Returns whether Code 93 is enabled or disabled.

### Syntax

*int far* StiDecGetCode93( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetConvertCode39toCode32

### Description

Returns whether Code 39 is converted to Code 32.

### Syntax

*int far* StiDecGetConvertCode39toCode32( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetConvertEan8toEan13

### Description

Returns whether an extended symbol is labeled as either an EAN-13 bar code or an EAN-8 bar code.

### Syntax

*int far* StiDecGetConvertEan8toEan13( *void* )

### Return Values

ENABLE  
DISABLE  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetConvertI2of5toEan13

### Description

Returns whether a 14-character I 2 of 5 code is converted to EAN-13 and transmitted to the host as EAN-13.

### Syntax

*int far* StiDecGetConvertI2of5toEan13( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetConvertUpcE1toUpcA

### Description

Returns whether Convert UPC-E1 (zero suppressed) to UPC-A format before transmission is enabled.

### Syntax

*int far* StiDecGetConvertUpcE1toUpcA( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR



## StiDecGetConvertUpcEtoUpcA

### Description

Returns whether Convert UPC-E (zero suppressed) to UPC-A format before transmission is enabled.

### Syntax

*int far* StiDecGetConvertUpcEtoUpcA( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetD2of5

### Description

Returns whether Discrete 2 of 5 is enabled or disabled.

### Syntax

```
int far StiDecGetD2of5( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetDecodeEvent

### Description

Returns whether the Decode Event option is enabled or disabled.

### Syntax

```
int StiDecGetDecodeEvent( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetDecodeUpcEanRedundancy

### Description

Returns the number of times a symbol without supplementals is decoded before transmission, from 2 to 20 times.

### Syntax

*int far* StiDecGetDecodeUpcEanRedundancy( *void* )

### Return Values

Returns a value in the range [0..20]. If an error occurs, the function returns one of the following values:

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetDecodeUpcEanSupplementals

### Description

Returns the Decode UPC/EAN Supplementals option setting. Supplementals are additionally appended characters (2 or 5) according to specific code format conventions (e.g., UPC A+2, UPC E+2, EAN 8+2). Three options are available.

### Syntax

*int far* StiDecGetDecodeUpcEanSupplementals( *void* )

### Return Values

DECODE\_SUPPLEMENTALS  
IGNORE\_SUPPLEMENTALS  
AUTODISCRIMINATE\_SUPPLEMENTALS  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetEan13

### Description

Returns whether EAN-13 is enabled or disabled.

### Syntax

*int far* StiDecGetEan13( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetEan8

### Description

Returns whether EAN-8 is enabled or disabled.

### Syntax

*int far* StiDecGetEan8( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetEanZeroExtend

### Description

Returns whether five leading zeros are added to decoded EAN-8 symbols to make them compatible in format to EAN-13 symbols.

### Syntax

*int far* StiDecGetEanZeroExtend( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR



## StiDecGetHostCharacterTimeOut

### Description

Returns the maximum time the decoder waits between characters transmitted by the host before discarding the received data and declaring an error.

### Syntax

*int far* StiDecGetHostCharacterTimeOut( *void* )

### Return Values

Returns a value in the range [0..99] , representing a time period from 0.00 to 0.99 seconds in 0.01 increments. If an error occurs, one of the following status codes is returned:

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetHostSerialResponseTimeOut

### Description

Returns the Host Serial Response Timeout, which specifies how long the decoder waits for an ACK, NAK or CTS before determining that a transmission error has occurred.

### Syntax

*int far* StiDecGetHostSerialResponseTimeOut( *void* )

### Return Values

Returns a value in the range [0..99] , representing a time period from 0.0 to 9.9 seconds in 0.1 increments. If an error occurs, one of the following status codes is returned:

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetI2of5

### Description

Returns whether Interleaved 2 of 5 is enabled or disabled.

### Syntax

*int far* StiDecGetI2of5( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetI2of5CheckDigitVerification

### Description

Checks the integrity of an I 2 of 5 symbol to ensure it complies with specified algorithms, either USS (Uniform Symbology Specification), or OPCC (Optical Product Code Council).

### Syntax

*int far* StiDecGetI2of5CheckDigitVerification( *void* )

### Return Values

DISABLE  
USS\_CHECK\_DIGIT  
OPCC\_CHECK\_DIGIT  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetIntercharacterDelay

### Description

Returns the intercharacter delay period, which gives the host system time to service its receiver and perform other tasks between characters.

### Syntax

*int far* StiDecGetIntercharacterDelay( *void* )

### Return Values

Returns a value in the range [0..99] , representing a time period from 0 to 99 msec in 1 msec increments. If an error occurs, one of the following status codes is returned:

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetIsbt128

### Description

Returns whether ISBT 128 is enabled or disabled.

### Syntax

```
int far StiDecGetIsbt128( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetLaserOnTime

### Description

Gets the maximum time decode processing continues during a scan attempt.

### Syntax

```
int far StiDecGetLaserOnTime( void )
```

### Return Values

Returns an integer value in the range [5..99], representing a time period from 0.5 to 9.9 seconds in 0.1 second increments. If an error occurs, the function returns one of the following values:

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetLengthsCodabar

### Description

Returns the setting for Codabar lengths. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters), including check digit(s) the code contains.

### Syntax

*int far* StiDecGetLengthsCodabar( *int far \*ptr* )

*ptr[0]* returns one of the following values:

ONE\_DISCRETE\_LENGTH  
TWO\_DISCRETE\_LENGTHS  
LENGTH\_WITHIN\_RANGE  
ANY\_LENGTH

*ptr[1]* returns length1

*ptr[2]* returns length2

### Return Values

STATUS\_OK  
BAD\_PARAM  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR



## StiDecGetLengthsCode39

### Description

Returns the setting for Code 39 lengths. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters), including check digit(s) the code contains.

### Syntax

*int far* StiDecGetLengthsCode39( *int far \*ptr* )

*ptr[0]* returns one of the following values:

- ONE\_DISCRETE\_LENGTH
- TWO\_DISCRETE\_LENGTHS
- LENGTH\_WITHIN\_RANGE
- ANY\_LENGTH

*ptr[1]* returns length1

*ptr[2]* returns length2

### Return Values

- STATUS\_OK
- BAD\_PARAM
- BATCH\_ERROR
- NOT\_SUPPORTED
- COMMUNICATIONS\_ERROR

## StiDecGetLengthsCode93

### Description

Returns the setting for Code 93 lengths. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters), including check digit(s) the code contains.

### Syntax

*int far* StiDecGetLengthsCode93( *int far \*ptr*)

*ptr[0]* returns one of the following values:

ONE\_DISCRETE\_LENGTH  
TWO\_DISCRETE\_LENGTHS  
LENGTH\_WITHIN\_RANGE  
ANY\_LENGTH

*ptr[1]* returns length1

*ptr[2]* returns length2

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetLengthsD2of5

### Description

Returns the setting for D 2 of 5 lengths. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters), including check digit(s) the code contains.

### Syntax

*int far* StiDecGetLengthsD2of5( *int far* \*ptr )

*ptr[0]* returns one of the following values:

- ONE\_DISCRETE\_LENGTH
- TWO\_DISCRETE\_LENGTHS
- LENGTH\_WITHIN\_RANGE
- ANY\_LENGTH

*ptr[1]* returns length1

*ptr[2]* returns length2

### Return Values

- STATUS\_OK
- BAD\_PARAM
- NOT\_SUPPORTED
- COMMUNICATIONS\_ERROR

## StiDecGetLengths12of5

### Description

Returns the setting for 1 2 of 5 lengths. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters), including check digit(s) the code contains.

### Syntax

*int far* StiDecGetLengths12of5( *int far \*ptr* )

*ptr[0]* returns one of the following values:

ONE\_DISCRETE\_LENGTH  
TWO\_DISCRETE\_LENGTHS  
LENGTH\_WITHIN\_RANGE  
ANY\_LENGTH

*ptr[1]* returns length1

*ptr[2]* returns length2

### Return Values

STATUS\_OK  
BAD\_PARAM  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetLengthsMsiPlessey

### Description

Returns the setting for MSI Plessey lengths. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters), including check digit(s) the code contains.

### Syntax

*int far* StiDecGetLengthsMsiPlessey( *int far \*ptr* )

*ptr[0]* returns one of the following values:

ONE\_DISCRETE\_LENGTH  
TWO\_DISCRETE\_LENGTHS  
LENGTH\_WITHIN\_RANGE  
ANY\_LENGTH

*ptr[1]* returns length1

*ptr[2]* returns length2

### Return Values

STATUS\_OK  
BAD\_PARAM  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetLinearCodeTypeSecurityLevel

### Description

Returns the level of decode security for linear code types (e.g. Code 39, Interleaved 2 of 5) set. Higher security levels are set for low levels of bar code quality. As security levels increase, the decoder's aggressiveness decreases.

### Syntax

*int far* StiDecGetLinearCodeTypeSecurityLevel( *void* )

### Return Values

SECURITY\_LEVEL1  
SECURITY\_LEVEL2  
SECURITY\_LEVEL3  
SECURITY\_LEVEL4  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetMiscellaneousEvent1

### Description

Returns whether the Miscellaneous Event 1 option is enabled or disabled.

### Syntax

```
int StiDecGetMiscellaneousEvent1( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetMiscellaneousEvent2

### Description

Returns whether the Miscellaneous Event 2 option is enabled or disabled.

### Syntax

```
int StiDecGetMiscellaneousEvent2( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR



## StiDecGetMsiPlessey

### Description

Returns whether MSI Plessey is enabled or disabled.

### Syntax

```
int far StiDecGetMsiPlessey( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetMsiPlesseyCheckDigitAlgorithm

### Description

Returns whether MOD10/MOD11 or MOD10/MOD10 algorithm is selected.

### Syntax

*int far* StiDecGetMsiPlesseyCheckDigitAlgorithm( *void* )

### Return Values

MOD10\_MOD11

MOD10\_MOD10

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetMsiPlesseyCheckDigits

### Description

Returns the number of check digits at the end of the bar code that verify the integrity of the data.

### Syntax

*int far* StiDecGetMsiPlesseyCheckDigits( *void* )

### Return Values

ONE\_CHECK\_DIGIT

TWO\_CHECK\_DIGITS

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetNotisEditing

### Description

Returns whether NOTIS Editing is enabled or disabled.

### Syntax

*int far* StiDecGetNotisEditing( *void* )

Returns one of the following values:

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetParameterEvent

### Description

Returns whether the Parameter Event option is enabled or disabled.

### Syntax

```
int StiDecGetParameterEvent( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetParameterScanning

### Description

Returns whether decoding of parameter bar codes is enabled. Note that the Set Defaults and Enable Parameter Scanning parameter bar codes can still be decoded.

### Syntax

*int far* StiDecGetParameterScanning( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetPowerMode

### Description

Gets the power mode setting, whether power remains on when the decoder is not busy. In low power mode, the decoder enters a low power consumption mode whenever possible. In continuous power mode, the decoder does not automatically enter the low power consumption mode.

### Syntax

*int far* StiDecGetPowerMode( *void* )

### Return Values

CONTINUOUS\_ON  
LOW\_POWER  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetPrefixSuffixValues

### Description

Returns whether a prefix and/or one or two suffixes is appended to scan data for use in data editing.

### Syntax

*int far* StiDecGetPrefixSuffixValues( *int far \*ptr* )

where:

*ptr[0]* returns prefix

*ptr[1]* returns suffix\_1

*ptr[2]* returns suffix\_2

### Return Values

STATUS\_OK

BAD\_PARAM

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR



## StiDecGetScanDataTransmissionFormat

### Description

Returns the setting of the Scan Data Transmission Format.

### Syntax

*int far* StiDecGetScanDataTransmissionFormat( *void* )

### Return Values

DATA\_AS\_IS  
DATA\_SUFFIX 1  
DATA\_SUFFIX 2  
DATA\_SUFFIX 1\_SUFFIX 2  
PREFIX\_DATA  
PREFIX\_DATA\_SUFFIX 1  
PREFIX\_DATA\_SUFFIX 2  
PREFIX\_DATA\_SUFFIX 1\_SUFFIX 2  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetScanningError

### Description

Returns whether the Scanning Error option is enabled or disabled.

### Syntax

```
int StiDecGetScanningError( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetSystemError

### Description

Returns whether the System Error option is enabled or disabled.

### Syntax

```
int StiDecGetSystemError( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetSystemEvent

### Description

Returns whether the System Event option is enabled or disabled.

### Syntax

```
int StiDecGetSystemEvent( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetTimeOutBetweenSameSymbol

### Description

In Continuous triggering mode, gets the minimum time that must elapse before the decoder decodes a second bar code which is identical to the first decoded. This reduces the risk of accidentally scanning the same symbol twice.

### Syntax

*int far* StiDecGetTimeOutBetweenSameSymbol( *void* )

### Return Values

Returns a value in the range [0..99] , representing a time period from 0.0 to 9.9 seconds in 0.1 increments. If an error occurs, the function returns one of the following values:

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## **StiDecGetTransmitCode39CheckDigit**

### **Description**

Returns whether Code 39 Check Digit is enabled or disabled.

### **Syntax**

*int far* StiDecGetTransmitCode39CheckDigit( *void* )

### **Return Values**

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetTransmitCodeIdCharacter

### Description

Returns whether the Code ID character is transmitted with the data.

### Syntax

*int far* StiDecGetTransmitCodeIdCharacter( *void* )

### Return Values

SYMBOL\_CODE\_ID\_CHARACTER

AIM\_CODE\_ID\_CHARACTER

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetTransmitl2of5CheckDigit

### Description

Returns whether l 2 of 5 check digit is enabled or disabled.

### Syntax

*int far* StiDecGetTransmitl2of5CheckDigit( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR



## StiDecGetTransmitMsiPlesseyCheckDigit

### Description

Returns whether MSI Plessey Check Digit is transmitted with the data.

### Syntax

*int far* StiDecGetTransmitMsiPlesseyCheckDigit( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetTransmitNoReadMessage

### Description

Returns whether the decoder transmits "NR" if a symbol does not decode. Any prefix or suffixes enabled are appended around this message.

### Syntax

*int far* StiDecGetTransmitNoReadMessage( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetTransmitUpcACheckDigit

### Description

Returns whether a symbol is transmitted with or without the UPC-A check digit.

### Syntax

*int far* StiDecGetTransmitUpcACheckDigit( *void* )

### Return Values

TRANSMIT\_CHECK\_DIGIT  
DO\_NOT\_TRANSMIT\_CHECK\_DIGIT  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetTransmitUpcE1CheckDigit

### Description

Returns whether a symbol is transmitted with or without the UPC-E1 check digit.

### Syntax

*int far* StiDecGetTransmitUpcE1CheckDigit( *void* )

### Return Values

TRANSMIT\_CHECK\_DIGIT  
DO\_NOT\_TRANSMIT\_CHECK\_DIGIT  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetTransmitUpcECheckDigit

### Description

Returns whether a symbol is transmitted with or without the UPC-E check digit.

### Syntax

*int far* StiDecGetTransmitUpcECheckDigit( *void* )

### Return Values

TRANSMIT\_CHECK\_DIGIT  
DO\_NOT\_TRANSMIT\_CHECK\_DIGIT  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetTriggeringModes

### Description

Gets the triggering mode of the decoder.

### Syntax

*int far* StiDecGetTriggeringModes( *void* )

### Return Values

LEVEL  
PULSE  
CONTINUOUS  
BLINKING  
HOST  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetTriopticCode39

### Description

Returns whether Trioptic Code 39 is enabled or disabled.

### Syntax

```
int far StiDecGetTriopticCode39( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetUccEan128

### Description

Returns whether UCC/EAN-128 is enabled or disabled.

### Syntax

*int far* StiDecGetUccEan128( *void* )

Returns one of the following values:

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR



## StiDecGetUpcA

### Description

Returns whether UPC-A is enabled or disabled.

### Syntax

```
int far StiDecGetUpcA( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetUpcAPreamble

### Description

Returns the selected UPC-A Preamble option: transmit system character only, transmit system character and country code ("0" for USA), or no preamble transmitted. The lead-in characters are considered part of the symbol.

### Syntax

*int far* StiDecGetUpcAPreamble( *void* )

### Return Values

NO\_PREAMBLE  
SYSTEM\_CHARACTER  
SYSTEM\_CHARACTER\_COUNTRY\_CODE  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetUpcE

### Description

Returns whether UPC-E is enabled or disabled.

### Syntax

*int far* StiDecGetUpcE( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetUpcE1

### Description

Returns whether UPC-E1 is enabled or disabled.

### Syntax

```
int far StiDecGetUpcE1( void )
```

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetUpcEanCouponCode

### Description

Returns whether UPC-A, UPC-A with 2 supplemental characters, UPC-A with 5 supplemental characters, and UPC-A/EAN128 bar codes are decoded.

### Syntax

*int far* StiDecGetUpcEanCouponCode( *void* )

### Return Values

ENABLE

DISABLE

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetUpcEanSecurityLevel

### Description

Returns the UPC/EAN Security Level selected.

### Syntax

*int far* StiDecGetUpcEanSecurityLevel( *void* )

### Return Values

SECURITY\_LEVEL0

SECURITY\_LEVEL1

SECURITY\_LEVEL2

SECURITY\_LEVEL3

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecGetUpcE1Preamble

### Description

Returns the selected UPC-E1 Preamble option: transmit system character only, transmit system character and country code ("0" for USA), or no preamble transmitted. The lead-in characters are considered part of the symbol.

### Syntax

*int far* StiDecGetUpcE1Preamble( *void* )

### Return Values

NO\_PREAMBLE  
SYSTEM\_CHARACTER  
SYSTEM\_CHARACTER\_COUNTRY\_CODE  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR

## StiDecGetUpcEPreamble

### Description

Returns the selected UPC-E Preamble option: transmit system character only, transmit system character and country code ("0" for USA), or no preamble transmitted. The lead-in characters are considered part of the symbol.

### Syntax

*int far* StiDecGetUpcEPreamble( *void* )

### Return Values

NO\_PREAMBLE  
SYSTEM\_CHARACTER  
SYSTEM\_CHARACTER\_COUNTRY\_CODE  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR



## StiDecRspReplyRevision

### Description

Returns the revision string obtained through the REQUEST\_REVISION command.

### Syntax

*int far* StiDecRspReplyRevision( *char \*ptr, int max\_length*)

Copies the ASCII revision string to a user specified location.

where:

*\*ptr* is a pointer to a user allocated char array. This function places the revision into the array, null terminated.

*max\_length* is a maximum number of characters to be copied to *ptr[ ]*.

### Return Values

Length of the revision string if no errors are encountered, otherwise,

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiDecSendParams

### Description

Sends batched parameters. Parameters set with the following functions (**StiDecSet.....**) are not sent to the decoder until **StiDecSendParams** is executed.

### Syntax

*int far* StiDecSendParams( *int change*, *int func\_wait* )

where:

*change* is one of the following values:

TEMPORARY  
PERMANENT

*func\_wait* is one of the following values:

WAIT        Wait for the function to complete before returning to the caller.  
NO\_WAIT    Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* = WAIT):

STATUS\_OK  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR  
BAD\_PARAM

if (*func\_wait* = NO\_WAIT):

MSG\_PENDING  
BAD\_PARAM

## StiDecSetAimDuration

### Description

When a long-range (LR) or high-visibility (HV) scanner is triggered either by a trigger pull or a START\_DECODE command, this parameter sets the duration the aiming pattern is seen before a scan attempt begins. It does not apply to the aim signal or the AIM\_ON command. It is programmable in 0.1 second increments from 0.0 to 9.9 seconds. No aim pattern is visible when the value is 0.0.

### Syntax

*int far* StiDecSetAimDuration( *int aim\_duration*)

where:

*aim\_duration* is an integer value in the range [0..99], representing a time period from 0.0 to 9.9 seconds in 0.1 second increments.

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetBeepAfterGoodDecode

### Description

Enables or disables beeping after a good decode. The beeper still operates during parameter menu scanning and indicates error conditions.

### Syntax

*int far* StiDecSetBeepAfterGoodDecode( *int beep* )

where:

*beep* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetBeeperTone

### Description

Sets the decode beep frequency (tone).

### Syntax

*int* far StiDecSetBeeperTone( *int* beeper\_tone)

where:

*beeper\_tone* is one of the following values:

LOW\_FREQUENCY  
MEDIUM\_FREQUENCY  
HIGH\_FREQUENCY

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetBidirectionalRedundancy

### Description

This parameter is only valid when a Linear Code Type Security Level is enabled. When enabled, a bar code must be successfully scanned in both directions (forward and reverse) before being decoded.

### Syntax

*int far* StiDecSetBidirectionalRedundancy( *int redundancy* )

where:

*redundancy* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetBooklandEan

### Description

Enables or disables Bookland EAN.

### Syntax

*int* far StiDecSetBooklandEan( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetBootUpEvent

### Description

Enables Boot Up Event option.

### Syntax

```
int StiDecSetBootUpEvent( int enable, void far (*eventFunction)(void))
```

where:

*enable* is one of the following values:

ENABLE

DISABLE

*eventFunction* is a pointer to a function which will be called if the Boot Up Event is enabled when the Boot Up Event occurs.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR



## StiDecSetClsiEditing

### Description

Strips the start and stop characters and inserts a space after the first, fifth, and tenth characters of a 14-character Codabar symbol.



**NOTE** Symbol length does not include start and stop characters.

### Syntax

*int far* StiDecSetClsiEditing( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetCodabar

### Description

Enables or disables Codabar.

### Syntax

*int far* StiDecSetCodabar( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetCode128

### Description

Enables or disables Code 128.

### Syntax

*int far* StiDecSetCode128( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetCode32Prefix

### Description

Appends the character 'A' to the start of the decode data if enabled.

### Syntax

*int far* StiDecSetCode32Prefix( *int enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetCode39

### Description

Enables or disables Code 39.

### Syntax

*int far* StiDecSetCode39( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetCode39CheckDigit

### Description

Checks the integrity of a Code 39 symbol to ensure it complies with specified algorithms. Only Code 39 symbols which include a modulo 43 check digit are decoded.

### Syntax

*int* far StiDecSetCode39CheckDigit( *int* *check\_digit* )

where:

*check\_digit* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetCode39FullAscii

### Description

Enables or disables Code 39 Full ASCII.

When enabled, the ASCII character set assigns a code to letters, punctuation marks, numerals, and most control keystrokes on the keyboard.

The first 32 codes are non-printable and are assigned to keyboard control characters such as BACKSPACE and RETURN. The other 96 are called printable codes because all but SPACE and DELETE produce visible characters.

Code 39 Full ASCII interprets the bar code special character (\$ + % /) preceding a Code 39 character and assigns an ASCII character value. For example, when Code 39 Full ASCII is enabled and a +B is scanned, it is interpreted as b, %J as 7, and \$H emulates the keystroke BACKSPACE. Scanning ABC\$M outputs the keystroke equivalent of ABC ENTER.

Do not enable Code 39 Full ASCII and Trioptic Code 39 simultaneously. The decoder does not autodiscriminate between Code 39 and Code 39 Full ASCII.

### Syntax

*int* far StiDecSetCode39FullAscii( *int* full\_ascii )

where:

*full\_ascii* is one of the following values:

- ENABLE
- DISABLE

### Return Values

- STATUS\_OK
- BAD\_PARAM
- BATCH\_ERROR

## StiDecSetCode93

### Description

Enables or disables Code 93.

### Syntax

*int far* StiDecSetCode93( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR



## StiDecSetConvertCode39toCode32

### Description

Converts Code 39 to Code 32.

### Syntax

*int* far StiDecSetConvertCode39toCode32( *int* *enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetConvertEan8toEan13

### Description

When EAN Zero Extend is enabled, labels the extended symbol as either an EAN-13 bar code, or an EAN-8 bar code.

When EAN Zero Extend is disabled, this parameter has no effect on bar code data.

### Syntax

*int far* StiDecSetConvertEan8toEan13( *int enable* )

where:

*enable* is one of the following values:

- ENABLE
- DISABLE

### Return Values

- STATUS\_OK
- BAD\_PARAM
- BATCH\_ERROR

## StiDecSetConvertI2of5toEan13

### Description

Converts a 14-character I 2 of 5 code to EAN-13, and transmits to the host as EAN-13. To accomplish this, the I 2 of 5 code must be enabled, one length must be set to 14, and the code must have a leading zero and a valid EAN-13 check digit.

### Syntax

*int* far StiDecSetConvertI2of5toEan13( *int enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetConvertUpcE1toUpcA

### Description

Converts UPC-E1 (zero suppressed) decoded data to UPC-A format before transmission. After conversion, data follows UPC-A format and is affected by UPC-A programming selections (e.g., Preamble, Check Digit).

Selecting DISABLE allows you to transmit UPC-E1 (zero suppressed) decoded data

### Syntax

*int far* StiDecSetConvertUpcE1toUpcA( *int enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetConvertUpcEtoUpcA

### Description

Converts UPC-E (zero suppressed) decoded data to UPC-A format before transmission. After conversion, data follows UPC-A format and is affected by UPC-A programming selections (e.g., Preamble, Check Digit).

Selecting DISABLE allows you to transmit UPC-E (zero suppressed) decoded data.

### Syntax

*int far* StiDecSetConvertUpcEtoUpcA( *int enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetD2of5

### Description

Enables or disables Discrete 2 of 5.

### Syntax

*int far* StiDecSetD2of5( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetDecodeEvent

### Description

Enables Decode Event option.

### Syntax

```
int StiDecSetDecodeEvent( int enable, void far (*eventFunction)(void) )
```

where:

*enable* is one of the following values:

ENABLE

DISABLE

*eventFunction* is a pointer to a function which will be called if the Decode Event is enabled when the Decode Event occurs.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetDecodeUpcEanRedundancy

### Description

When Autodiscriminate UPC/EAN Supplementals selected, adjusts the number of times a symbol without supplementals is decoded before transmission. The range is from 2 to 20 times. Five or above is recommended when decoding a mix of UPC/EAN symbols with and without supplementals, and the autodiscriminate option is selected.

### Syntax

*int far StiDecSetDecodeUpcEanRedundancy(int supplemental\_redundancy)*

where:

*supplemental\_redundancy* is an integer value in the range [2..20].

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR



## StiDecSetDecodeUpcEanSupplementals

### Description

Sets Decode UPC/EAN Supplementals option. Supplementals are additionally appended characters (2 or 5) according to specific code format conventions (e.g., UPC A+2, UPC E+2, EAN 8+2). Three options are available.

- If UPC/EAN with supplemental characters is selected, UPC/EAN symbols without supplemental characters are not decoded.
- If UPC/EAN without supplemental characters is selected, and the decoder is presented with a UPC/EAN plus supplemental symbol, the UPC/EAN is decoded and the supplemental characters ignored.
- An autodiscriminate option is also available.

### Syntax

*int* far StiDecSetDecodeUpcEanSupplementals( *int* *supplementals* )

where:

*supplementals* is one of the following values:

DECODE\_SUPPLEMENTALS  
IGNORE\_SUPPLEMENTALS  
AUTODISCRIMINATE\_SUPPLEMENTALS

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetEan13

### Description

Enables or disables EAN-13.

### Syntax

*int far* StiDecSetEan13( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetEan8

### Description

Enables or disables EAN-8.

### Syntax

*int far* StiDecSetEan8( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetEanZeroExtend

### Description

When enabled, five leading zeros are added to decoded EAN-8 symbols to make them compatible in format to EAN-13 symbols.

Disabling this returns EAN-8 symbols to their normal format.

### Syntax

*int far* StiDecSetEanZeroExtend( *int enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetHostCharacterTimeOut

### Description

Determines the maximum time the decoder waits between characters transmitted by the host before discarding the received data and declaring an error. The time-out is set in 0.01 second increments from 0.01 to 0.99 seconds.

### Syntax

*int far* StiDecSetHostCharacterTimeOut( *int time\_out* )

where:

*time\_out* is an integer value in the range [1..99], representing a time period from 0.01 to 0.99 seconds in 0.01 second increments.

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetHostSerialResponseTimeOut

### Description

Specifies how long the decoder waits for an ACK, NAK or CTS before determining that a transmission error has occurred. The delay period can range from 0.0 to 9.9 seconds in .1 second increments.

### Syntax

*int* *far* StiDecSetHostSerialResponseTimeOut( *int* *time\_out* )

where:

*time\_out* is an integer value in the range [0..99], representing a time period from 0.0 to 9.9 seconds in 0.1 increments.

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSet12of5

### Description

Enables or disables Interleaved 2 of 5.

### Syntax

*int far* StiDecSet12of5( *int enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetI2of5CheckDigitVerification

### Description

Checks the integrity of an I 2 of 5 symbol to ensure it complies with a specified algorithm, either USS (Uniform Symbology Specification), or OPCC (Optical Product Code Council).

### Syntax

*int* far StiDecSetI2of5CheckDigitVerification( *int* *check\_digit* )

where:

*check\_digit* is one of the following values:

DISABLE

USS\_CHECK\_DIGIT

OPCC\_CHECK\_DIGIT

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR



## StiDecSetIntercharacterDelay

### Description

Sets the intercharacter delay option to match host requirements. The intercharacter delay gives the host system time to service its receiver and perform other tasks between characters. The delay period can range from no delay to 99 msec in 1 msec increments.

### Syntax

*int* far StiDecSetIntercharacterDelay( *int intercharacter\_delay* )

where:

*intercharacter\_delay* is an integer value in the range [0..99], representing a time period from 0 to 99 msec in 1 msec increments.

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetIsbt128

### Description

Enables or disables ISBT 128.

### Syntax

*int far* StiDecSetIsbt128( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetLaserOnTime

### Description

Sets the maximum time decode processing continues during a scan attempt. It is programmable in 0.1 second increments from 0.5 to 9.9 seconds.

### Syntax

*int far* StiDecSetLaserOnTime( *int laser\_on\_time*)

where:

*laser\_on\_time* is an integer value in the range [5..99], representing a time period from 0.5 to 9.9 seconds in 0.1 second increments.

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetLengthsCodabar

### Description

Sets lengths for Codabar. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters) the code contains. It also includes any start or stop characters.

- One Discrete Length - Decodes only those codes containing a selected length.
- Two Discrete Lengths - Decodes only those codes containing two selected lengths.
- Length Within Range - Decodes a code type within a specified range.
- Any length - Decodes Codabar symbols containing any number of characters.

### Syntax

```
int far StiDecSetLengthsCodabar( int length_type, int length1, int length2 )
```

where:

*length\_type* is one of the following values:

```
ONE_DISCRETE_LENGTH  
TWO_DISCRETE_LENGTHS  
LENGTH_WITHIN_RANGE  
ANY_LENGTH
```

*length1* and *length2* describe the discrete length(s) or the specific range of values.

### Return Values

```
STATUS_OK  
BAD_PARAM  
BATCH_ERROR
```

## StiDecSetLengthsCode39

### Description

Sets lengths for Code 39. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters), including check digit(s) the code contains. If Code 39 Full ASCII is enabled, Length Within a Range or Any Length are the preferred options.

- One Discrete Length - decodes only those codes containing a selected length.
- Two Discrete Lengths - decodes only those codes containing two selected lengths.
- Length Within Range - decodes a code type within a specified range.
- Any Length - decodes Code 39 symbols containing any number of characters.

### Syntax

```
int far StiDecSetLengthsCode39( int length_type, int length1, int length2 )
```

where:

*length\_type* is one of the following values:

```
ONE_DISCRETE_LENGTH
TWO_DISCRETE_LENGTHS
LENGTH_WITHIN_RANGE
ANY_LENGTH
```

*length1* and *length2* describe the discrete length(s) or the specific range of values.

### Return Values

```
STATUS_OK
BAD_PARAM
BATCH_ERROR
```

## StiDecSetLengthsCode93

### Description

Sets lengths for Code 93. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters), including check digit(s) the code contains.

- One Discrete Length - Decodes only those codes containing a selected length.
- Two Discrete Lengths - Decodes only those codes containing two selected lengths.
- Length Within Range - Decodes a code type within a specified range.
- Any Length - Decodes Code 93 symbols containing any number of characters.

### Syntax

```
int far StiDecSetLengthsCode93( int length_type, int length1, int length2 )
```

where:

*length\_type* is one of the following values:

```
ONE_DISCRETE_LENGTH  
TWO_DISCRETE_LENGTHS  
LENGTH_WITHIN_RANGE  
ANY_LENGTH
```

*length1* and *length2* describe the discrete length(s) or the specific range of values.

### Return Values

```
STATUS_OK  
BAD_PARAM  
BATCH_ERROR
```

## StiDecSetLengthsD2of5

### Description

Sets lengths for D 2 of 5. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters) the code contains, and includes check digits.

- One Discrete Length - Decodes only those codes containing a selected length.
- Two Discrete Lengths - Decodes only those codes containing two selected lengths.
- Length Within Range - Decodes a code type within a specified range.
- Any Length - Decodes D 2 of 5 symbols containing any number of characters.

✓ **NOTE** Selecting this option may lead to misdecodes for D 2 of 5 codes.

### Syntax

*int far* StiDecSetLengthsD2of5( *int length\_type*, *int length1*, *int length2* )

where:

*length\_type* is one of the following values:

ONE\_DISCRETE\_LENGTH  
 TWO\_DISCRETE\_LENGTHS  
 LENGTH\_WITHIN\_RANGE  
 ANY\_LENGTH

*length1* and *length2* describe the discrete length(s) or the specific range of values.

### Return Values

STATUS\_OK  
 BAD\_PARAM  
 BATCH\_ERROR

## StiDecSetLengths12of5

### Description

Sets lengths for 1 2 of 5. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters) the code contains, and includes check digits.

- One Discrete Length - Decodes only those codes containing a selected length.
- Two Discrete Lengths - Decodes only those codes containing two selected lengths.
- Length Within Range - Decodes a code type within a specified range.
- Any Length - Decodes 1 2 of 5 symbols containing any number of characters.

✓ **NOTE** Selecting this option may lead to misdecodes for 1 2 of 5 codes.

### Syntax

*int far* StiDecSetLengths12of5( *int length\_type*, *int length1*, *int length2* )

where:

*length\_type* is one of the following values:

ONE\_DISCRETE\_LENGTH  
 TWO\_DISCRETE\_LENGTHS  
 LENGTH\_WITHIN\_RANGE  
 ANY\_LENGTH

*length1* and *length2* describe the discrete length(s) or the specific range of values.

### Return Values

STATUS\_OK  
 BAD\_PARAM  
 BATCH\_ERROR



## StiDecSetLengthsMsiPlessey

### Description

Sets lengths for MSI Plessey. Options are any length, one or two discrete lengths, or lengths within a specific range. The length of a code refers to the number of characters (i.e., human readable characters) the code contains, and includes check digits.

- One Discrete Length - Decodes only those codes containing a selected length.
- Two Discrete Lengths - Decodes only those codes containing two selected lengths.
- Length Within Range - Decodes a code type within a specified range.
- Any Length - Decodes MSI Plessey symbols containing any number of characters.

✓ **NOTE** Selecting this option may lead to misdecodes for codes.

### Syntax

*int far* StiDecSetLengthsMsiPlessey( *int length\_type*, *int length1*, *int length2* )

where:

*length\_type* is one of the following values:

ONE\_DISCRETE\_LENGTH  
 TWO\_DISCRETE\_LENGTHS  
 LENGTH\_WITHIN\_RANGE  
 ANY\_LENGTH

*length1* and *length2* describe the discrete length(s) or the specific range of values.

### Return Values

STATUS\_OK  
 BAD\_PARAM  
 BATCH\_ERROR

## StiDecSetLinearCodeTypeSecurityLevel

### Description

Four levels of decode security for linear code types (e.g. Code 39, Interleaved 2 of 5) are supported. Select a higher security level for low levels of bar code quality. As security levels increase, the decoder's aggressiveness decreases.

- Linear Security Level 1: The following code types must be successfully read twice before being decoded:

Code Type	Length
Codabar	All
MSI Plessey	4 or less
D2of 5	8 or less
12 of 5	8 or less

- Linear Security Level 2: All code types must be successfully read twice before being decoded.
- Linear Security Level 3: Code types other than the following must be successfully read twice before being decoded. The following codes must be read three times:

Code Type	Length
MSI Plessey	4 or less
D2of 5	8 or less
12of 5	8 or less

- Linear Security Level 4: All code types must be successfully read three times before being decoded.

### Syntax

*int far* StiDecSetLinearCodeTypeSecurityLevel(*int security\_level*)

where:

*security\_level* is one of the following values:

```
SECURITY_LEVEL1
SECURITY_LEVEL2
SECURITY_LEVEL3
SECURITY_LEVEL4
```

### Return Values

```
STATUS_OK
BAD_PARAM
BATCH_ERROR
```

## StiDecSetMiscellaneousEvent1

### Description

Enables Miscellaneous Event 1 option.

### Syntax

```
int StiDecSetMiscellaneousEvent1( int enable, void far (*eventFunction)(void))
```

where:

*enable* is one of the following values:

ENABLE

DISABLE

*eventFunction* is a pointer to a function which will be called if the Miscellaneous Event 1 is enabled when the Miscellaneous Event 1 occurs.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetMiscellaneousEvent2

### Description

Enables Miscellaneous Event 2 option.

### Syntax

```
int StiDecSetMiscellaneousEvent2( int enable, void far (*eventFunction)(void) )
```

where:

*enable* is one of the following values:

ENABLE

DISABLE

*eventFunction* is a pointer to a function which will be called if the Miscellaneous Event 2 is enabled when the Miscellaneous Event 2 occurs.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetMsiPlessey

### Description

Enables or disables MSI Plessey.

### Syntax

*int far* StiDecSetMsiPlessey( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetMsiPlesseyCheckDigitAlgorithm

### Description

When Two MSI Plessey check digits is selected, sets an additional verification is required to ensure integrity. Two following algorithms may be selected: MOD10/MOD11 or MOD10/MOD10.

### Syntax

*int far* StiDecSetMsiPlesseyCheckDigitAlgorithm( *int algorithm* )

where:

*algorithm* is one of the following values:

MOD10\_MOD11  
MOD10\_MOD10

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetMsiPlesseyCheckDigits

### Description

Sets the number of check digits at the end of the bar code that verify the integrity of the data. At least one check digit is always required. Check digits are not automatically transmitted with the data.

### Syntax

*int far* StiDecSetMsiPlesseyCheckDigits( *int check\_digits* )

where:

*check\_digits* is one of the following values:

ONE\_CHECK\_DIGIT  
TWO\_CHECK\_DIGITS

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetNotisEditing

### Description

Strips the start and stop characters from decoded Codabar symbol.

### Syntax

*int far* StiDecSetNotisEditing( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR



## StiDecSetParameterEvent

### Description

Enables Parameter Event option.

### Syntax

```
int StiDecSetParameterEvent( int enable, void far (*eventFunction)(void))
```

where:

*enable* is one of the following values:

ENABLE

DISABLE

*eventFunction* is a pointer to a function which will be called if the Parameter Event is enabled when the Parameter Event occurs.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetParameterScanning

### Description

Enables or disables decoding of parameter bar codes. Note that the Set Defaults and Enable Parameter Scanning parameter bar codes can still be decoded.

### Syntax

*int* far StiDecSetParameterScanning( *int* *parameter\_scanning* )

where:

*parameter\_scanning* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetPowerMode

### Description

Determines whether power remains on when the decoder is not busy. In low power mode, the decoder enters a low power consumption mode whenever possible. In continuous power mode, the decoder does not automatically enter the low power consumption mode.

### Syntax

*int* far StiDecSetPowerMode( *int* *power\_mode*)

where:

*power\_mode* is one of the following values:

CONTINUOUS\_ON  
LOW\_POWER

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetPrefixSuffixValues

### Description

Appends a prefix and/or one or two suffixes to scan data for use in data editing.



**NOTE** In order to use Prefix/Suffix values, the Scan Data Transmission Format must be set.

### Syntax

*int far StiDecSetPrefixSuffixValues(int prefix, int suffix\_1, int suffix\_2)*

where:

*prefix*, *suffix\_1* and *suffix\_2* are the ASCII values desired.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetScanDataTransmissionFormat

### Description

Sets the Scan Data Transmission Format.

### Syntax

*int* far StiDecSetScanDataTransmissionFormat( *int* *transmission\_format* )

where:

*transmission\_format* is one of the following values:

- DATA\_AS\_IS
- DATA\_SUFFIX\_1
- DATA\_SUFFIX\_2
- DATA\_SUFFIX\_1\_SUFFIX\_2
- PREFIX\_DATA
- PREFIX\_DATA\_SUFFIX\_1
- PREFIX\_DATA\_SUFFIX\_2
- PREFIX\_DATA\_SUFFIX\_1\_SUFFIX\_2

### Return Values

- STATUS\_OK
- BAD\_PARAM
- BATCH\_ERROR

## StiDecSetScanningError

### Description

Enables Scanning Error option.

### Syntax

```
int StiDecSetScanningError( int enable, void far (*eventFunction)(void))
```

where:

*enable* is one of the following values:

ENABLE

DISABLE

*eventFunction* is a pointer to a function which will be called if the Scanning Event is enabled when the Scanning Event occurs.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetSystemError

### Description

Enables System Error option.

### Syntax

```
int StiDecSetSystemError( int enable, void far (*eventFunction)(void))
```

where:

*enable* is one of the following values:

ENABLE

DISABLE

*eventFunction* is a pointer to a function which will be called if the System Event is enabled when the System Event occurs.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetSystemEvent

### Description

Enables System Event option.

### Syntax

```
int StiDecSetSystemEvent( int enable, void far (*eventFunction)(void))
```

where:

*enable* is one of the following values:

ENABLE

DISABLE

*eventFunction* is a pointer to a function which will be called if the System Event is enabled when the System Event occurs.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR



## StiDecSetTimeOutBetweenSameSymbol

### Description

In Continuous triggering mode, sets the minimum time that must elapse before the decoder decodes a second bar code which is identical to the first decoded. This reduces the risk of accidentally scanning the same symbol twice. It is programmable in .1 second increments from 0.0 to 9.9 seconds.

### Syntax

*int* far StiDecSetTimeOutBetweenSameSymbol( *int* *time\_out* )

where:

*time\_out* is an integer value in the range [0..99], representing a time period from 0.0 to 9.9 seconds in 0.1 second increments.

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetTransmitCode39CheckDigit

### Description

Enables or disables Code 39 Check Digit.

### Syntax

*int far* StiDecSetTransmitCode39CheckDigit( *int check\_digit* )

where:

*check\_digit* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetTransmitCodeIdCharacter

### Description

Transmits Code ID character which identifies the code type of a scanned bar code. This may be useful when the decoder is decoding more than one code type. In addition to any single character prefix already selected, the code ID character is inserted between the prefix and the decoded symbol.

The user may select no code ID character, a Symbol Code ID character, or an AIM Code ID character. The Symbol Code ID characters are listed below.

A = UPC-A, UPC-E, UPC-E1, EAN-8, EAN-13

B = Code 39, Code 32

C = Codabar

D = Code 128, ISBT 128

E = Code 93

F = Interleaved 2 of 5

G = Discrete 2 of 5, or Discrete 2 of 5 IATA

J = MSI Plessey

K = UCC/EAN-128

L = Bookland EAN

M = Trioptic Code 39

N = Coupon Code

### Syntax

*int* far StiDecSetTransmitCodeIdCharacter( *int* code\_id )

where:

*code\_id* is one of the following values:

SYMBOL\_CODE\_ID\_CHARACTER

AIM\_CODE\_ID\_CHARACTER

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetTransmit12of5CheckDigit

### Description

Enables or disables the 1 2 of 5 check digit.

### Syntax

*int far* StiDecSetTransmit12of5CheckDigit( *int check\_digit* )

where:

*check\_digit* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetTransmitMsiPlesseyCheckDigit

### Description

Enables or disables transmission of MSI Plessey Check Digit.

### Syntax

*int* far StiDecSetTransmitMsiPlesseyCheckDigit( *int* *check\_digits* )

where:

*check\_digits* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetTransmitNoReadMessage

### Description

When enabled, the decoder transmits “NR” if a symbol does not decode. Any prefix or suffixes enabled are appended around this message.

### Syntax

*int* far StiDecSetTransmitNoReadMessage( *int enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetTransmitUpcACheckDigit

### Description

Transmits the symbol with or without the UPC-A check digit.

### Syntax

*int far* StiDecSetTransmitUpcACheckDigit( *int check\_digit* )

where:

*check\_digit* is one of the following values:

TRANSMIT\_CHECK\_DIGIT  
DO\_NOT\_TRANSMIT\_CHECK\_DIGIT

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetTransmitUpcE1CheckDigit

### Description

Transmits the symbol with or without the UPC-E1 check digit.

### Syntax

*int far* StiDecSetTransmitUpcE1CheckDigit( *int check\_digit* )

where:

*check\_digit* is one of the following values:

TRANSMIT\_CHECK\_DIGIT  
DO\_NOT\_TRANSMIT\_CHECK\_DIGIT

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR



## StiDecSetTransmitUpcECheckDigit

### Description

Transmits the symbol with or without the UPC-E check digit.

### Syntax

*int far* StiDecSetTransmitUpcECheckDigit( *int check\_digit* )

where:

*check\_digit* is one of the following values:

TRANSMIT\_CHECK\_DIGIT  
DO\_NOT\_TRANSMIT\_CHECK\_DIGIT

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetTriggeringModes

### Description

Triggers the decoder.

### Syntax

*int* StiDecSetTriggeringModes( *int* *triggering\_mode*)

where:

*triggering\_mode* is one of the following values:

LEVEL

PULSE

CONTINUOUS

BLINKING

HOST

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetTriopticCode39

### Description

Enables or disables Trioptic Code 39. Trioptic Code 39 symbols always contain six characters. Do not enable Trioptic Code 39 and Code 39 Full ASCII simultaneously.

### Syntax

*int* far StiDecSetTriopticCode39( *int enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetUccEan128

### Description

Enables or disables UCC/EAN-128.

### Syntax

*int far* StiDecSetUccEan128( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetUpcA

### Description

Enables or disables UPC-A.

### Syntax

*int far* StiDecSetUpcA( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetUpcAPreamble

### Description

Sets the UPC-A Preamble option. Three options are given for lead-in characters for UPC-A symbols transmitted to the host device: transmit system character only, transmit system character and country code ("0" for USA), and no preamble transmitted. The lead-in characters are considered part of the symbol.

### Syntax

*int* far StiDecSetUpcAPreamble( *int* preamble )

where:

*preamble* is one of the following values:

NO\_PREAMBLE  
SYSTEM\_CHARACTER  
SYSTEM\_CHARACTER\_COUNTRY\_CODE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetUpcE

### Description

Enables or disables UPC-E.

### Syntax

*int far* StiDecSetUpcE( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiDecSetUpcE1

### Description

Enables or disables UPC-E1.

### Syntax

*int far* StiDecSetUpcE1( *int enable* )

where:

*enable* is one of the following values:

ENABLE

DISABLE

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR



## StiDecSetUpcE1Preamble

### Description

Sets the UPC-E1 Preamble option. Three options are given for lead-in characters for UPC-E1 symbols transmitted to the host device: transmit system character only, transmit system character and country code ("0" for USA), and no preamble transmitted. The lead-in characters are considered part of the symbol.

### Syntax

*int* far StiDecSetUpcE1Preamble( *int* preamble )

where:

*preamble* is one of the following values:

NO\_PREAMBLE  
SYSTEM\_CHARACTER  
SYSTEM\_CHARACTER\_COUNTRY\_CODE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetUpcEanCouponCode

### Description

When enabled, decodes UPC-A, UPC-A with 2 supplemental characters, UPC-A with 5 supplemental characters, and UPC-A/EAN128 bar codes. UPC-A with supplemental characters need not be enabled.

### Syntax

*int* far StiDecSetUpcEanCouponCode( *int enable* )

where:

*enable* is one of the following values:

ENABLE  
DISABLE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetUpcEanSecurityLevel

### Description

Sets the UPC/EAN Security Level. There are four levels of decode security for UPC/EAN bar codes. Select a higher level of security are provided for decreasing levels of bar code quality. There is an inverse relationship between security and decoder aggressiveness, so be sure to choose only that level of security necessary for any given application.

- UPC/EAN Security Level 0: This default setting allows the decoder to operate in its most aggressive state, while providing sufficient security in decoding “in-spec” UPC/EAN bar codes.
- UPC/EAN Security Level 1: As bar code quality levels diminish, certain characters become prone to misdecodes before others (i.e., 1, 2, 7, 8). If you are experiencing misdecodes of poorly printed bar codes, and the misdecodes are limited to these characters, select this security level.
- UPC/EAN Security Level 2: If you are experiencing misdecodes of poorly printed bar codes, and the misdecodes are not limited to characters 1, 2, 7, and 8, select this security level.
- UPC/EAN Security Level 3: If you have tried Security Level 2, and are still experiencing misdecodes, select this security level. Be advised, selecting this option is an extreme measure against mis-decoding severely out of spec bar codes. Selection of this level of security significantly impairs the decoding ability of the decoder. If this level of security is necessary you should try to improve the quality of your bar codes.

### Syntax

*int far* StiDecSetUpcEanSecurityLevel( *int security\_level* )

where:

*security\_level* is one of the following values:

SECURITY\_LEVEL0  
SECURITY\_LEVEL1  
SECURITY\_LEVEL2  
SECURITY\_LEVEL3

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

## StiDecSetUpcEPreamble

### Description

Sets the UPC-E Preamble option. Three options are given for lead-in characters for UPC-E symbols transmitted to the host device: transmit system character only, transmit system character and country code ("0" for USA), and no preamble transmitted. The lead-in characters are considered part of the symbol.

### Syntax

*int far* StiDecSetUpcEPreamble( *int preamble* )

where:

*preamble* is one of the following values:

NO\_PREAMBLE  
SYSTEM\_CHARACTER  
SYSTEM\_CHARACTER\_COUNTRY\_CODE

### Return Values

STATUS\_OK  
BAD\_PARAM  
BATCH\_ERROR

# Chapter 4 Communications API

---

## Introduction

The SSI-SDK Serial Comm Driver is platform-specific software that communicates between the serial port on the host, or the serial port driver code in the target operating system, and the platform-independent SSI Kernel code. This driver's functions use the **StiComm\_** prefix.

This code contains the functions required to:

- Initialize the serial port; read and control the appropriate modem control lines (i.e., RTS and CTS)
- Send a buffer with completion notification and error checking
- Receive a buffer with completion notification and error checking
- Provide low-level hardware and software handshaking support.

The Serial Comm driver also provides the necessary OS-specific Timer functions required to time communications events in the SSI Kernel.

---

## Return Value Definitions

The functions in this chapter may return the following standard status codes:

- Any non-negative value (0 to 32767): parameter value.
- STATUS\_OK: the function parameters were verified. If a function must wait for an ACK from the decoder, STATUS\_OK indicates the ACK was received.
- MSG\_PENDING: a message is pending in the transmit buffer. No further messages can be placed in the buffer in this condition; the program must wait until there is room for a new message in the transmit buffer.
- NOT\_SUPPORTED: the last packet received from the decoder was either a NAK\_DENIED or NAK\_BAD\_CONTEXT. When retrieving parameters from the decoder, this indicates that the specified parameter is not supported by this decoder, or that it was unable to comply with the request.
- COMMUNICATIONS\_ERROR: either a timeout condition or the maximum number of retries (or both) occurred. The previous transmit message was not acknowledged, and therefore is questionable.
- BAD\_PARAM: the user-supplied parameter(s) in the function call was not in the expected range.
- BATCH\_ERROR: the limits of a batch function have been exceeded. Unless otherwise indicated, functions that start with **StiDecSet\_** are responsible for generating a batch command to establish decoder parameters. The parameters are not sent to the decoder until the **StiDecSendParams()** function is called, when a new batch is started.
- ERROR\_UNDEFINED: an error condition not specifically associated with the decoder or its communications.

---

## Initialize Communications Port

The SSI-SDK uses a commercially available, royalty-free serial communications library for Personal Computers. Functions referred to by the **Sio\_** prefix are provided by the Serial I/O Library. The library of functions is identical under DOS and Windows and provides direct access to the serial communications hardware.

## SioBaud

### Description

Sets the baud rate without resetting the port. It is used to change the baud rate after calling **SioReset**.

### Syntax

*int* SioBaud(*int* Port,*int* BaudCode)

Code	Rate	Name	Code	Rate	Name
0	300	Baud300	5	9600	Baud9600
1	600	Baud600	6	19200	Baud19200
2	1200	Baud1200	7	38400	Baud38400
3	2400	Baud2400	8	57600	Baud57600
4	4800	Baud4800	9	115200	Baud115200

where:

*Port*: Port selected (COM1 - COM20)

*BaudCode*: Baud code

### Return Values

-4 : No such port. Expect 0 to MaxPort.

-11 : Bad baud rate code.

## SioBrkSig

### Description

Controls the BREAK bit in the line status register. The legal commands are:

ASSERT\_BREAK ('A') to assert BREAK  
CANCEL\_BREAK ('C') to cancel BREAK  
DETECT\_BREAK ('D') to detect BREAK

### Syntax

*int* SioBrkSig(*int* Port,*char* Cmd)

*Port*: Port selected (COM1 thru COM20)

*char* *Cmd*: ASSERT, CANCEL, or DETECT

### Return Values

- 2 : Port not enabled. Call **SioReset** first.
- 4 : No such port. Expect 0 to MaxPort.
- 6 : Illegal command. Expected 'A', 'C', or 'D'.
- >0 : BREAK signal detected (DETECT command only)

### Notes

- The Serial Comm driver also provides the necessary OS-specific Timer functions required to time communications events in the SSI Kernel.
- The periodic tic timer (18.6 Hz) is used for all timing. All required time functions are implemented within the Serial Comm driver functions.



## SioCTS

### Description

Reads the Clear to Send (CTS) modem status bit.

The CTS line is used by some error correcting modems to implement hardware flow control. The modem drops CTS to signal the computer not to send data and raises CTS to signal the computer to continue.

### Syntax

*int* SioCTS(*int Port*)

where:

*int Port*: Port selected (COM1 thru COM20)

### Return Values

- 2 : Port not enabled. Call SioReset first.
- 4 : No such port. Expect 0 to MaxPort.
- 0 : CTS is clear.
- >0 : CTS is set.

### Note

- Send a buffer with completion notification and error checking.

## SioDone

### Description

Terminates further serial processing. You **MUST** call **SioDone** before exiting your application so that interrupts can be restored to their original state. Failure to do this can crash the operating system. If you do not call **SioDone** before exiting, re-boot your computer. You may call **SioDone** even if **SioReset** has not been called.

**SioDone** dereferences the transmit and receive buffers set up by **SioRxQue** and **SioTxQue**.

### Syntax

*int* SioDone(*int* Port)

where:

*Port*: Port selected (COM1 thru COM20)

### Return Values

-2 : Port not enabled. Call **SioReset** first.

-4 : No such port. Expect 0 to MaxPort.

## SioFIFO

### Description

Enables both transmit and receive FIFOs for 16550 UARTS, and sets the trigger level at which receive interrupts are generated.

For example, if the FIFO level is set to 8, the 16550 UART does not generate an interrupt until 8 bytes are received. This reduces the number of interrupts generated and allows faster processing with slower machines or when running simultaneous ports.

To test if your port is a 16550 UART, call **SioFIFO** with a **LevelCode** of other than **FIFO\_OFF**. **SioFIFO** can be called for the 8250 and 16450 UART without negative effect.

Code Name	Trigger Level
-1: <b>FIFO_OFF</b>	Disable FIFO
0: <b>LEVEL_1</b>	1 byte
1: <b>LEVEL_4</b>	4 bytes
2: <b>LEVEL_8</b>	8 bytes
3: <b>LEVEL_14</b>	14 bytes

### Syntax

*int* SioFIFO(*int Port*,*int LevelCode*)

where:

*Port*: Port selected (COM1 thru COM20)

*LevelCode*: FIFO level code (see below)

### Return Values

-2 : Port not enabled. Call SioReset first.

-4 : No such port. Expect 0 to MaxPort.

>0 : FIFO level set.

0 : FIFO level not set (not 16550).

## SioFlow

### Description

Enables or disables hardware flow control, which uses RTS and CTS to control data flow between the modem and the computer.

**Tics** is the number of timer tics before **SioPutc** returns timeout on transmission because CTS is down. To disable flow control, call **SioFlow** with Tics = -1.

For hardware flow control to work correctly, your modem must also be configured to work with hardware flow control, and your computer-to-modem cable must have RTS and CTS wired straight through. If you enable hardware flow control, do not modify the RTS line (by calling **SioRTS**) unless you are an experienced user.

Flow control is disabled after resetting a port. To explicitly disable hardware flow control, call **SioFlow** with Flag=FALSE.

### Syntax

```
int SioFlow(int Port,int Tics)
```

where:

*Port*: Port selected (COM1 thru COM20)

*Tics*: # tics before TX timeout

### Return Values

- 2 : Port not enabled. Call **SioReset** first.
- 4 : No such port. Expect 0 to MaxPort.
- =0 : Flow control disabled.
- >0 : Flow control enabled.

## SioGetc

### Description

Reads a byte from the selected serial port and waits for the number of system tics given by the Tics argument before returning “timed out”. There are 18.2 tics per second. Try to limit Tics since no other Windows task can run while waiting for input.

### Syntax

*int* SioGetc(*int* Port, *int* Tics)

where:

*Port*: Port selected (COM1 thru COM20)

### Return Values

- 2 : Port not enabled. Call **SioReset** first.
- 4 : No such port. Expect 0 to MaxPort.
- 1 : If timed out.
- >0 : Character read.

## SioGetDiv

### Description

Reads the baud rate divisor. The baud rate can then be determined by the divisor.

### Syntax

*int* SioGetDiv(*int* Port)

Baud	Divisor	Baud	Divisor	Baud	Divisor
300	0180	4800	0018	38400	0003
1200	0060	9600	000C	57600	0002
2400	0030	19200	0006	115200	0001

where:

*Port*: Port selected (COM1 thru COM20)

### Return Values

- 2 : Port not enabled. Call SioReset first.
- 4 : No such port. Expect 0 to MaxPort.
- >0 : Baud rate divisor.

## SioGets

### Description

Reads bytes from the selected serial port. This function reads either the number of requested bytes, or fewer if no character is immediately available. **SioGets** cannot return more characters than are in the receive buffer at the time it is called. The number of characters read is returned.

### Syntax

```
int SioGets(int Port, char *Buffer, int Length)
```

where:

*Port*: Port selected (COM1 thru COM20)

*Buffer*: Character buffer

*Length*: Length of Buffer (# of requested bytes)

### Return Values

- 2 : Port not enabled. Call **SioReset** first.
- 4 : No such port. Expect 0 to MaxPort.
- 1 : If timed out.
- >0 : Number of characters read into Buffer.

## SioLine

### Description

- ✓ **NOTE** This function has not been used in the provided code as the transmitter empty bit does not appear to set correctly. Instead, the hardware is read directly using SioRead (int Port, int Reg) where Reg. is 5 (the Line Status Register). The bit masks are identical to those below.

Reads the line status register. The individual bit masks are:

- 0x40 = Transmitter empty.
- 0x20 = Transmitter buffer empty.
- 0x10 = Break detected.
- 0x08 = Framing error.
- 0x04 = Parity error.
- 0x02 = Overrun error.
- 0x01 = Data ready.

### Syntax

*int* SioLine(*int* Port)

where:

*Port*: Port selected (COM1 thru COM20)

### Return Values

- 2 : Port not enabled. Call SioReset first.
- 4 : No such port. Expect 0 to MaxPort.
- >0 : Line status (rightmost byte of word).



## SioModem

### Description

Reads the modem register. The bit definitions for the function mask are as follows:

Bit	Name	Function
7	DCD	Data Carrier Detect
6	RI	Ring Indicator
5	DSR	Data Set Ready
4	CTS	Clear To Send
3	DeltaDCD	DCD has changed
2	DeltaRI	RI has changed
1	DeltaDSR	DSR has changed
0	DeltaCTS	CTS has changed

Bits 4 through 7 represent the absolute state of their respective RS-232 inputs. Bits 0 through 3 represent a change in the state of their respective RS-232 inputs since last read. Once UART register 3 is read, the Delta bits are cleared, so do not depend on the Delta bits.

### Syntax

*int* SioModem(*int* Port, *int* Mask)

where:

*Port*: Port selected (COM1 thru COM20)

*Mask*: Modem function mask

### Return Values

- 2 : Port not enabled. Call **SioReset** first.
- 4 : No such port. Expect 0 to MaxPort.
- >0 : Modem status (rightmost byte of word).

## SioParms

### Description

Sets the parity, stop bits, and word length. If the default parity (none), stop bits (1), or word length (8) is not acceptable, change them by calling SioParms, either before or after calling SioReset.

	Value	Description	Name
<b>ParityCode</b>	*0	no parity	NoParity
	1	odd parity	OddParity
	3	even parity	EvenParity
<b>StopBitsCode</b>	*0	1 stop bit	OneStopBit
	1	2 stop bits	TwoStopBits
<b>WordLengthCode</b>	0	5 data bits	WordLength5
	1	6 data bits	WordLength6
	2	7 data bits	WordLength7
	*3	8 data bits	WordLength8

### Syntax

*int* SioParms(*int* Port,*int* Parity,*int* StopBits, *int* DataBits)

where:

*Port*: Port selected (COM1 - COM20)

*Parity*: Parity code [0,1,2]

*StopBits*: Stop bits code [0,1]

*DataBits*: Word length code [0,1,2,3]

### Return Values

- 4 : No such port. Expect 0 to MaxPort.
- 7 : Bad parity code selected. Expecting 0 to 2.
- 8 : Bad stop bits code. Expecting 0 or 1.
- 9 : Bad word length code. Expecting 0 to 3.

## SioPorts

### Description

Call the **SioPorts** function before ANY other serial functions. **SioPorts** function sets the total number of ports, the first DigiBoard (or BOCA board) port and the DigiBoard (or BOCA board) status register address. Once **SioPorts** is called, all COM ports starting with "FirstPort" are treated as DigiBoard (or BOCA board) ports. The default setup is 4 standard PC ports and no DigiBoard or BOCA ports [**SioPorts**(4,4,0,PC\_PORTS) ].

### Syntax

*int SioPorts(int NbrPorts,int FirstPort,int StatusReg, int Code)*

where:

*NbrPorts*: Total number of ports

*FirstPort*: First DigiBoard port

*StatusReg*: DigiBoard Status Register

*Code*: PC\_PORTS, DIGIBOARD, or BOCABOARD

### Return Values

-4 : No such port. Expect 0 to 9.

0 : No error (sets MaxPort to NumberPorts-1).

## SioPutc

### Description

Transmits one character over the selected serial line.

If flow control is enabled, **SioPutc** may return a -1 (time out) if the number of tics specified in the **SioFlow** function was exceeded waiting for the modem to raise CTS.

If transmitter interrupts are enabled (there are separate versions of the library for transmitter interrupts enabled), the byte is placed in the transmit buffer and waits for transmission by the interrupt service routine.

### Syntax

```
int SioPutc(int Port,char Ch)
```

where:

*Port*: Port selected (COM1 thru COM20)

*Ch*: Character to send

### Return Values

- 2 : Port not enabled. Call SioReset first.
- 4 : No such port. Expect 0 to MaxPort.
- 1 : Timed out waiting for CTS (flow control enabled)

## SioPuts

### Description

Transmits each buffer character over the selected serial line, and returns the number of characters transmitted. This function can take a long time for large buffers if transmitter interrupts are not enabled!

If flow control is enabled, **SioPuts** may transmit fewer characters than requested if the number of tics specified in the **SioFlow** function was exceeded waiting for the modem to raise CTS.

If transmitter interrupts are enabled, **SioPuts** transmits fewer than the number of characters requested if the transmit buffer would overflow. The actual number of characters transmitted is returned.

### Syntax

```
int SioPuts(int Port,char *Buffer,int Length)
```

where:

*Port*: Port selected (COM1 thru COM20)

*Buffer*: Character buffer

*Length*: Length of Buffer

### Return Values

- 2 : Port not enabled. Call **SioReset** first.
- 4 : No such port. Expect 0 to MaxPort.
- >=0: Number of characters actually transmitted.

## SioRead

### Description

Reads the contents of any of the 7 UART registers. This function is useful when debugging application programs and as a method for verifying UART contents.

### Syntax

```
int SioRead(int Port,int Reg)
```

where:

*Port*: Port selected (COM1 thru COM20)

*Reg*: UART register (0 to 7)

### Return Values

-3 : No buffer available. Call **SioRxBuf** first.

-4 : No such port. Expect 0 to MaxPort.

## SioReset

### Description

Initializes the selected serial port. Call **SioReset** after calling **SioParm** and **SioRxBuf** but before making any other calls to the serial library. **SioReset** uses the parity, stop bits, and word length value previously set if **SioParm** was called, otherwise the default values (see **SioParm**) are used.

COM1 and COM3 share the same interrupt vector, so cannot operate simultaneously. Similarly, COM2 and COM4 cannot operate simultaneously. Any other combination of two ports can be used.

By specifying NORESET (-1) for the baud rate code, the port will NOT be reset. This is used to “take over” a port from a host communications program that allows a “DOS gateway”. External protocols can be implemented this way. See **SioBaud** for a list of the baud rate codes.

### Syntax

```
int SioReset(int Port,int BaudCode)
```

where:

*Port*: Port selected (COM1 thru COM20)

*BaudCode*: Baud code or -1

### Return Values

- 3 : No buffer available. Call **SioRxBuf** first.
- 4 : No such port. Expect 0 to MaxPort.
- 11 : Bad baud rate code selected. Expecting 0 to 9.
- 13 : UART undefined. **SioUART**(Port,0) was called previously.
- 14 : Bad or missing UART. You may not have hardware present.
- 15 : Port already enabled. **SioReset** has already been called.
- 16 : Interrupt already in use.

## SioRTS

### Description

Controls the Request to Send (RTS) bit in the modem control register.

The RTS line is used by some error correcting modems to implement hardware flow control. The host drops RTS to signal the modem not to send data, and raise RTS to signal the modem to continue. Set RTS when communicating with a modem, unless you are using Flow Control.

SET\_LINE ('S') - set RTS (ON)

CLEAR\_LINE ('C') | clear RTS (OFF)

READ\_LINE ('R') - read RTS

### Syntax

*int* SioRTS(*Port*, *char Cmd*)

where:

*Port*: Port selected (COM1 thru COM20)

*Cmd*: RTS command (SET, CLEAR, or READ)

### Return Values

-2 : Port not enabled. Call **SioReset** first.

-4 : No such port. Expect 0 to MaxPort.

-5 : Command is not one of 'S', 'C', or 'R'.

0 : RTS is OFF (READ\_LINE Command).

>0 : RTS is ON (READ\_LINE Command).



## SioRxBuf

### Description

Sets the address selector and size of the receive buffer. A receive buffer is required for each port in simultaneous operation since the receive function is interrupt driven. It must be called before any incoming characters can be received. **SioRxBuf** must be called before **SioReset**.

Size Code	Buffer Size	Name
4	128 bytes	Size128
5	256 bytes	Size256
6	512 bytes	Size512
7	1024 bytes	Size1024 or Size1K
8	2048 bytes	Size2048 or Size2K
9	4096 bytes	Size4096 or Size4K
10	8192 bytes	Size8192 or Size8K
11	16384 bytes	Size16384 or Size16K
12	32768 bytes	Size32768 or Size32K

### Syntax

```
int SioRxBuf(int Port,int Selector,SizeCode)
```

where:

*Port*: Port selected (COM1 thru COM20)

*Selector*: Receive buffer selector

*SizeCode*: Buffer size code

### Return Values

- 4 : No such port. Expect 0 to MaxPort.
- 10 : Bad buffer size code. Expecting 0 to 11.

## SioRxClear

### Description

Deletes any characters in the receive buffer for the specified port. After execution, the receive buffer is empty. Call **SioRxBuf** after resetting a port to delete any spurious characters.

### Syntax

```
int SioRxClear(int Port)
```

where:

*Port*: Port selected (COM1 thru COM20)

### Return Values

-2 : Port not enabled. Call **SioReset** first.

-4 : No such port. Expect 0 to MaxPort.

## SioRxQue

### Description

Returns the number of characters in the receive queue at the time of the call. It can be used to implement XON/XOFF flow control.

### Syntax

```
int SioRxQue(int Port)
```

where:

*Port*: Port selected (COM1 thru COM20)

### Return Values

-2 : Port not enabled. Call **SioReset** first.

-4 : No such port. Expect 0 to MaxPort.

## SioTxBuf

### Description

Assigns the address selector and size of the transmit buffer for each port in simultaneous operation. **SioTxBuf()** must be called before **SioReset**.

Size Code	Buffer Size	Name
4	128 bytes	Size128
5	256 bytes	Size256
6	512 bytes	Size512
7	1024 bytes	Size1024 or Size1K
8	2048 bytes	Size2048 or Size2K
9	4096 bytes	Size4096 or Size4K
10	8192 bytes	Size8192 or Size8K
11	16384 bytes	Size16384 or Size16K
12	32768 bytes	Size32768 or Size32K

This function is not used unless the transmitter interrupts are enabled.

### Syntax

*int SioTxBuf(int Port,int Selector,int SizeCode)*

where:

*Port*: Port selected (COM1 thru COM20)

*Selector*: Receive buffer selector

*SizeCode*: Buffer size code

### Return Values

- 4 : No such port. Expect 0 to MaxPort.
- 10 : Bad buffer size code. Expecting 0 to 11.

## SioTxClear

### Description

Deletes any characters in the transmit buffer for the specified port. After execution, the transmit buffer is empty. Once this function is called, any character in the transmit buffer (put there by **SioPutc**) is lost and not transmitted. This function is not used unless the transmitter interrupts are enabled.

### Syntax

```
int SioTxClear(int Port)
```

where:

*Port*: Port selected (COM1 thru COM20)

### Return Values

-2 : Port not enabled. Call **SioReset** first.

-4 : No such port. Expect 0 to MaxPort.

## SioTxFlush

### Description

Re-enables transmitter interrupts if they were disabled by CTS dropping. This forces all data out of the transmitter queue unless CTS drops again.

Once the transmitter interrupt is disabled (by CTS dropping), you may restart it by calling one of the serial I/O functions (**SioPutc**, **SioPuts**, **SioGetc**, or **SioGets**), **SioTxQue**, or **SioTxFlush**.

The main purpose of **SioTxFlush** is to provide an explicit means of restarting transmitter interrupts.

### Syntax

```
int SioTxFlush(int Port)
```

where:

*Port*: Port selected (COM1 thru COM20)

### Return Values

-2 : Port not enabled. Call SioReset first.

-4 : No such port. Expect 0 to MaxPort.

## SioTxQue

### Description

Returns the number of characters in the transmit queue at the time of the call. This function is only used if the transmitter interrupts are enabled.

### Syntax

```
int SioTxQue(int Port)
```

where:

*Port*: Port selected (COM1 thru COM20)

### Return Values

-2 : Port not enabled. Call **SioReset** first.

-4 : No such port. Expect 0 to MaxPort.

## SioUnGetc

### Description

Returns ("pushes") the character back into the serial input buffer. The character pushed is the next character returned by **SioGetc**. Only one character can be pushed back. This function works like the "ungetc" function in C language.

### Syntax

```
int SioUnGetc(int Port, char Ch)
```

where:

*Port*: Port selected (COM1 thru COM20)

*Ch*: Character to ungetc

### Return Values

-2 : Port not enabled. Call **SioReset** first.

-4 : No such port. Expect 0 to MaxPort.



## StiCommChangeDecoderSettings

### Description

Commands the decoder to change its baud rate, parity, and stop bits to a new setting. After the command is acknowledged by the decoder, this function changes the host communications settings to match those of the decoder. If the command is not acknowledged, no changes are made to the host communication settings.

### Syntax

```
int far StiCommChangeDecoderSettings( COMM_STRUCT comm, int change_type )
```

where:

*comm* is a structure specifying all communications parameters for connection with the decoder.

*change\_type* is:

- PERMANENT
- TEMPORARY

### Return Values

- STATUS\_OK
- NOT\_SUPPORTED
- COMMUNICATIONS\_ERROR
- BAD\_PARAM

## ***StiCommInitPort***

### **Description**

Sets up serial communications parameters such as baud rate, parity, buffering, and handshaking on the host. This function does not change the communications settings for the decoder.

### **Syntax**

*int far* StiCommInitPort( *COMM\_STRUCT comm* )

where:

*comm* is a structure specifying all of the communications parameters for connection with the decoder.

### **Return Values**

STATUS\_OK  
BAD\_PARAM  
NOT\_SUPPORTED

## StiCommRxInterrupt

### Description

Receive Interrupt Service Routine. Will be implemented in the serial I/O library functionality.

### Syntax

```
void interrupt StiCommRxInterrupt( )
```

### Note

Provides low-level hardware and software handshaking support.

## StiCommTxInterrupt

### Description

Transmit Interrupt Service Routine. Will be implemented in the serial I/O library functionality.

### Syntax

```
void interrupt StiCommTxInterrupt()
```

### Note

- Receive a buffer with completion notification and error checking.

# Chapter 5 Kernel API

---

## Introduction

The SSI-SDK Kernel (functions denoted by the `StiSsi_` prefix) performs all functions required to maintain the SSI between the host and SSI-compliant decoder, including:

- Creation of message packets destined for the decoder
- Interpretation of message packets from the decoder
- Assembly of multi-packet messages from the decoder
- High-level implementation of interface handshaking modes
- Appropriate communications to the Host application, through the Host API function set, of interface events and data.

The Kernel also can detect and recover from interface error conditions, such as bad packets (invalid checksum, bad format, unexpected format, out of context messages, communications event timeouts, and protocol violations).

The Kernel uses the periodic tic timer interrupt (18.2 Hz) that typically runs on a PC. After every timer tic, the Kernel executes code dealing with the following aspects:

- It determines if a complete message was received and is in the queue.
- It deals with any handshaking that must be performed. If the RTS line was shut down because the receive queue was full, it monitors the receive queue in an attempt to restore the RTS line to its operational state.
- If a message packet is received which indicates that a specific event has occurred, the Kernel sees if the event is associated with a “callback” function. If the callback function is defined, it executes the function. Otherwise, it keeps a count of how many times the event has occurred.
- If a NAK is received, the Kernel retries the operation as defined in Chapter 2, Introduction to SSI. If an invalid packet is received, the Kernel retries the message responsible for the error.
- If an ACK is received unexpectedly, the ACK packet is ignored (discarded). Unexpected ACK packets are not considered errors.

---

## Return Values Definitions

The functions in this chapter may return the following standard status codes:

- Any non-negative value (0 to 32767): parameter value.
- STATUS\_OK: the function parameters were verified. If a function must wait for an ACK from the decoder, STATUS\_OK indicates the ACK was received.
- MSG\_PENDING: a message is pending in the transmit buffer. No further messages can be placed in the buffer in this condition; the program must wait until there is room for a new message in the transmit buffer.
- NOT\_SUPPORTED: the last packet received from the decoder was either a NAK\_DENIED or NAK\_BAD\_CONTEXT. When retrieving parameters from the decoder, this indicates that the specified parameter is not supported by this decoder, or that it was unable to comply with the request.
- COMMUNICATIONS\_ERROR: either a timeout condition or the maximum number of retries (or both) occurred. The previous transmit message was not acknowledged, and therefore is questionable.
- BAD\_PARAM: the user-supplied parameter(s) in the function call was not in the expected range.
- BATCH\_ERROR: the limits of a batch function have been exceeded. Unless otherwise indicated, functions that start with **StiDecSet\_** are responsible for generating a batch command to establish decoder parameters. The parameters are not sent to the decoder until the **StiDecSendParams()** function is called, when a new batch is started.
- ERROR\_UNDEFINED: an error condition not specifically associated with the decoder or its communications.

## PARAM\_REQUEST

### Description

Returns the current decoder value for the requested parameter.

### Syntax

*int* far StiSsiParamRequest( *int param* )

where:

*param* specifies a single, specific parameter stored in non-volatile memory in the decoder.

### Return Values

Returns the current decoder value for the requested parameter. If an error occurs, the returned error status is one of the following:

NOT\_SUPPORTED  
COMMUNICATION\_ERROR  
BAD\_PARAM

## PARAM\_REQUEST\_MULTIPLE

### Description

Returns the current decoder value for the requested parameters.

### Syntax

```
int far StiSsiParamRequestMultiple( int far param[ ], int length )
```

where:

*param[ ]* is an array of specific parameters which are stored in non-volatile memory on the decoder.

*length* specifies how many individual parameters are contained within param[].

### Return Values

If an error occurs, the returned error status is one of the following:

NOT\_SUPPORTED

COMMUNICATION\_ERROR

BAD\_PARAM



## PARAM\_SEND

### Description

Changes the specified parameter value. Changes can be either PERMANENT or TEMPORARY. PERMANENT changes are stored in the non-volatile memory and retain their settings after cycling power to the decoder. TEMPORARY changes lose effect when power is cycled on the decoder or if they are overwritten by another **StiSsiParamSend()** to the same parameter.

### Syntax

*int far* StiSsiSendParams( *int change\_type*, *int beep*, *int func\_wait* )

where:

*change\_type* is one of the following:

PERMANENT  
TEMPORARY

*beep* is one of the following values:

ONE\_SHORT\_HIGH  
TWO\_SHORT\_HIGH  
THREE\_SHORT\_HIGH  
FOUR\_SHORT\_HIGH  
FIVE\_SHORT\_HIGH

ONE\_SHORT\_LOW  
TWO\_SHORT\_LOW  
THREE\_SHORT\_LOW  
FOUR\_SHORT\_LOW  
FIVE\_SHORT\_LOW

ONE\_LONG\_HIGH  
TWO\_LONG\_HIGH  
THREE\_LONG\_HIGH  
FOUR\_LONG\_HIGH  
FIVE\_LONG\_HIGH

ONE\_LONG\_LOW  
TWO\_LONG\_LOW  
THREE\_LONG\_LOW  
FOUR\_LONG\_LOW  
FIVE\_LONG\_LOW

FAST\_WARBLE  
SLOW\_WARBLE

MIX1

MIX2

MIX3

MIX4

If *beep* is not one of these values, no beep is generated. This does not cause an error condition.

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### **Return Values**

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

## StiSsiCmdAck

### Description

Interprets and verifies the CMD\_ACK Opcode format. It marks the previous packeted command as sent, allowing the next message format to be queued for transmission.

### Syntax

```
int far StiSsiCmdAck( char far rx_cmd[ ] )
```

where:

*char rx\_cmd[ ]* is the entire buffered command including the length, Ack Opcode, and checksum characters.

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

## StiSsiCmdNak

### Description

Interprets and verifies the CMD\_NAK Opcode format.

- If the NAK Type is NAK\_RESEND, the previous packeted command is resent in accordance with the retry provisions of the Simple Serial Interface.
- If the NAK Type is NAK\_DENIED, the previous packeted command is marked as sent and returns an ERROR\_UNDEFINED.
- If the NAK Type is NAK\_BAD\_CONTEXT, the previous packeted command is marked as sent and returns an ERROR\_UNDEFINED.

### Syntax

```
int far StiSsiCmdNak( char far rx_cmd[ ] )
```

where:

*char rx\_cmd[ ]* is the entire buffered command including the length, Nak Opcode, and checksum characters.

### Return Values

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiSsiCommandSend

### Description

Queues up a command to be sent to the decoder. This function appends checksum information to the command string.

### Syntax

```
int far StiSsiCommandSend( char far *ptr, int length, int func_wait )
```

where:

*ptr* is a pointer to the command structure that must be sent to the decoder WITHOUT checksum information.

*length* specifies the length, in bytes, of this command sequence without checksum digits.

*func\_wait* is one of the following values:

WAIT: Wait for the function to complete before returning to the caller.

NO\_WAIT: Do not wait for the function to complete before returning to the caller.

### Return Values

if (*func\_wait* == WAIT)

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

if (*func\_wait* == NO\_WAIT)

MSG\_PENDING

BAD\_PARAM

### Note

Interpretation of message packets from the decoder.

## StiSsiDecodeData

### Description

Interprets and verifies the DECODE\_DATA Opcode format. It copies the decoded information into a DECODE\_DATA\_STRUCT. If a callback function is defined, the callback is executed. If no callback function is defined, a flag is set indicating the availability of data.

### Syntax

```
int far StiSsiDecodeData( char far rx_cmd[ ] )
```

where:

*char rx\_cmd[ ]* is the entire buffered command including the length, Decode\_Data Opcode, and checksum characters.

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

## StiSsiEvent

### Description

Interprets the Event Opcode format and services the decoder event represented by the Event Code. If a callback function is defined for a specific Event Code, the callback is executed. If no callback function is defined, a counter is incremented to reflect the event.

### Syntax

```
int far StiSsiEvent( char far rx_cmd[ ] )
```

where:

*char rx\_cmd[ ]* is the entire buffered command including the length, Event Opcode, and checksum characters.

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

## StiSsiGetAllParams

### Description

Retrieves all current decoder parameter values. The parameters are stored starting the location *ptr*[0]. Up to *maxlength* characters of parameter data may be stored in *ptr*[ ]. The parameters are returned as data pairs consisting of (parameter\_number, parameter\_value). The user must parse through the data pairs and associate each parameter\_number with a specific decoder capability.

If *maxlength* is less than the number of decoder parameters retrieved, the remaining parameters are discarded. It is recommended that *ptr* be at least 256 bytes long.

### Syntax

```
int far StiSsiGetAllParams( unsigned char far *ptr, int maxlength )
```

where:

*ptr*[ ] is an array of *maxlength* bytes where the decoder's parameter information will be deposited.

### Return Values

the number of bytes copied into *ptr*[ ]. If an error occurs, the returned error status is one of the following:

NOT\_SUPPORTED  
COMMUNICATION\_ERROR



## StiSsiParamPacket

### Description

Verifies the specified parameter against its *low\_limit* and *hi\_limit* values. If the parameter is correct, it attempts to put the opcode and parameter into the `ParamBatch.data[ ]` array. The contents of the array are processed by **StiSsiParamSend**.

### Syntax

*int far* StiSsiParamPacket( *int opcode*, *int param*, *int low\_limit*, *int hi\_limit* )

where:

*opcode* specifies the decoder parameter to be modified.

*param* is the new setting for the decoder parameter.

*low\_limit* is the lowest allowable setting for the parameter.

*hi\_limit* is the highest allowable setting for the parameter.

### Return Values

STATUS\_OK

BAD\_PARAM

BATCH\_ERROR

## StiSsiParamSend

### Description

Interprets and verifies the PARAM\_SEND Opcode format. It verifies the message and uses the parameter data to respond to the PARAM\_REQUEST command.

### Syntax

```
int far StiSsiParamSend( char far rx_cmd[ ] )
```

where:

*char rx\_cmd[ ]* is the entire buffered command including the length, Param\_Send Opcode, and checksum characters.

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

## StiSsiRecovery

### Description

Performs retry operations on Host API Messages, ACK, or NAK messages. It retries the last transmission with the resend status bit set. If the maximum number of retries for a given message is exhausted, the function returns a COMMUNICATIONS\_ERROR.

### Syntax

*int far* StiSsiRecovery( *void* )

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

## StiSsiReplyRevision

### Description

Interprets and verifies the REPLY REVISION Opcode format. It copies the revision information into a REVISION\_DATA\_STRUCT.

### Syntax

```
int far StiSsiReplyRevision( char far rx_cmd[ ] )
```

where:

*char rx\_cmd[ ]* is the entire buffered command including the length, Reply\_Revision Opcode, and checksum characters.

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

### Notes

- High-level implementation of interface handshaking modes.
- Appropriate communications to the Host application, through the Host API function set, of interface events and data.
- This also includes the capability to detect and recover from interface error conditions such as bad packets, examples: invalid checksum, bad format, unexpected format, out of context messages, communications event timeouts, and protocol violations.

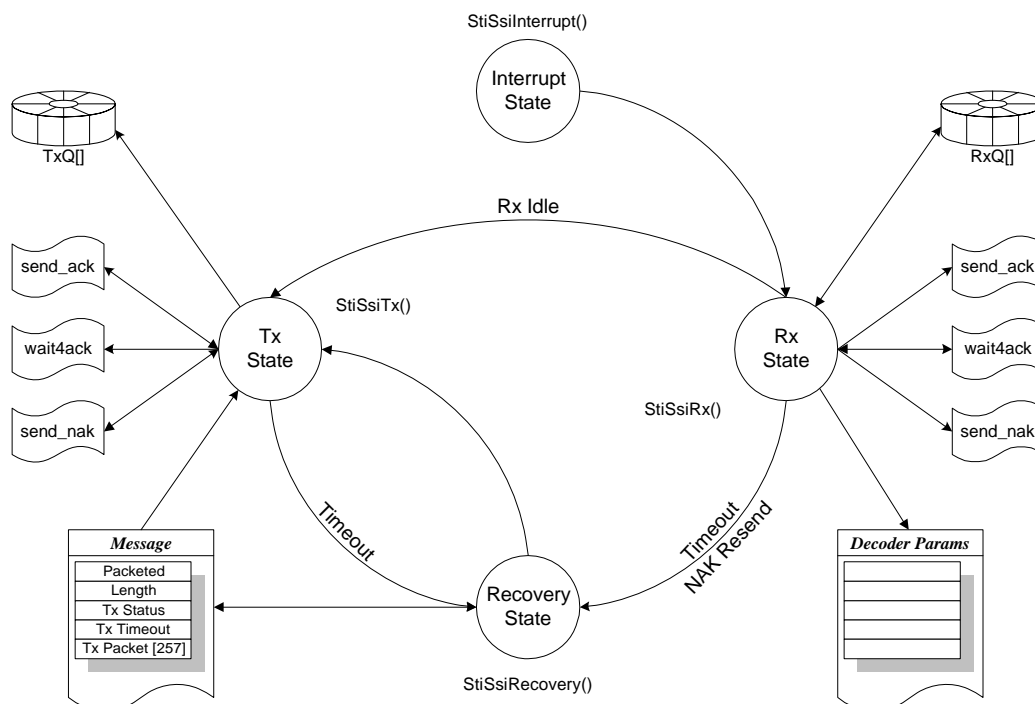
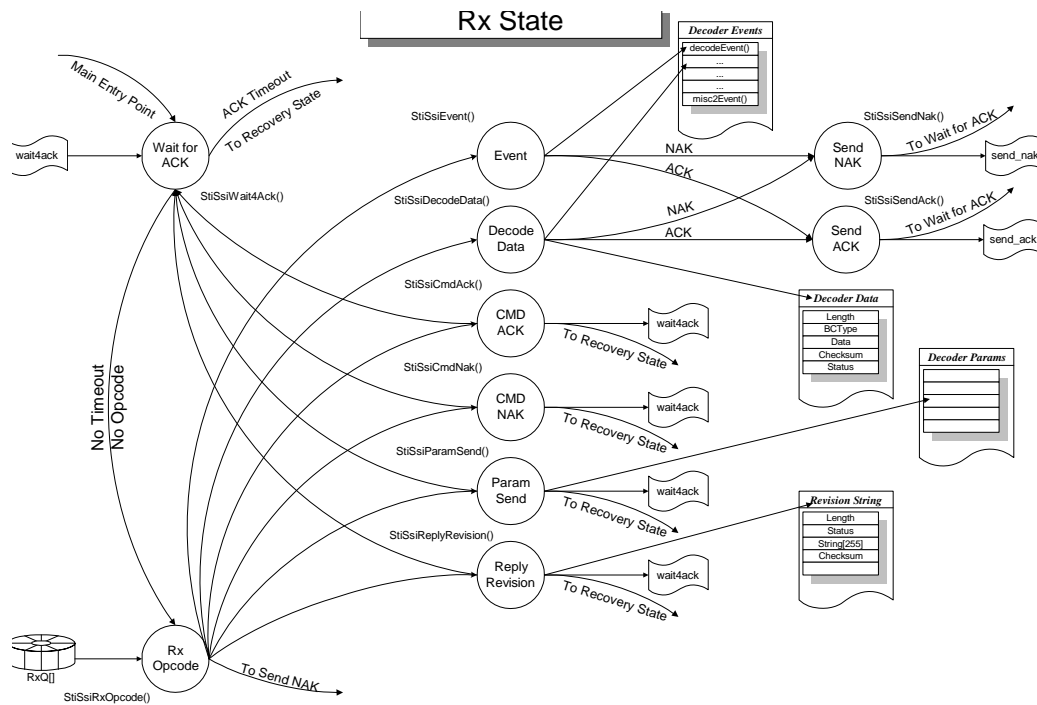


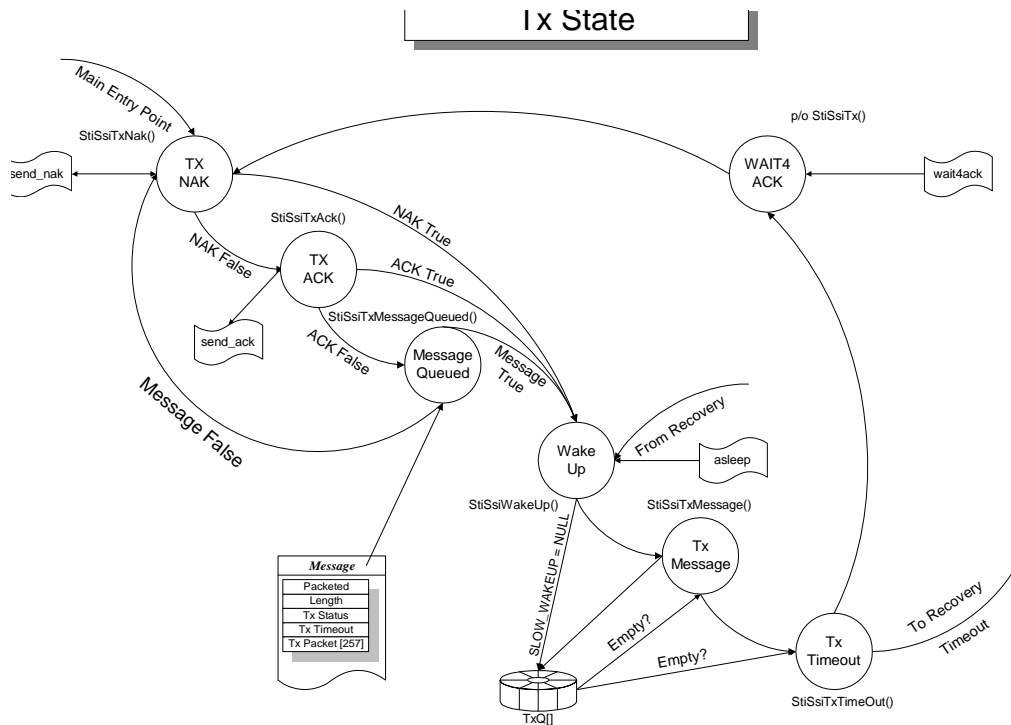
Figure 5-1 Kernel State Machine

These requirements are shown in the State Diagrams. The top level state diagram, <Blue>Figure 5-1, is the Kernel State Machine. Enter the Kernel State Machine via the **StsSsiInterrupt()** function. On even ticks, the TX State of the state machine is serviced. On odd ticks, the RX State of the state machine is serviced. This reduces the amount of overhead that the Kernel imposes on the host machine. Since serial communications is relatively slow, and the communications is running half-duplex, the Kernel does not need to run the entire machine during each interrupt.



**Figure 5-1. RX State Machine Details**

<Blue>Figure 5-1 shows the inner details of the RX State machine, including the processing required for ACK/NAK timeouts as well as received command processing. Data structures show how received data is stored for the host application. Callback functions, where implemented, allow the Host API to hook into the data and event processing. High-level communications handshaking is represented by the various flags **wait4ack**, **send\_nak**, and **send\_ack**. Hooks to the Recovery State permit Host API Messages to be retried as defined in the Simple Serial Interface protocol.



**Figure 5-2. TX State Machine Details**

<Blue>Figure 5-2 shows the inner details of the TX State machine, including the processing of high-level ACK/NAK handshaking and Host API Message formats. It is able to wake the decoder if the sleep option is enabled. The TX state machine checks the timeout status of messages and handshaking events. Hooks to the Recovery State permit Host API Messages and handshaking to be retried as defined in the Simple Serial Interface protocol.

## StiSsiRx

### Description

Monitors the received message queue for commands and timing out ACK/NAK/PARAM\_SEND commands from the previous message transmission.

### Syntax

*int far* StiSsiRx( *void* )

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

## StiSsiRxOpcode

### Description

Gets messages from the UART receive queue and interprets the opcode field. When an entire message is received, it calls the appropriate message handling routine to verify the contents of the message and perform any actions that are required. If no Opcode matches the message contents, a NAK is sent to the decoder.

### Syntax

```
int far StiSsiRxOpcode( void )
```

### Return Values

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR



## StiSsiSendAck

### Description

Causes an ACK to be transmitted during the next available transmission slot.

### Syntax

```
int far StiSsiSendAck( void )
```

### Return Values

STATUS\_OK

## StiSsiSendNak

### Description

Causes a NAK to be transmitted during the next available transmission slot.

### Syntax

*int far* StiSsiSendNak( *int problem* )

where:

*problem* is the cause of the NAK message. Valid values for *problem* are:

- INVALID\_CHECKSUM
- BAD\_FORMAT
- UNEXPECTED\_FORMAT
- OUT\_OF\_CONTEXT\_MESSAGE
- COMMUNICATION\_TIMEOUT
- PROTOCOL\_VIOLATION

### Return Values

- STATUS\_OK

## StiSsiTx

### Description

Wakes the decoder (if required), queuing ACK, NAK, or Host API Messages to the decoder, and checking the timeout state of transmissions.

### Syntax

```
int far StiSsiTx( void )
```

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

## StiSsiTxAck

### Description

Generates an ACK message to be sent to the decoder when a **send\_ack** is requested by the receive state processing. ACK is generated before any pending Host API Messages can be queued. When an ACK is required, it passes the message of to the **StiSsiWakeUp()** function for further processing.

### Syntax

```
int far StiSsiTxAck( void )
```

### Return Values

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiSsiTxMessage

### Description

“Kick starts” the transmit interrupt service routine and sends the contents of the transmit queue to the decoder.

### Syntax

```
int far StiSsiTxMessage( void )
```

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

## StiSsiTxMessageQueued

### Description

Determines if a Host API Message should to be queued to the decoder. When a message is available, it passes the message to the **StiSsiWakeUp()** function for further processing. Only one Host API Message can be queued up at a time.

### Syntax

*int far* StiSsiTxMessageQueued( *void* )

### Return Values

MSG\_PENDING

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

## StiSsiTxNak

### Description

Generates a NAK message to be sent to the decoder whenever a **send\_nak** is requested by the receive state processing. NAK is generated before any pending Host API Messages can be queued. When a NAK is required, it passes the message of to the **StiSsiWakeUp()** function for further processing.

### Syntax

```
int far StiSsiTxNak( void )
```

### Return Values

STATUS\_OK  
COMMUNICATIONS\_ERROR

## StiSsiTxTimeOut

### Description

Counts down the transmit timeout event once per Kernel loop. If the timeout expires before the transmit queue is empty, this function initiates the recovery operation to retry the message in accordance with the Simple Serial Interface protocol. This function halts serial transmissions and flushes the transmit queue in the event of a timeout. If the queue transmits the entire packeted message within the allotted time, the **wait4ack** flag is set to alert the receive processing to expect either an ACK, a NAK, or a Param Send Command (if the message was a Param Request). Unpacketed messages and ACK/NAK commands do not set the **wait4ack** flag.

### Syntax

*int far* StiSsiTxTimeOut( *void* )

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR



## StiSsiWait4Ack

### Description

Determines if a Host API Message is acknowledged by the decoder within the specified timeout period. If the timeout expires without an acknowledge, the Kernel performs a retry operation in accordance with the Simple Serial Interface protocol.

### Syntax

*int far* StiSsiWait4Ack( *void* )

### Return Values

STATUS\_OK  
COMMUNICATIONS\_ERROR  
NOT\_SUPPORTED

## StiSsiWakeUp

### Description

Wakes the decoder if the low power mode is used or if the decoder was told to Sleep. If required, it generates a wake up command sequence in accordance with the Simple Serial Interface protocol before any messages are sent out.

### Syntax

```
int far StiSsiWakeUp( void)
```

### Return Values

STATUS\_OK

COMMUNICATIONS\_ERROR

## StiSsiWakeUpMethod

### Description

Determines which method of waking up the decoder is used. The default method is SLOW. When the Kernel needs to wake up the decoder, this setting determines how the wakeup is performed.

- If the SLOW\_WAKEUP method is used, the Kernel asserts RTS, transmits a NULL character, waits at least 10 milliseconds, then waits for the CTS signal before transmitting messages to the decoder.
- If the FAST\_WAKEUP method is used, the Kernel asserts RTS, then waits for the CTS signal before transmitting messages to the decoder.

### Syntax

*int far* StiSsiWakeUpMethod( *int type* )

where:

*type* specifies one of the following conditions:

SLOW\_WAKEUP

FAST\_WAKEUP

### Return Values

STATUS\_OK

BAD\_PARAM

---

## Decoder Setup

The functions in this section are used to set up and initialize the decoder. They are made Kernel functions to hide their operation from the user. They are not called when servicing the Kernel interrupt.

## StiDeclnitDecoder

### Description

This single call initializes the decoder and all of the software structures for the SSI-SDK interface. The initialization consists of:

1. Initialize all memory structures, queues, and pointers.
2. Establish a serial communications connection with the decoder using the user specified port and communication settings.
3. Initialize all interrupt processing related to the serial interface.
4. Enable ACK/NAK handshaking on the decoder.
5. Enable packeted decode data responses.
6. Query the decoder for all of its current programmable settings and allowable configuration parameters.

If any errors are detected, the serial communications are restored to its original form.

### Syntax

DOS Only:

```
int far StiDeclnitDecoder( COMM_STRUCT comm )
```

Windows Only:

```
int far StiDeclnitDecoder( struct COMM_STRUCT comm, HINSTANCE hInstance )
```

where:

*comm* is a structure containing the information about the communications link, such as: Port, Baud Rate, Parity and Stop Bits.

*hInstance* is a 16-bit handle to an instance of a module or application (Windows Only).

### Return Values

STATUS\_OK  
NOT\_SUPPORTED  
COMMUNICATIONS\_ERROR  
BAD\_PARAM

## StiDecRestoreDecoder

### Description

This single call restores the comm port and all of the software structures for the the SSI-SDK interface

### Syntax

*int far* StiDecRestoreDecoder( *COMM\_STRUCT comm* )

where:

*comm* is a structure containing the information about the communications link, such as: Port, Baud Rate, Parity and Stop Bits.

### Return Values

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

BAD\_PARAM

## StiSsiEstablishComm

### Description

Establishes a serial communications connection with the decoder using the user-specified port and communication settings. If a connection cannot be established, an error condition is reported.

This function enables ACK/NAK software handshaking with the decoder on the current serial port settings. To show the user Symbol's recommended approach to serial communications, ACK/NAK handshaking is always enabled.

### Syntax

```
int far StiSsiEstablishComm( COMM_STRUCT comm )
```

where:

*comm* is a structure containing the information about the communications link, such as Port, Baud Rate, Parity and Stop Bits.

### Return Values

- STATUS\_OK
- BAD\_PARAM
- ERROR\_UNDEFINED

## StiSsilInitStructs

### Description

Initializes structures, buffers and pointers.

### Syntax

*int far* StiSsilInitStructs( *void* )

### Return Values

STATUS\_OK

BAD\_PARAM

ERROR\_UNDEFINED



## StiSsiPacketedDecodeDataFormat

### Description

Forces decoded data to be transmitted with the packet format as defined by the serial protocol.

### Syntax

*int far* StiSsiPacketedDecodeDataFormat( *void* )

### Return Values

STATUS\_OK

NOT\_SUPPORTED

COMMUNICATIONS\_ERROR

---

## Additional Functions

The following functions are added by Wipro Ltd.,

### ***StiSsilInterruptProcess***

#### **Description**

Performs the Kernel State processing. It is responsible for directing transmit and receive processing. Additionally, it performs communications checking for unexpected formats, out of context messages, and protocol violations.

#### **Syntax**

*void* StiSsilInterruptProcess(*void*)

## StiSsiReset

### Description

Resets all the communication-related queues and the structure fields, variables.

### Syntax

```
int StiSsiReset(void)
```

### Return Values

STATUS\_OK

COMMUNICATION\_ERROR

## StiSsiVersion

### Description

Returns the version of the SSI-SDK. It returns a 16 bit value, where the higher byte is major version and the lower byte is minor version

### Syntax

*unsigned short* StiSsiVersion(*void*)

### Return Values

Higher byte - major version number

Higher byte - minor version number

# Chapter 6 OS API

---

## Introduction

The SSI-SDK Operating System-specific functions (denoted by the **StiOS\_** prefix) are implemented for the target operating system, and the platform-independent SSI Kernel code. The OS APIs provide the OS-specific services for the external functions. The API provides the following functionalities:

- Enable/disable of interrupts
- Memory Copy and Memory Set functions
- Initialization and restoration of the timer interrupt service routines.

---

## Return Value Definitions

The standard returned status codes are as follows:

- **STATUS\_OK**: the function parameters were verified or the function completed processing successfully.
- **MSG\_PENDING**: a message is pending (Windows).
- **NOT\_USED**: there is no functionality for this OS platform.
- **ERROR\_UNDEFINED**: an error condition not specifically associated with the decoder or its communications.

There are values such as the destination pointer address, other implementation specific APIs return values which are also returned.

## **StiOSDisableInterrupt**

### **Description**

Disables the hardware interrupts.

### **Syntax**

*void* StiOSDisableInterrupt(*void*)

## StiOSEnableInterrupt

### Description

Enables the hardware interrupts.

### Syntax

```
void StiOSEnableInterrupt(void)
```

## StiOSInitInterrupts

### Description

Hooks the callback or timer interrupt function used for asynchronous event indication. If the interrupt was already hooked, it returns an error value. **StiOSRestoreInterrupt** is the complementary function. Every call of this function must be accompanied by its complementary function before return from the application, or the same function is called again.

### Syntax

```
int StiOSInitInterrupts(volatile int* pWaitTimer, void (*fp_InterruptProcess)(void)
```

Where:

*PWaitTimer* is the volatile pointer to the timeout variable. The pointed value is decremented for every timer tick interrupt inside the interrupt service routine.

*fp\_InterruptProcess* is the function pointer of return type void. This function is called for every timer tick interrupt.

### Returned Status

STATUS\_OK - if the timer interrupt gets hooked

NOT\_SUPPORTED - if the timer interrupt fails to get hooked or if the interrupt is already hooked before calling this function.



## StiOSMemoryCopy

### Description

Copies the contents of source memory block to destination memory block.

### Syntax

```
void* StiOSMemoryCopy(void *dest, const void *src, int count)
```

Where:

*dest* is a pointer to the destination buffer

*src* is a constant pointer of the source buffer

*count* gives the number of bytes to be copied

### Returned Status

Destination address

## StiOSMemorySet

### Description

Fills the buffer with the given character value.

### Syntax

```
void* StiOSMemorySet(void *dest, int val, int count)
```

Where:

*dest* is a pointer to the destination buffer

*val* is the value to be set or filled

*count* gives the number of byte locations to be filled

### Returned Status

Destination address

## StiOSNotifyError

### Description

Displays the error message to the user. Used only in windows version.

### Syntax

```
void StiOSNotifyError(char *message, char* title)
```

Where:

*message* & *title* are the character string pointers that are displayed

## StiOSRestoreInterrupt

### Description

Unhooks the callback or timer interrupt function if already hooked. After planting the timer callback using **StiOSInitInterrupts**, call this function before the application quits.

### Syntax

```
int StiOSRestoreInterrupt(void)
```

### Returned Status

STATUS\_OK - successfully unhooked the interrupt if already hooked

NOT\_SUPPORTED - unsuccessful attempt to unhook the timer interrupt

## StiOSWait

### Description

Yields control to the OS while the application waits for a response from the decoder. This is currently used only in the Windows version, where it looks for the message and receives it if a message is pending.

### Syntax

```
int StiOSWait(void)
```

### Returned Status

STATUS\_OK - if there is no message

NOT\_USED - returned by DOS version

MSG\_PENDING - if the message pending is "quit application"



# Chapter 7 Port API

---

## Introduction

The SSI-SDK Port API (functions denoted by the **StiPort\_** prefix) is hardware-specific software implemented for the target operating system and the platform-independent SSI Kernel code. The Port APIs provide the platform-independent interface for the external functions. The API performs following:

- Initialization of the port and set up of the transmit and receive buffers.
- Character I/O over the port, and block data I/O using the data buffers.
- Communication control and all other port control functionality.

✓ **NOTE** This API provides a wrapper to the port-specific. OS-specific or vendor-specific code can be called inside this interface. The return data that follows is specific only to this wrapper interface; refer to the specific implementation documentation for other implementation-specific return values.

---

## Return Value Definitions

The standard returned status codes are as follows:

- STATUS\_OK: the function parameters were verified or the function completed processing successfully.
- BAD\_PARAM: the user-supplied parameter(s) in the function call was not in the expected range.
- STI\_PORT\_ERROR: an error condition for all the negative values???
- DECODER\_OK: the external device is ready for communication.
- DECODER\_BUSY - if the external device is not ready for communication.



## StiPortAllowDecoderTransmit

### Description

Clears the RTS line and allows the host transmission.

### Syntax

```
int StiPortAllowDecoderTransmit(int port)
```

Where:

*port* indicates the port number such as 1, 2.

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortClearReceiveBuf

### Description

Resets the receive data buffer. This function deletes any characters in the receive buffer for the specified port. After execution, the receive buffer is empty.

### Syntax

```
int StiPortClearReceiveBuf(int port)
```

Where:

*port* indicates the port number such as 1, 2 etc.,

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortClearTransmitBuf

### Description

Resets the transmit data buffer to all zeroes. This function deletes any characters in the transmit buffer for the specified port. After execution, the transmit buffer is empty.

### Syntax

```
int StiPortClearTransmitBuf(int port)
```

Where:

*port* indicates the port number such as 1, 2 etc.,

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortCommunicationDone

### Description

Completes the ongoing serial processing. Inside this function it de-references the transmit and receive buffers already set up.

### Syntax

```
int StiPortCommunicationDone(int port)
```

Where:

*port* indicates the port number such as 1, 2.

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortGetChar

### Description

Gets a character byte from the port if the character is available within the programmed amount of time; otherwise it returns an error message.

### Syntax

```
int StiPortGetChar(int port, int pics)
```

Where:

*port* indicates the port number such as 1, 2 etc.,

*tics* indicates the timeout in terms of number of timer ticks for the function to return the data or error

### Returned Status

STI\_PORT\_ERROR- for all error conditions.

If no error it returns the data read from the port.

## StiPortGetDecoderStatus

### Description

Gets the status of the clear-to-send control line. The CTS line is used by some error correcting modems to implement hardware flow control. The modem drops CTS to signal the computer not to send data, and raises CTS to signal the computer to continue.

### Syntax

```
int StiPortGetDecoderStatus(int port)
```

Where:

*port* indicates the port number such as 1, 2.

### Returned Status

STI\_PORT\_ERROR - for error conditions

DECODER\_OK - if the external device is ready for communication

DECODER\_BUSY - if the external device is not ready for communication

## StiPortGetLineStatus

### Description

Returns the line status register contents of the serial port

### Syntax

```
int StiPortGetLineStatus(int port)
```

Where:

*port* indicates the port number such as 1, 2.

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortGetReceiveQueueLength

### Description

Returns the receive buffer queue length

### Syntax

```
int StiPortGetReceiveQueueLength(int port)
```

Where:

*port* indicates the port number such as 1, 2 etc.,

### Returned Status

STI\_PORT\_ERROR - for all error conditions.



## StiPortGetTransmitQueueLength

### Description

Returns the transmit buffer queue length.

### Syntax

```
int StiPortGetTransmitQueueLength(int port)
```

Where:

*port* indicates the port number such as 1, 2 etc.,

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortIndicateHostReception

### Description

Sets the Request to Send control line of the serial port and indicates the host reception.

### Syntax

```
int StiPortIndicateHostReception(int port)
```

Where:

*port* indicates the port number such as 1, 2.

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortIndicateHostTransmission

### Description

Clears the RTS line and indicates the host transmission.

### Syntax

```
int StiPortIndicateHostTransmission(int port)
```

Where:

*port* indicates the port number such as 1, 2.

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortInitPort

### Description

Sets up and initializes the Transmit and Receive buffers.

### Syntax

```
int StiPortInitPort(int port)
```

Where:

*port* indicates the port number such as 1, 2.

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortPreventDecoderTransmit

### Description

Sets the RTS line and prevents host transmission.

### Syntax

```
int StiPortPreventDecoderTransmit(int port)
```

Where:

*port* indicates the port number such as 1, 2.

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortPutChar

### Description

Sends a character byte to the port which is transmitted.

### Syntax

```
int StiPortPutChar(int port, unsigned char dataByte)
```

Where:

*port* indicates the port number such as 1, 2 etc.,

*dataByte* is the byte of data to be transmitted

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

## StiPortResetBuffers

### Description

Sets the transmit and receive buffers with the null value in the DOS version. The Windows version returns void.

### Syntax

```
void StiPortResetBuffers(void)
```

## StiPortSetBaudRate

### Description

Sets the serial port's baud rate.

### Syntax

```
int StiPortSetBaudRate(int port, int BaudRate)
```

Where:

*port* indicates the port number such as 1, 2.

### Returned Status

STI\_PORT\_ERROR - for all error conditions.



## StiPortSetCommStruct

### Description

Copies the data (port parameters) from the source structure to the destination structure.

### Syntax

```
int StiPortSetCommStruct(struct COMM_STRUCT source, struct COMM_STRUCT* destination)
```

Where:

*source* is the source communication structure

*destination* is the pointer to the destination communication structure

### Returned Status

BAD\_PARAM- if the input value is out of range or invalid

STATUS\_OK- if the function completes processing successfully

## StiPortSetParams

### Description

Sets up the serial port parameters (parity, stopbits, data length).

### Syntax

```
int StiPortSetParams(int port, int parity, int stopBit, int dataBit)
```

Where:

*port* indicates the port number such as 1, 2

*parity* indicates the parity (value is implementation-specific; should be #defined)

*stopBit* indicates the stop bit (value is implementation-specific; should be #defined)

*dataBit* indicates the data size (value is implementation-specific; should be #defined)

### Returned Status

STI\_PORT\_ERROR - for all error conditions.

# Appendix A SSI Commands

This chapter describes each available SSI command, including field descriptions and host and decoder requirements.

## SSI Command Lists

The following table lists the available SSI commands alphabetically.

**Table A-1. SSI Commands**

Name	Type	Opcode	Description	Page
<b>ABORT_MACRO_PDF</b>	H	0x11	Terminates MacroPDF sequence and discards segments.	<a href="#">A-4</a>
<b>AIM_OFF</b>	H	0xC4	Deactivates aim pattern.	<a href="#">A-5</a>
<b>AIM_ON</b>	H	0xC5	Activates aim pattern.	<a href="#">A-6</a>
<b>BATCH_DATA</b>	D	0xD6	Transmits stored decode data.	<a href="#">A-8</a>
<b>BATCH_REQUEST</b>	H	0xD5	Requests stored decode data.	<a href="#">A-10</a>
<b>BEEP</b>	H	0xE6	Sounds the beeper.	<a href="#">A-11</a>
<b>CAPABILITIES_REPLY</b>	D	0xD4	Lists commands which decoder will perform.	<a href="#">A-13</a>
<b>CAPABILITIES_REQUEST</b>	H	0xD3	Requests commands which decoder will perform.	<a href="#">A-15</a>
<b>CMD_ACK</b>	H/D	0xD0	Positive acknowledgment of received packet.	<a href="#">A-16</a>
<b>CMD_NAK</b>	H/D	0xD1	Negative acknowledgment of received packet.	<a href="#">A-18</a>
<b>DECODE_DATA</b>	D	0xF3	Decode data in SSI packet format.	<a href="#">A-20</a>
<b>EVENT</b>	D	0xF6	Event indicated by associated event code.	<a href="#">A-30</a>
<b>FLUSH_MACRO_PDF</b>	H	0x10	Terminates MacroPDF sequence and transmits captured segments.	<a href="#">A-32</a>

Note: D = Decoder, H = Host, H/D = Host/Decoder

**Table A-1. SSI Commands (Continued)**

Name	Type	Opcode	Description	Page
FLUSH_QUEUE	H	0xD2	Tells the decoder to eliminate all packets in its transmission queue.	<a href="#">A-33</a>
IMAGE_DATA	D	0xB1	Data comprising the image.	<a href="#">A-34</a>
IMAGER_MODE	H	0xF7	Commands imager into operational modes.	<a href="#">A-36</a>
LED_OFF	H	0xE8	Extinguishes LEDs.	<a href="#">A-37</a>
LED_ON	H	0xE7	Activates LED output.	<a href="#">A-38</a>
PARAM_DEFAULTS	H	0xC8	Sets parameter default values.	<a href="#">A-39</a>
PARAM_REQUEST	H	0xC7	Requests values of certain parameters.	<a href="#">A-40</a>
PARAM_SEND	H/D	0xC6	Sends parameter values.	<a href="#">A-43</a>
REPLY_REVISION	D	0xA4	Replies to REQ_REV with decoder's software/hardware configuration.	<a href="#">A-45</a>
REQUEST_REVISION	H	0xA3	Requests the decoder's configuration.	<a href="#">A-47</a>
SCAN_DISABLE	H	0xEA	Prevents the operator from scanning bar codes.	<a href="#">A-48</a>
SCAN_ENABLE	H	0xE9	Permits bar code scanning.	<a href="#">A-49</a>
SLEEP	H	0xEB	Requests to place the decoder into low power.	<a href="#">A-50</a>
START_SESSION	H	0xE4	Tells decoder to attempt to decode a bar code.	<a href="#">A-51</a>
STOP_SESSION	H	0xE5	Tells decoder to abort a decode attempt.	<a href="#">A-52</a>
VIDEO_DATA	D	0xB4	Data comprising the video.	<a href="#">A-53</a>
WAKEUP	H	N/A	Wakes up decoder after it's been powered down.	<a href="#">A-55</a>

Note: D = Decoder, H = Host, H/D = Host/Decoder

<Blue>Table A-2 lists the SSI commands by Opcode.

**Table A-2. SSI Commands by Opcode**

Opcode	Name
0x10	FLUSH_MACRO_PDF
0x11	ABORT_MACRO_PDF
0xA3	REQUEST_REVISION
0xA4	REPLY_REVISION
0xB0	Reserved
0xB1	IMAGE_DATA
0xB4	VIDEO_DATA

Table A-2. SSI Commands by Opcode (Continued)

Opcode	Name
0xC4	AIM_OFF
0xC5	AIM_ON
0xC6	PARAM_SEND
0xC7	PARAM_REQUEST
0xC8	PARAM_DEFAULTS
0xD0	CMD_ACK
0xD1	CMD_NAK
0xD2	FLUSH_QUEUE
0xD3	CAPABILITIES_REQUEST
0xD4	CAPABILITIES_REPLY
0xE4	START_SESSION
0xE5	STOP_SESSION
0xE6	BEEP
0xE7	LED_ON
0xE8	LED_OFF
0xE9	SCAN_ENABLE
0xEA	SCAN_DISABLE
0xEB	SLEEP
0xF3	DECODE_DATA
0xF6	EVENT
0xF7	IMAGER_MODE
N/A	WAKEUP

**ABORT\_MACRO\_PDF****Description**

Terminates MacroPDF sequence and discards all captured segments.

**Packet Format**

Length	Opcode	Message Source	Status	Checksum
04h	11h	04h		

**Field Descriptions**

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	11h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type (for parameters)</b> 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

**Host Requirements**

None.

**Decoder Requirements**

The decoder terminates the current MacroPDF sequence and discards all captured MacroPDF segments.

## AIM\_OFF

### Description

Turns off aiming pattern.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	C4h	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	C4h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type (for parameters)</b> 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

This command applies only to decoders that support an aim pattern.

### Decoder Requirements

The decoder turns off the aim pattern, and responds with a CMD\_ACK (if ACK/NAK handshaking is enabled).

If the aim pattern is not supported, the decoder responds with NAK\_DENIED (if ACK/NAK handshaking is enabled).

## AIM\_ON

### Description

Turns on aiming pattern.

### Packet Format

Length	Opcod	Message Source	Status	Checksum
04h	C5h	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcod</b>	C5h	1 Byte	Identifies this Opcod type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type (for parameters)</b> 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

This command applies only to decoders which support an aim pattern.



## Decoder Requirements

The decoder turns on the aim pattern, and responds with a CMD\_ACK (if ACK/NAK handshaking is enabled).

If the aim pattern is not supported, the decoder responds with NAK\_DENIED (if ACK/NAK handshaking is enabled).

The Aim Duration parameter controls the amount of time the aiming pattern stays on during a trigger pull. The valid values for this parameter are 0 - 99, which equal 0.1 to 9.9 seconds in 100 msec increments. <Blue>Table A-3 lists Aim mode behavior in various situations.

**Table A-3. Aim Mode**

Command Sequence	Action performed	Aim duration parameters
<b>AIM_ON</b>	Turns on the aiming pattern indefinitely.	aim duration = 0
<b>AIM_OFF</b>	Turns off the aiming pattern.	aim duration = 0
<b>AIM_ON, START_DECODE</b>	Turns on the aiming pattern, when START_DECODE received turns on scan pattern and begins decoding.	aim duration = 0
<b>AIM_ON, AIM_OFF, START_DECODE</b>	Turns on aiming pattern, turns off aiming pattern, turns on scan pattern and begins decoding.	aim duration = 0
<b>START_DECODE</b>	Turns on aiming pattern for aim duration time, turns on scan pattern and begins decoding.	aim duration > 0

## BATCH\_DATA

### Description

Transmits stored decode data as a reply to the BATCH\_REQUEST command. Scanners that can not store scans send a NAK DENIED or NAK BAD CONTEXT response.

### Packet Format

Length	Opcode	Message Source	Status	Bar Code String(s)	Checksum
	D6h	00h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	D6h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	0 = Decoder	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Bar Code String(s)</b>	See Text	Variable	Data from a bar code scan in the bar code string format. Multiple instances of this field may be repeated in one message. For multipacket messages, a partial string may be sent, continued in the next packet.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

## Bar Code String

Each string is stored in this message in three components: Size, Type, and Scan Data. To specify a bar code string these components are combined in the order specified.

- Size: One byte value that contains the length of the Scan Data component
- Type: One byte value that indicates the bar code type of the data scanned:
  - A = UPC/EAN
  - B = Code 39
  - D = EAN 128
  - F = Interleaved 2 of 5
  - G = Discrete 2 of 5
  - K = Code 128
  - N = Coupon code
  - W = Web Code
- Scan Data: One or more bytes of the scanner bar code data in ASCII.

## BATCH\_REQUEST

### Description

Requests stored decode data from the scanner. The scanner responds with the BATCH\_REQUEST command. Scanners that can not store scans respond with a NAK DENIED or NAK BAD CONTEXT.

### Packet Format

Length	Opcode	Message Source	Status	Bar Code String(s)	Checksum
	D5h	04h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	D5h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

## BEEP

### Description

Sounds the beeper.

### Packet Format

Length	Opcode	Message Source	Status	Beep Code	Checksum
05h	E6h	04h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	E6h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type (for parameters)</b> 0 = Temporary change 1 = Permanent change
<b>Beep Code</b>	See <Blue>Table A-4.	1 Byte	Number that identifies a beep sequence.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This Opcode instructs the receiver to sound the beep sequence indicated by the Beep Code field.

For <Blue>Table A-4, Duration is the length of a sound, Pitch is the pitch of the sound, and Number of Beeps indicates the number of times a beep pitch is repeated at the specified duration.

**Table A-4. Beep Code Definitions**

Beep Code	Duration	Pitch	Number of Beeps	Beep Code	Duration	Pitch	Number of Beeps
00h	Short	High	1	0Dh	Long	High	4
01h	Short	High	2	0Eh	Long	High	5
02h	Short	High	3	0Fh	Long	Low	1

Table A-4. Beep Code Definitions (Continued)

Beep Code	Duration	Pitch	Number of Beeps	Beep Code	Duration	Pitch	Number of Beeps
03h	Short	High	4	10h	Long	Low	2
04h	Short	High	5	11h	Long	Low	3
05h	Short	Low	1	12h	Long	Low	4
06h	Short	Low	2	13h	Long	Low	5
07h	Short	Low	3	14h	Fast Warble	Hi-Lo-Hi-Lo	4
08h	Short	Low	4	15h	Slow Warble	Hi-Lo-Hi-Lo	4
09h	Short	Low	5	16h	Mix 1	Hi-Lo	2
0Ah	Long	High	1	17h	Mix 2	Lo-Hi	2
0Bh	Long	High	2	18h	Mix 3	Hi-Lo-Hi	3
0Ch	Long	High	3	19h	Mix 4	Lo-Hi-Lo	3

### Host Requirements

The host sends this command to cause the decoder to beep. The host may also send these beep codes as part of the PARAM\_SEND directive.

### Decoder Requirements

When the decoder receives this command, it beeps the sequence provided in the BEEP directive. If ACK/NAK handshaking is enabled, the decoder ACKs if a valid beep code is requested. Otherwise it sends CMD\_NAK, host directive denied.

## CAPABILITIES\_REPLY

### Description

Decoder details the serial capabilities.

### Packet Format

Length	Opcode	Message Source	Status	Data	Checksum
04h	D4h				

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	D4h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	0 = Decoder	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Data</b>			<Xref>Table A-5 on page A-14.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

The host must not CMD\_ACK or CMD\_NAK this message, as this is a natural response to the CAPABILITIES\_REQUEST message.

## Decoder Requirements

The decoder sends this message upon receipt of the CAPABILITIES\_REQUEST message.

**Table A-5. Data Fields**

Field	Size	Description		Supported
Baud Rates Supported	2 Bytes Bit mapped	<b>Bit</b>	<b>Definition</b>	1 = Supported 0 = Not Supported
		0	300 Baud	
		1	600 Baud	
		2	1200 Baud	
		3	2400 Baud	
		4	4800 Baud	
		5	9600 Baud	
		6	19200 Baud	
		7	28800 Baud	
		8	38400 Baud	
		9	57600 Baud	
		10	115200 Baud	
		11	Reserved	
		12	Reserved	
		13	Reserved	
		14	Reserved	
15	Reserved			
Misc Serial Parameters	1 Byte Bit Mapped	<b>Bit</b>	<b>Definition</b>	1 = Supported 0 = Not Supported
		0	Odd Parity	
		1	Even Parity	
		2	Parity None	
		3	Check Parity	
		4	Do Not Check Parity	
		5	One Stop Bit	
6	Two Stop Bits			
<b>Multi Packet Options</b>	1 Byte Bit Mapped	<b>Bit</b>	<b>Definition</b>	1 = Supported 0 = Not Supported
		0	Option 1	
		1	Option 2	
		2	Option 3	
<b>Command List</b>	1 Byte per Command	In this sequential list, the decoder details the commands it supports. For example, imagers support video commands, while laser-based decoders do not. Commands associated with video mode will not appear in the list for laser-based decoders, but will for imagers.		



## CAPABILITIES\_REQUEST

### Description

Requests the decoder's serial capabilities.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	D3h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	D3h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

The host transmits this message to request the serial capabilities of the decoder system.

### Decoder Requirements

Upon receipt of this command, the decoder responds with the CAPABILITIES\_REPLY message.

## CMD\_ACK

### Description

Positive acknowledgment of received packet.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	D0h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	D0h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	0 = Decoder 4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This message is sent to the SSI packet transmitter when the received packet passes the checksum check and no negative acknowledgment conditions apply (see CMD\_NAK). If the data is in response to a command (e.g., PARAM\_REQUEST, REQUEST\_REVISION, etc.), no ACK is sent.

- ✓ **NOTE** ACK/NAK handshaking can be disabled, although we recommend it remain enabled.
- ✓ **NOTE** DO NOT respond to a valid ACK or NAK message.

**Host Requirements**

A CMD\_ACK or response data must be sent by the decoder within the programmable Serial Response Time-out to acknowledge receipt of all messages, unless noted otherwise in the message description section. If the host sends data and does not receive a response within the programmable serial response time-out, it should resend the message (with the retransmit status bit set) before declaring a failure. The host should limit the number of retries.

**Decoder Requirements**

A CMD\_ACK or response data must be sent by the decoder within the programmable Serial Response Time-out to acknowledge receipt of all messages, unless noted otherwise in the message description section. If the decoder does not receive an ACK within this time period, it sends the previous message again (retry). The decoder retries two more times (with the retransmit status bit set) before declaring a transmit error.

**CMD\_NAK****Description**

Negative acknowledgment of received packet.

**Packet Format**

Length	Opcode	Message Source	Status	Cause	Checksum
05	D1h				

**Field Descriptions**

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	D1h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	0 = Decoder 4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Cause</b>	Reason code	1 Byte	Identifies the reason the NAK occurred: 0 = Reserved 1 = (RESEND) Checksum failure 2 = (BAD_CONTEXT) Unexpected or Unknown message 3 = Reserved 4 = Reserved 5 = Reserved 6 = (DENIED) Host Directive Denied 7 = Reserved 8 = Reserved 9 = Reserved 10 = (CANCEL) Undesired Message
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This message is sent when the received packet fails the checksum verification or some error occurred while handling the message.

- ✓ **NOTE** ACK/NAK handshaking can be disabled, although we recommend it remain enabled.
- ✓ **NOTE** DO NOT respond to a valid ACK or NAK message.

NAK types supported by the decoder are listed in <Blue>Table A-6.

**Table A-6. Decoder-Supported NAK Types**

NAK Type	Meaning	Receiver Action
<b>BAD_CONTEXT</b>	Host does not recognize the command.	
<b>CANCEL</b>	Host does not want the message in progress.	Decoder discards the current message.
<b>DENIED</b>	Host is unable to comply with the requested message (e.g., beep code is out of range).	Do not send data with this message again. Developer should check values with specified values. Developer should ensure the proper character is sent, if using wake-up character.
<b>RESEND</b>	Checksum incorrect.	Ensure checksum is correct. Limit number of resends. Send packet again with resend bit set.

The decoder only resends a message twice. If the message has not been sent successfully at that time, the decoder declares a transmit error, and issues transmit error beeps (LO-LO-LO-LO).

CMD\_NAK, cancel is a special message used when the decoder is sending a message the host does not want, for example a very large image message. The message is discarded by the decoder upon receipt of the CMD\_NAK, cancel. This only affects the first queued message. Subsequent messages are not touched. If the host wants the decoder to discard all messages, the host must send a FLUSH\_QUEUE message.

## DECODE\_DATA

### Description

Decode data in SSI packet format.

### Packet Format

Length	Opcode	Message Source	Status	Bar code Type	Decode Data	Checksum
	F3h	00h				

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	F3h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	0 = Decoder	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Bar Code Type</b>	See <Blue>Table A-7	1 Byte	Identifies the scanned data code type. 0 = Not Applicable
<b>Decode Data</b>	<data>	Variable	Data is decoded data including prefix and suffix sent in ASCII format.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This Opcode is used by the decoder when packeted data is selected to send decoded bar code data to the host. The decoded message is contained in the *Decode Data* field.

If the decoded data contains more structure than can be presented in the standard format, the Bar Code Type field is set to 0x99 to indicate the Decode Data message contains multiple packets. The format of the Decode

Data field contains the actual Bar Code Type and a packeted form of decode data. For example, a packeted Decode Data message for Micro PDF417 would look like:

Length	Opcode	Message Source	Status	Bar code Type	Decode Data	Checksum
12	F3h	00h	0	99	see below	

where the Decode Data field is broken out as follows:

Actual Bar code Type	# of Packets	Spare Byte	Byte Length of Packet #1	Data	Spare Byte	Byte Length of Packet #2	Data
1A	2	0	00 03	ABC	0	00 04	DEFG

Note that the *Packet Length* subfields consist of two bytes, where the first byte represents the high value of length x 256.

**Structured Append**

Structured append data for PDF417 and Micro PDF417 can be transmitted in either an unstructured format which adheres to the PDF417 specification, or a structured "smart format" using the multipacketed format above. The *Bar Code Type* field contains 0x99 and data is sent from a single structured append symbol in two Decode Data packets. The first packet contains the main bar code data, and the second contains any bar code identification enabled for transmission (e.g., the control block, optional fields, symbol terminator). Each field begins with its identifying marker codeword (e.g., \928 for control blocks, \923 for optional fields, and \922 for the symbol terminator).

<Blue>Table A-7 and <Blue>Table A-8 lists all supported code types, by code name and hex value (SSI ID). The associated hex value for each code (as required) is entered in the *Code Type* field.

✓ **NOTE** For multipacketed data, this code type appears in every packet.

**Table A-7. Code Types and Identifiers**

Symbology	SSI ID	Code ID	AIM ID Letter	AIM ID Modifier
Bookland	0x16	L	X	0
Codabar	0x02	C	F	0 (1) - standard (ABC)
Code 11	0x0C	H	H	0 (1) [2] - 1 (2) [0] check digits included
Code 128	0x03	D	C	0 (also see UCC/EAN-128)
Code 32	0x20	B	A	Same rules as for Code 39
<b>Notes:</b>				
1. <b>E+C</b> denotes 2 AIM IDs are transmitted: one for the UPC/EAN block; the second prefixes the extended EAN-128 data.				
2. <b>E+E</b> denotes 2 AIM IDs are transmitted: the first prefixes the main UPC/EAN block; the second prefixes the supplemental block.				
3. UPCE, UPCE1, and UPCA are converted to EAN-13 for AIM ID.				

Table A-7. Code Types and Identifiers (Continued)

Symbology	SSI ID	Code ID	AIM ID Letter	AIM ID Modifier
<b>Code 39</b>	0x01	B	A	0 - no check digit 1 (3) - check digit included (excluded)
<b>Code 39 Full ASCII</b>	0x13	B	A	4 - no check digit 5 (7) - check digit included (excluded)
<b>Code 93</b>	0x07	E	G	0
<b>Composite (CC-A + EAN-128)</b>	0x51	T		See <Blue>Table A-9
<b>Composite (CC-A + EAN-13)</b>	0x52	T		See <Blue>Table A-9
<b>Composite (CC-A + EAN-8)</b>	0x53	T		See <Blue>Table A-9
<b>Composite (CC-A + RSS Expanded)</b>	0x54	T		See <Blue>Table A-9
<b>Composite (CC-A + RSS Limited)</b>	0x55	T		See <Blue>Table A-9
<b>Composite (CC-A + RSS-14)</b>	0x56	T		See <Blue>Table A-9
<b>Composite (CC-A + UPC-A)</b>	0x57	T		See <Blue>Table A-9
<b>Composite (CC-A + UPC-E)</b>	0x58	T		See <Blue>Table A-9
<b>Composite (CC-B + EAN-128)</b>	0x61	T		See <Blue>Table A-9
<b>Composite (CC-B + EAN-13)</b>	0x62	T		See <Blue>Table A-9
<b>Composite (CC-B + EAN-8)</b>	0x63	T		See <Blue>Table A-9
<b>Composite (CC-B + RSS Expanded)</b>	0x64	T		See <Blue>Table A-9
<b>Composite (CC-B + RSS Limited)</b>	0x65	T		See <Blue>Table A-9
<b>Composite (CC-B + RSS-14)</b>	0x66	T		See <Blue>Table A-9
<b>Notes:</b>				
1. <b>E+C</b> denotes 2 AIM IDs are transmitted: one for the UPC/EAN block; the second prefixes the extended EAN-128 data.				
2. <b>E+E</b> denotes 2 AIM IDs are transmitted: the first prefixes the main UPC/EAN block; the second prefixes the supplemental block.				
3. UPCE, UPCE1, and UPCA are converted to EAN-13 for AIM ID.				



Table A-7. Code Types and Identifiers (Continued)

Symbology	SSI ID	Code ID	AIM ID Letter	AIM ID Modifier
Composite (CC-B + UPC-A)	0x67	T		See <Blue>Table A-9
Composite (CC-B + UPC-E)	0x68	T		See <Blue>Table A-9
Composite (CC-C + EAN-128)	0x59	T		See <Blue>Table A-9
Coupon Code	0x17	N	E+C <sup>1</sup>	0+1
Cue CAT Code	0x38	Q	X	0
D25	0x04	G	S	0
Data Matrix	0x1B	P00	d	4 (1) - ECC 200 with (w/o) ECI
EAN-128	0x0F	K	C	1 (2) - character 1 (2) is Function 1 (F1)
EAN-13	0x0B	A	E	0
EAN-13 + 2	0x4B	A	E + E <sup>2</sup>	0 for main block; 1 for supplemental
EAN-13 + 5	0x8B	A	E + E <sup>2</sup>	0 for main block; 2 for supplemental
EAN-8	0x0A	A	E	4
EAN-8 + 2	0x4A	A	E + E <sup>2</sup>	4 for main block; 1 for supplemental
EAN-8 + 5	0x8A	A	E + E <sup>2</sup>	4 for main block; 2 for supplemental
IATA	0x05	G	S	0
ISBT-128	0x19	D	C	0
ISBT-128 Concat.	0x21	D	C	4
ITF	0x06	F	I	Same rules as for Code 39
Macro Micro PDF	0x9A	X	L	Same rules as for Micro PDF-417
Macro PDF-417	0x28	X	L	Same rules as for PDF-417
Maxicode	0x25	P02	U	1 - Mode 0, 2 or 3, without ECI 3 (1) - Extended EC with (w/o) ECI
Micro PDF	0x1A	X	L	3 - Code 128 emul: implied F1 in 1st position 4 - Code 128 emul: F1 after 1st letter/digits 5 - Code 128 emul: no implied F1
<b>Notes:</b>				
1. E+C denotes 2 AIM IDs are transmitted: one for the UPC/EAN block; the second prefixes the extended EAN-128 data.				
2. E+E denotes 2 AIM IDs are transmitted: the first prefixes the main UPC/EAN block; the second prefixes the supplemental block.				
3. UPCE, UPCE1, and UPCA are converted to EAN-13 for AIM ID.				

Table A-7. Code Types and Identifiers (Continued)

Symbology	SSI ID	Code ID	AIM ID Letter	AIM ID Modifier
<b>MSI</b>	0x0E	J	M	0 - Modulo 10 symbol check character validated and transmitted 1 - Modulo 10 symbol check character validated but not transmitted
<b>Multipacket Format</b>	0x99	N/A	N/A	Data is packeted; SSI ID is embedded in decode data.
<b>Parameter (FNC3)</b>	0x33	N/A	N/A	
<b>PDF-417</b>	0x11	X	L	0 - Conforms with 1994 PDF-417 spec 1 - Backslash characters doubled 2 - Backslash characters not doubled
<b>Planet (US)</b>	0x1F	P04	X	
<b>Postal (Australia)</b>	0x23	P09	X	0
<b>Postal (Dutch)</b>	0x24	P08	X	0
<b>Postal (Japan)</b>	0x22	P05	X	0
<b>Postal (UK)</b>	0x27	P06	X	0
<b>Postbar (CA)</b>	0x26	P07	X	0
<b>Postnet (US)</b>	0x1E	P03	X	0
<b>QR Code</b>	0x1C	P01	Q	0
<b>RSS Expanded</b>	0x32	R		
<b>RSS Limited</b>	0x31	R		
<b>RSS-14</b>	0x30	R		
<b>Scanlet Webcode</b>	0x37	W	X	0
<b>TLC-39</b>	0x5A	T		See <Blue>Table A-9
<b>Trioptic</b>	0x15	M	X	0
<b>UPCA</b>	0x08	A	E	0
<b>UPCA + 2</b>	0x48	A	E + E <sup>2</sup>	0 for main block; 1 for supplemental
<b>UPCA + 5</b>	0x88	A	E + E <sup>2</sup>	0 for main block; 2 for supplemental
<b>UPCE<sup>3</sup></b>	0x09	A	E	0
<b>UPCE + 2</b>	0x49	A	E + E <sup>2</sup>	0 for main block; 1 for supplemental
<b>UPCE + 5</b>	0x89	A	E + E <sup>2</sup>	0 for main block; 2 for supplemental
<b>Notes:</b>				
1. <b>E+C</b> denotes 2 AIM IDs are transmitted: one for the UPC/EAN block; the second prefixes the extended EAN-128 data.				
2. <b>E+E</b> denotes 2 AIM IDs are transmitted: the first prefixes the main UPC/EAN block; the second prefixes the supplemental block.				
3. UPCE, UPCE1, and UPCA are converted to EAN-13 for AIM ID.				

Table A-7. Code Types and Identifiers (Continued)

Symbology	SSI ID	Code ID	AIM ID Letter	AIM ID Modifier
UPCE1	0x10	A	E	0
UPCE1 + 2	0x50	A	E + E <sup>2</sup>	0 for main block; 1 for supplemental
UPCE1 + 5	0x90	A	E + E <sup>2</sup>	0 for main block; 2 for supplemental
<b>Notes:</b>				
1. <b>E+C</b> denotes 2 AIM IDs are transmitted: one for the UPC/EAN block; the second prefixes the extended EAN-128 data.				
2. <b>E+E</b> denotes 2 AIM IDs are transmitted: the first prefixes the main UPC/EAN block; the second prefixes the supplemental block.				
3. UPCE, UPCE1, and UPCA are converted to EAN-13 for AIM ID.				

Table A-8. Code Types by SSI ID

Symbology	SSI ID	Code ID	AIM ID Letter	AIM ID Modifier
Code 39	0x01	B	A	0 - no check digit 1 (3) - check digit included (excluded)
Codabar	0x02	C	F	0 (1) - standard (ABC)
Code 128	0x03	D	C	0 (also see UCC/EAN-128)
D25	0x04	G	S	0
IATA	0x05	G	S	0
ITF	0x06	F	I	Same rules as for Code 39
Code 93	0x07	E	G	0
UPCA	0x08	A	E	0
UPCE <sup>3</sup>	0x09	A	E	0
EAN-8	0x0A	A	E	4
EAN-13	0x0B	A	E	0
Code 11	0x0C	H	H	0 (1) [2] - 1 (2) [0] check digits included
MSI	0x0E	J	M	0 - Modulo 10 symbol check character validated and transmitted 1 - Modulo 10 symbol check character validated but not transmitted
<b>Notes:</b>				
1. <b>E+C</b> denotes 2 AIM IDs are transmitted: one for the UPC/EAN block; the second prefixes the extended EAN-128 data.				
2. <b>E+E</b> denotes 2 AIM IDs are transmitted: the first prefixes the main UPC/EAN block; the second prefixes the supplemental block.				
3. UPCE, UPCE1, and UPCA are converted to EAN-13 for AIM ID.				

Table A-8. Code Types by SSI ID (Continued)

Symbology	SSI ID	Code ID	AIM ID Letter	AIM ID Modifier
<b>EAN-128</b>	0x0F	K	C	1 (2) - character 1 (2) is Function 1 (F1)
<b>UPCE1</b>	0x10	A	E	0
<b>PDF-417</b>	0x11	X	L	0 - Conforms with 1994 PDF-417 spec 1 - Backslash characters doubled 2 - Backslash characters not doubled
<b>Code 39 Full ASCII</b>	0x13	B	A	4 - no check digit 5 (7) - check digit included (excluded)
<b>Trioptic</b>	0x15	M	X	0
<b>Bookland</b>	0x16	L	X	0
<b>Coupon Code</b>	0x17	N	E+C <sup>1</sup>	0+1
<b>ISBT-128</b>	0x19	D	C	0
<b>Micro PDF</b>	0x1A	X	L	3 - Code 128 emul: implied F1 in 1st position 4 - Code 128 emul: F1 after 1st letter/digits 5 - Code 128 emul: no implied F1
<b>Data Matrix</b>	0x1B	P00	d	4 (1) - ECC 200 with (w/o) ECI
<b>QR Code</b>	0x1C	P01	Q	0
<b>Postnet (US)</b>	0x1E	P03	X	0
<b>Planet (US)</b>	0x1F	P04	X	
<b>Code 32</b>	0x20	B	A	Same rules as for Code 39
<b>ISBT-128 Concat.</b>	0x21	D	C	4
<b>Postal (Japan)</b>	0x22	P05	X	0
<b>Postal (Australia)</b>	0x23	P09	X	0
<b>Postal (Dutch)</b>	0x24	P08	X	0
<b>Maxicode</b>	0x25	P02	U	1 - Mode 0, 2 or 3, without ECI 3 (1) - Extended EC with (w/o) ECI
<b>Postbar (CA)</b>	0x26	P07	X	0
<b>Postal (UK)</b>	0x27	P06	X	0
<b>Macro PDF-417</b>	0x28	X	L	Same rules as for PDF-417
<b>RSS-14</b>	0x30	R		
<b>Notes:</b>				
1. <b>E+C</b> denotes 2 AIM IDs are transmitted: one for the UPC/EAN block; the second prefixes the extended EAN-128 data.				
2. <b>E+E</b> denotes 2 AIM IDs are transmitted: the first prefixes the main UPC/EAN block; the second prefixes the supplemental block.				
3. UPCE, UPCE1, and UPCA are converted to EAN-13 for AIM ID.				

Table A-8. Code Types by SSI ID (Continued)

Symbology	SSI ID	Code ID	AIM ID Letter	AIM ID Modifier
RSS Limited	0x31	R		
RSS Expanded	0x32	R		
Parameter (FNC3)	0x33	N/A	N/A	
Scanlet Webcode	0x37	W	X	0
Cue CAT Code	0x38	Q	X	0
UPCA + 2	0x48	A	E + E <sup>2</sup>	0 for main block; 1 for supplemental
UPCE + 2	0x49	A	E + E <sup>2</sup>	0 for main block; 1 for supplemental
EAN-8 + 2	0x4A	A	E + E <sup>2</sup>	4 for main block; 1 for supplemental
EAN-13 + 2	0x4B	A	E + E <sup>2</sup>	0 for main block; 1 for supplemental
UPCE1 + 2	0x50	A	E + E <sup>2</sup>	0 for main block; 1 for supplemental
Composite (CC-A + EAN-128)	0x51	T		See <Blue>Table A-9
Composite (CC-A + EAN-13)	0x52	T		See <Blue>Table A-9
Composite (CC-A + EAN-8)	0x53	T		See <Blue>Table A-9
Composite (CC-A + RSS Expanded)	0x54	T		See <Blue>Table A-9
Composite (CC-A + RSS Limited)	0x55	T		See <Blue>Table A-9
Composite (CC-A + RSS-14)	0x56	T		See <Blue>Table A-9
Composite (CC-A + UPC-A)	0x57	T		See <Blue>Table A-9
Composite (CC-A + UPC-E)	0x58	T		See <Blue>Table A-9
Composite (CC-C + EAN-128)	0x59	T		See <Blue>Table A-9
TLC-39	0x5A	T		See <Blue>Table A-9
Composite (CC-B + EAN-128)	0x61	T		See <Blue>Table A-9
Composite (CC-B + EAN-13)	0x62	T		See <Blue>Table A-9
<b>Notes:</b>				
1. <b>E+C</b> denotes 2 AIM IDs are transmitted: one for the UPC/EAN block; the second prefixes the extended EAN-128 data.				
2. <b>E+E</b> denotes 2 AIM IDs are transmitted: the first prefixes the main UPC/EAN block; the second prefixes the supplemental block.				
3. UPCE, UPCE1, and UPCA are converted to EAN-13 for AIM ID.				

Table A-8. Code Types by SSI ID (Continued)

Symbology	SSI ID	Code ID	AIM ID Letter	AIM ID Modifier
<b>Composite (CC-B + EAN-8)</b>	0x63	T		See <Blue>Table A-9
<b>Composite (CC-B + RSS Expanded)</b>	0x64	T		See <Blue>Table A-9
<b>Composite (CC-B + RSS Limited)</b>	0x65	T		See <Blue>Table A-9
<b>Composite (CC-B + RSS-14)</b>	0x66	T		See <Blue>Table A-9
<b>Composite (CC-B + UPC-A)</b>	0x67	T		See <Blue>Table A-9
<b>Composite (CC-B + UPC-E)</b>	0x68	T		See <Blue>Table A-9
<b>UPCA + 5</b>	0x88	A	E + E <sup>2</sup>	0 for main block; 2 for supplemental
<b>UPCE + 5</b>	0x89	A	E + E <sup>2</sup>	0 for main block; 2 for supplemental
<b>EAN-8 + 5</b>	0x8A	A	E + E <sup>2</sup>	4 for main block; 2 for supplemental
<b>EAN-13 + 5</b>	0x8B	A	E + E <sup>2</sup>	0 for main block; 2 for supplemental
<b>UPCE1 + 5</b>	0x90	A	E + E <sup>2</sup>	0 for main block; 2 for supplemental
<b>Multipacket Format</b>	0x99	N/A	N/A	Data is packeted; SSI ID is embedded in decode data.
<b>Macro Micro PDF</b>	0x9A	X	L	Same rules as for Micro PDF-417
<b>Notes:</b>				
1. <b>E+C</b> denotes 2 AIM IDs are transmitted: one for the UPC/EAN block; the second prefixes the extended EAN-128 data.				
2. <b>E+E</b> denotes 2 AIM IDs are transmitted: the first prefixes the main UPC/EAN block; the second prefixes the supplemental block.				
3. UPCE, UPCE1, and UPCA are converted to EAN-13 for AIM ID.				

Table A-9. Composite Code Data Formats

1D Component	Data Format	
	Standard Mode	EAN-128 Emulation Mode
<b>EAN-13, UPC-A, UPC-E</b>	1D: ]E0 2D: ]e0 See note 5	1D: ]E0 2D: ]C1 before each EAN-128 split transmission See notes 3 -5
<b>EAN-8</b>	1D: ]E4 2D: ]e0 See note 5	1D: ]E4 2D: ]C1 before each EAN-128 split transmission See notes 3 -5
<b>RSS-14 RSS Limited</b>	1D: ]e0 2D: ]e1 See note 2	]C1 before each EAN-128 split transmission See notes 3 -5
<b>Code 39 (TLC39)</b>	<i>ANSI MH10.8.3M syntax:</i> 06 Format: ]> <sup>R</sup> <sub>S</sub> 06 <sup>G</sup> <sub>S</sub> 6P 1D <sup>G</sup> <sub>S</sub> S 2D <sup>R</sup> <sub>S</sub> EOT 05 Format: ]> <sup>R</sup> <sub>S</sub> 05 <sup>G</sup> <sub>S</sub> 906P 1D <sup>G</sup> <sub>S</sub> 8004 2D <sup>R</sup> <sub>S</sub> EOT See note 6	
<b>EAN-128 RSS Expanded</b>	If the last AI in the EAN-128 is a predefined, fixed length: ]e0 Otherwise, ]e0 GS See note 2	]C1 before each EAN-128 split transmission See notes 3 and 4
<b>Notes:</b>		
<ol style="list-style-type: none"> <li>1. All Function 1 characters in the 1D and 2D are sent as <sup>G</sup><sub>S</sub> (29<sub>10</sub>); the first Function 1 in the EAN-128 is not transmitted.</li> <li>2. In standard mode, the data following symbol separator begins with AIM ID "]e1". The data following the composite component escape mechanism begins with AIM ID "]e2" if ECI interpretation is enabled, "]e3" if ECI interpretation is not enabled.</li> <li>3. In EAN-128 emulation mode, each packet is split on an AI boundary and limited to less than 48 characters.</li> <li>4. In EAN-128 emulation mode, data is discarded after the first symbol separator or escape mechanism.</li> <li>5. If the UPC/EAN component has a supplemental , ]E1 precedes a 2-digit supplemental and ]E2 precedes the 5-digit supplemental</li> <li>6. RS is character 30<sub>10</sub> and EOT is character 04. The transmitted format (05 or 06) is data dependent.</li> </ol>		

### Host Requirements

If DECODE\_EVENT reporting is enabled, the decode event message is received before the DECODE\_DATA message. If ACK/NAK handshaking is enabled, the host responds to each of these messages.

### Decoder Requirements

Decode data is sent in this format if packeted decode data is selected via parameter. The host responds to this message with a CMD\_ACK, if ACK/NAK handshaking is enabled.

## EVENT

### Description

Indicates selected events occurred.

### Packet Format

Length	Opcode	Message Source	Status	Event Code	Checksum
05h	F6h	00h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	F6h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	0 = Decoder	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Event Code</b>	Type of Event Code.	1 Byte	See <Xref>Table A-10 on page A-31.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This message is sent by the decoder when an enabled event occurs. Use <Blue>Table A-10 and parameters F0h 00h through F0h 07h to determine which events you would like to be reported.



**Host Requirements**

The host receives this message when a selected event occurs.

**Decoder Requirements**

Generate this message when a selected event occurs. Events may vary by decoder type.

**Table A-10. Event Codes**

<b>Event</b>	<b>Code</b>
<b>Boot Event</b>	03h
<b>Decode Event</b>	01h
<b>Parameter Defaults</b>	0Ah
<b>Parameter Entry Error</b>	07h
<b>Parameter Num Expected</b>	0Fh
<b>Parameter Stored</b>	08h

## FLUSH\_MACRO\_PDF

### Description

Terminates MacroPDF sequence and sends all captured segments.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	10h	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	10h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type (for parameters)</b> 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

None.

### Decoder Requirements

The decoder terminates the current MacroPDF sequence and transmits the captured MacroPDF segments.

## FLUSH\_QUEUE

### Description

Eliminates content of decoder's transmission queue.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	D2h	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	D2h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This message is sent by the host to instruct the decoder to discard or flush the transmission queue. This is useful when the decoder is attempting to send a lengthy multipacket message. If the host does not want the message, the host can interrupt the decoder (by asserting RTS) and send a FLUSH\_QUEUE message.

The decoder ACK/NAKs the FLUSH\_QUEUE message. No further packets in the transmission queue are sent. Note that this does not abort decoder actions that cause packets to be added to the transmission queue.

We recommend issuing a SCAN\_DISABLE prior to issuing a FLUSH\_QUEUE so that new elements are not added to the queue just after it is emptied. Also, paradoxical cases may arise if a SCAN\_DISABLE is not issued first.

## IMAGE\_DATA

### Description

A JPEG, BMP, or TIFF image.

### Packet Format

Length	Opcode	Message Source	Status	Data	Checksum
	B1h	01h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	B1h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	0 = Decoder	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Data Content</b>		Up to 251 Bytes	Image Data records.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This packet contains image information. Images sent from the decoder to the host are described by the image preamble contained in the first 10 bytes of the first packet of the image. The details of the image preamble follow. Due to the small packet size of SSI, multiple packets of image data should be received by the host and re-assembled in the order given by the decoder. The packets describe, for example, a JPEG image when re-assembled.

The image preamble consists of the following fields:

**Table A-11. Image Preamble Fields**

Field	Field Size	Description
<b>File size</b>	4 byte field	Number of bytes in the overall image.
<b>Image Width</b>	2 byte field	Image width in pixels
<b>Image Height</b>	2 byte field	Image height in pixels
<b>Image Type</b>	1 byte field	0x31 = JPEG Image File 0x33 = BMP Windows Bit Map File 0x34 = TIFF File Note: These values are ASCII.
<b>Bits per Pixel</b>	1 byte field	Number of bits per pixel in image 0 = 1 bit/pixel Black White Image 1 = 4 bit/pixel 16 Grayscale Image 2 = 8 bit/pixel 256 Grayscale Image
<b>Note: The preamble only appears in the first packet of a multipacket message.</b>		

In a multipacketed environment, one image frame is spread over several packets in the following format:

**Packet 1**

Header	Preamble	Image Data, Part 1	Checksum
--------	----------	--------------------	----------

**Packet 2**

Header	Image Data, Part 2	Checksum
--------	--------------------	----------

.  
.  
.

**Packet N**

Header	Last of Image Data	Checksum
--------	--------------------	----------

This is re-assembled by the host into:

Preamble	Image Frame
----------	-------------

## IMAGER\_MODE

### Description

Commands Imager into Operational Modes.

### Packet Format

Length	Opcode	Message Source	Status	Data	Checksum
05h	F7h	00h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	F7h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Data Content</b>		1 Byte	Value 0, 1, or 2 decimal
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

This command is supported by the imager only. The host sends this command with the data field set to 0 for decode mode, 1 for image capture mode, and 2 for video mode.

### Decoder Requirements

The decoder (imager) sends a CMD\_ACK if the mode is valid, and CMD\_NAK if not.

## LED\_OFF

### Description

De-activates LED output.

### Packet Format

Length	Opcode	Message Source	Status	LED Selection	Checksum
05h	E8h	04h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	E8h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>LED Selection</b>	Bit 0 - 7: LED bit numbers to turn off.	1 Byte	Bit 0 = Decode LED See your product's Product Reference Guide for further bit information.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

The host sends this message to turn off the specified decoder LEDs.

### Host Requirements

None.

### Decoder Requirements

The decode LED is turned off by the decoder.

## LED\_ON

### Description

Activates LED output.

### Packet Format

Length	Opcode	Message Source	Status	LED Selection	Checksum
05h	E7h	04h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	E7h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>LED Selection</b>	Bit 0 - 7: LED bit numbers to turn on.	1 Byte	Bit 0 = Decode LED See your product's Product Reference Guide for further bit information.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

The host sends this message to turn on the specified decoder LEDs.

### Host Requirements

None.

### Decoder Requirements

The decode LED is turned on by the decoder.



## PARAM\_DEFAULTS

### Description

Sets the parameters to their default values.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	C8h	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	C8h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This command returns all parameters to their default settings.

### Host Requirements

The host sends this command to reset the decoder's parameter settings to the default values.

### Decoder Requirements

Upon receiving this command, the decoder resets all its parameters to the default values. This is equivalent to scanning a SET DEFAULTS bar code.

## PARAM\_REQUEST

### Description

Requests values of selected parameters.

### Packet Format

Length	Opcode	Message Source	Status	Request Data	Checksum
	C7h	04h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	C7h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Request Data</b>	<Param_num><Param_num> <Param_num>...	Variable	
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

The host uses this message to request selected parameters from the decoder.

### Host Requirements

The host requests the decoder's current values for specific parameters by listing the parameter numbers in the Request\_Data field. If the host asks for a parameter value not supported by the decoder, the decoder does not send a value for this unsupported param\_num. If none of the requested values is supported, an empty PARAM\_SEND message is transmitted. If the host requests the value of all the parameters, it sends a special param\_num called ALL\_PARAMS (FEh) in the first position of the Request\_Data field.

✓ **NOTE** The decoder's response to this command is PARAM\_SEND, not ACK. Depending on the time-out set, and the number of parameters requested, this reply may fall outside the programmable Serial Response Timeout. It should not be considered an error if the time-out is exceeded. To compensate, increase the time-out.

### Decoder Requirements

When the decoder receives this message, it processes the information by formatting a PARAM\_SEND message containing all requested parameters that are supported, and their values. The programmable Serial Response Time-out may be exceeded when processing this message, depending on the time-out set, and the number of parameters requested.

### Hints for Requesting Parameter Values

Before forming a PARAM\_REQUEST, be sure you are requesting parameters supported by the decoder (<Blue>Table A-12). To find out what parameters are supported, send an FEh (request all parameters). The decoder responds with a PARAM\_SEND which contains all the supported parameters and their values. This response may be multipacketed; ACK responses are not necessary.

**Table A-12. Example of Supported Parameter Numbers**

Supported Parameter Number	Associated Parameter Values
01	00
02	01
9C	07
E6	63

When using the FEh, it must be in the first position of the request\_data field, or it is treated as an unsupported parameter.

Unsupported parameters are not listed in the PARAM\_SEND response. Requesting unsupported parameters has no effect, but can cause delays in responding to requests for valid parameters. See <Blue>Table A-13 for example requests and responses.

**Table A-13. Example Requests and Replies**

PARAM_REQUEST message		Response PARAM_SEND message
#ALL	05 C7 04 00 FE FE 32	0D C6 00 00 FF 01 00 02 01 9C 07 E6 63 FC 3E
#1, 9C	06 C7 04 00 01 9C FE 92	09 C6 00 00 FF 01 00 9C 07 FD 8E
#All, 1, 9C	07 C7 04 00 FE 01 9C FD 93	0D C6 00 00 FF 01 00 02 01 9C 07 E6 63 FC 3E
#1, 9C, ALL	07 C7 04 00 01 9C FE FD 93	09 C6 00 00 FF 01 00 9C 07 FD 8E

**Table A-13. Example Requests and Replies (Continued)**

<b>PARAM_REQUEST message</b>		<b>Response PARAM_SEND message</b>
<b>#4</b>	05 C7 04 00 04 FF 2C	05 C6 00 00 FF FE 36
<b>#ALL - 3 times</b>	07 C7 04 00 FE FE FE FC 34	0D C6 00 00 FF 01 00 02 01 9C 07 E6 63 FC 3E
<b>#1 -3 times</b>	07 C7 04 00 01 01 01 FF 2B	0B C6 00 00 FF 01 00 01 00 01 00 FE 2D

## PARAM\_SEND

### Description

Responds to a PARAM\_REQUEST, changes particular parameter values.

### Packet Format

Length	Opcode	Message Source	Status	Beep Code	Param data	Checksum
	C6h					

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	C6h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	0 = Decoder 4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Beep code</b>	See <Xref>Table A-4 on page A-11.	1 Byte	If no beep is required, set this field to FF.
<b>Param_data</b>	See <Xref>Table A-14 on page A-44.		The parameter numbers and data to be sent to the requester.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This message is sent by the decoder in response to the PARAM\_REQUEST message, or by the host to change the decoder's parameter values.

Parameter numbers F0h (+256), F1h (+512), F2h (+768) access parameters whose numbers are 256 and higher. For example, to access the first parameter in the 256-511 range, use F0h and 00h.

**Table A-14. Param Data Format**

Parameter Number	Data Format
0 through EFh	<param_num> <value>
F0h, F1h, F2h	<extended parameter code> <param_num offset> <value>

### Host Requirements

- ✓ **NOTE** Due to the processing time of interpreting and storing parameters contained in the message, it may not be possible for the decoder to send an ACK within the programmable Serial Response Timeout. It should not be considered an error if the time-out is exceeded. To compensate, increase the time-out.

The host transmits this message to change the decoder's parameters. Be sure the Change Type bit in the Status byte is set as desired. If no beep is required, the beep code must be set to FFh, or the decoder beeps as defined in <Blue>Table A-4.

### Decoder Requirements

When the decoder receives a PARAM\_SEND, it interprets and stores the parameters, then ACKs the command (if ACK/NAK handshaking is enabled). These parameters are stored permanently only if the Change Type (bit 3 of the Status byte) is set to 1. If bit 3 is set to 0 the changes are temporary, and are lost when the decoder is powered down.

If the PARAM\_SEND sent by the host contains a valid beep code, the decoder issues the requested beep sequence, and changes the requested parameter values.

The decoder issues a PARAM\_SEND in response to a PARAM\_REQUEST from the host. It sends the values for all the supported parameter values requested in the PARAM\_REQUEST message. No value is sent for any unsupported param\_num. If none of the requested values is supported, the PARAM\_SEND message is transmitted with no parameters. When sending this command, the Change Type bit (bit 3 of Status byte) can be ignored.

- ✓ **NOTE** For multipacketed PARAM\_SEND, the beep code appears in every packet.

## REPLY\_REVISION

### Description

Replies to REQUEST\_REVISION command with software revision string.

### Packet Format

Length	Opcode	Message Source	Status	Revision	Checksum
	A4h	00h		S/W_REVISION <space> BOARD_TYPE <space> ENGINE_CODE <space> PGM_CHKSUM	

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	A4h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	0 = Decoder	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Revision</b>	ASCII data	variable	Revision String fields indicate: <b>S/W_REVISION</b> is the release name of the software <b>BOARD_TYPE</b> is N for non-flash decoder board, F for flash <b>ENGINE_CODE</b> indicates the type of scan engine paired with the decoder (see the scan engine's Integration Guide for the engine code value) <b>PGM_CHKSUM</b> is the two byte checksum of the program code
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### **Host Requirements**

None.

### **Decoder Requirements**

The decoder sends its revision string to the host. The revision string is decoder-dependent.



## REQUEST\_REVISION

### Description

Requests the software revision string from the decoder.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	A3h	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	A3h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

The host sends this message to request revision information from the decoder. The decoder responds with `REPLY_REVISION`.

### Decoder Requirements

The decoder sends its revision string to the host. See "`REPLY_REVISION`," for format.

## SCAN\_DISABLE

### Description

Prevents the decoder from scanning bar codes.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	EAh	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	EAh	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

All scan attempts are disabled by this command until either a SCAN\_ENABLE is sent, or the decoder is reset.

### Decoder Requirements

When the decoder receives this command, it ignores all trigger/START\_SESSION requests until a SCAN\_ENABLE command is received.

## SCAN\_ENABLE

### Description

Permits the decoder to scan bar codes.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	E9h	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	E9h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

The host sends the SCAN\_ENABLE command to tell the decoder to allow scanning. Scanning is enabled upon power-up, so this command need only be send if a prior SCAN\_DISABLE command has been sent.

### Decoder Requirements

The decoder allows scanning and decoding upon receipt of this command.

✓ **NOTE** At initial power-up, the decoder should assume SCAN\_ENABLED.

## SLEEP

### Description

Requests to place the decoder into low power mode.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	EBh	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	EBh	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

### Host Requirements

The host sends this command to place the decoder into low power mode. If the low power mode parameter is enabled, the scanner goes into low power mode automatically, and the SLEEP command is not necessary.



**NOTE** The decoder may not sleep immediately upon acknowledging the command, as it may be busy processing data at the time.

### Decoder Requirements

None.

## START\_SESSION

### Description

Tells decoder to attempt to obtain the requested data.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	E4h	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	E4h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This command tells the decoder to start a scan session. See <Blue>Table A-15 for the decoder's reactions to this command in each operational mode.

**Table A-15. START\_SESSION Actions**

Operational Mode	Actions upon Receipt of Command	End Result of Session
<b>Decode Mode</b>	The decoder attempts to decode a bar code	Successful decode, or STOP_SESSION command
<b>Image Capture</b>	The decoder clicks the shutter	An image is captured
<b>Video Mode</b>	The decoder continuously produces a video stream	STOP_SESSION command

### Decoder Requirements

Trigger Mode must be set to Host or a CMD\_NAK DENIED response is issued.

## STOP\_SESSION

### Description

Tells decoder to abort a decode attempt or video transmission.

### Packet Format

Length	Opcode	Message Source	Status	Checksum
04h	E5h	04h		

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	E5h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	4 = Host	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

This command tells the decoder to stop a scan and decode attempt.

### Host Requirements

Multipacketing option 2 or 3 should be selected to achieve reasonable throughput.

### Decoder Requirements

None.

## VIDEO\_DATA

### Description

Imager transmission of a video frame in JPEG format.

### Packet Format

Length	Opcode	Message Source	Status	Data	Checksum
	B4h	00h			

### Field Descriptions

Field Name	Format	Size	Description
<b>Length</b>	Length of message (not including checksum).	1 Byte	Length Field
<b>Opcode</b>	B4h	1 Byte	Identifies this Opcode type.
<b>Message Source</b>	00 = Decoder	1 Byte	Identifies where the message is coming from.
<b>Status</b>		1 Byte	<b>Bit 0: Retransmit</b> 0 = First transmission 1 = Subsequent transmission <b>Bit 1: Continuation</b> 0 = Last packet of a multipacket message 1 = Intermediate packet <b>Bit 2: Reserved</b> Always 0 <b>Bit 3: Parameter Change Type</b> (for parameters) 0 = Temporary change 1 = Permanent change
<b>Data</b>		Up to 251 Bytes	Image data.
<b>Checksum</b>	2's complement sum of message contents excluding checksum.	2 Bytes	Checksum of message.

The first packet of a video frame contains the video preamble, described below. The first packet also contains the JPEG data comprising the video frame. Multipacketing is expected in video mode.

The video preamble consists of the following fields:

**Table A-16. Video Preamble Fields**

Field	Field Size	Description
<b>File size</b>	4 byte field	Number of bytes in the overall image.
<b>Image Width</b>	2 byte field	Image width in pixels
<b>Image Height</b>	2 byte field	Image height in pixels

**Table A-16. Video Preamble Fields (Continued)**

Field	Field Size	Description
<b>Image Type</b>	1 byte field	0x31 = JPEG Image File 0x33 = BMP Windows Bit Map File 0x34 = TIFF File Note: These values are ASCII.
<b>Bits per Pixel</b>	1 byte field	Number of bits per pixel in image 0 = 1 bit/pixel Black White Image 1 = 4 bit/pixel 16 Grayscale Image 2 = 8 bit/pixel 256 Grayscale Image

In a multipacketed environment, one video frame is spread over several packets in the following format:

**Packet 1**

Header	Preamble	Video Data, Part 1	Checksum
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**Packet 2**

Header	Video Data, Part 2	Checksum
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.

.

.

**Packet N**

Header	Last of Video Data	Checksum
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This is re-assembled by the host into:

Preamble	Video Frame
----------	-------------



## WAKEUP

### Description

Wakes up decoder after it's been put into low power operation.

If the decoder is in low power mode, sending the single character **NULL** (00) wakes up the decoder. This character is only needed when hardware handshaking is not being used or is bypassed.

### Host Requirements

Once the WAKEUP character is sent, the host must wait a period of time to permit the decoder to wake up. The decoder remains awake for a fixed period of time after wake up. These time periods vary by decoder.

### Decoder Requirements

The decoder must not go back into low power mode for a decoder-dependent time period after waking up.

- ✓ **NOTE** The mechanism to wake up a decoder in this manner also works if characters other than WAKEUP are sent to the decoder. There is, however, no guarantee that these commands are interpreted correctly upon power-up. Therefore, it is not recommended that characters other than WAKEUP be used to awaken the decoder.

The WAKEUP character has no effect if sent when the scanner is awake. If the host is unsure of the scanner state, it should send the wakeup character when it wants to communicate with the scanner.



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